

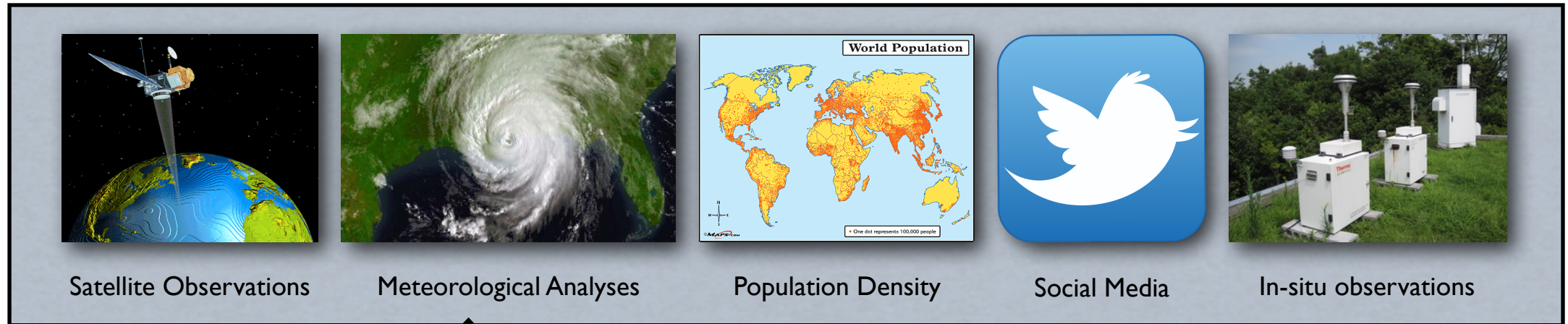
Airborne Networks and Applications

Prof. David John Lary

Next Generation of High Speed Networks to Facilitate the Next Generation of Proactive Smart Health Care Applications

Local cloud computing coupled with widely distributed national and global sensor networks

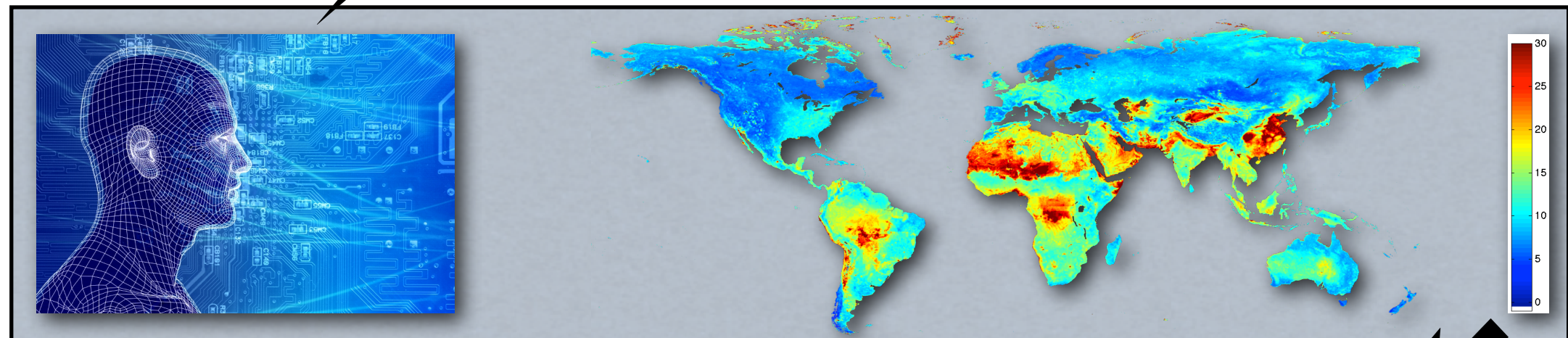
Air Quality



Multiple global high-resolution datasets

Requires ultra-low latency gigabit to the end user

Combined Using Machine Learning to Provide a High-Resolution Global Products



Veteran's Administration Country's Largest Health Care Provider

Combined with Electronic Health Records to provide:

1. Real time personal health alerts
2. Physician Decision Support Tools
3. Logistical Planning for Emergency Rooms
4. Improved Policy Decisions

Prof. David Lary



Next Generation of High Speed Low latency Networks to Facilitate the Next Generation of Smart Fire Detection & Water Conservation Applications

Requires ultra-low latency wireless gigabit for very-high resolution hyperspectral video imagery for real time flight control of aerial vehicles

11 drought-ridden western and central states have just been declared as primary natural disaster areas seriously threatening US food security. Further, every year between \$1 and \$2 billion dollars are spent on fire suppression costs alone.

A fleet of low cost aerial vehicles working together autonomously utilizing uncompressed very-high resolution hyperspectral video imagery. The geo-tagged imagery is streamed using high-speed low-latency wireless networks to communicate to a powerful cloud computing cluster running machine learning and image processing algorithms for real time direction of the optimal flight patterns, and the delivery of early warning for timely interventions.

Fire: Appropriate preemptive fire prevention can lead to massive savings in fire control costs, loss of life, and property damage.

Agriculture: Appropriate and timely early warning of crop infestations, infections and/or water stress can



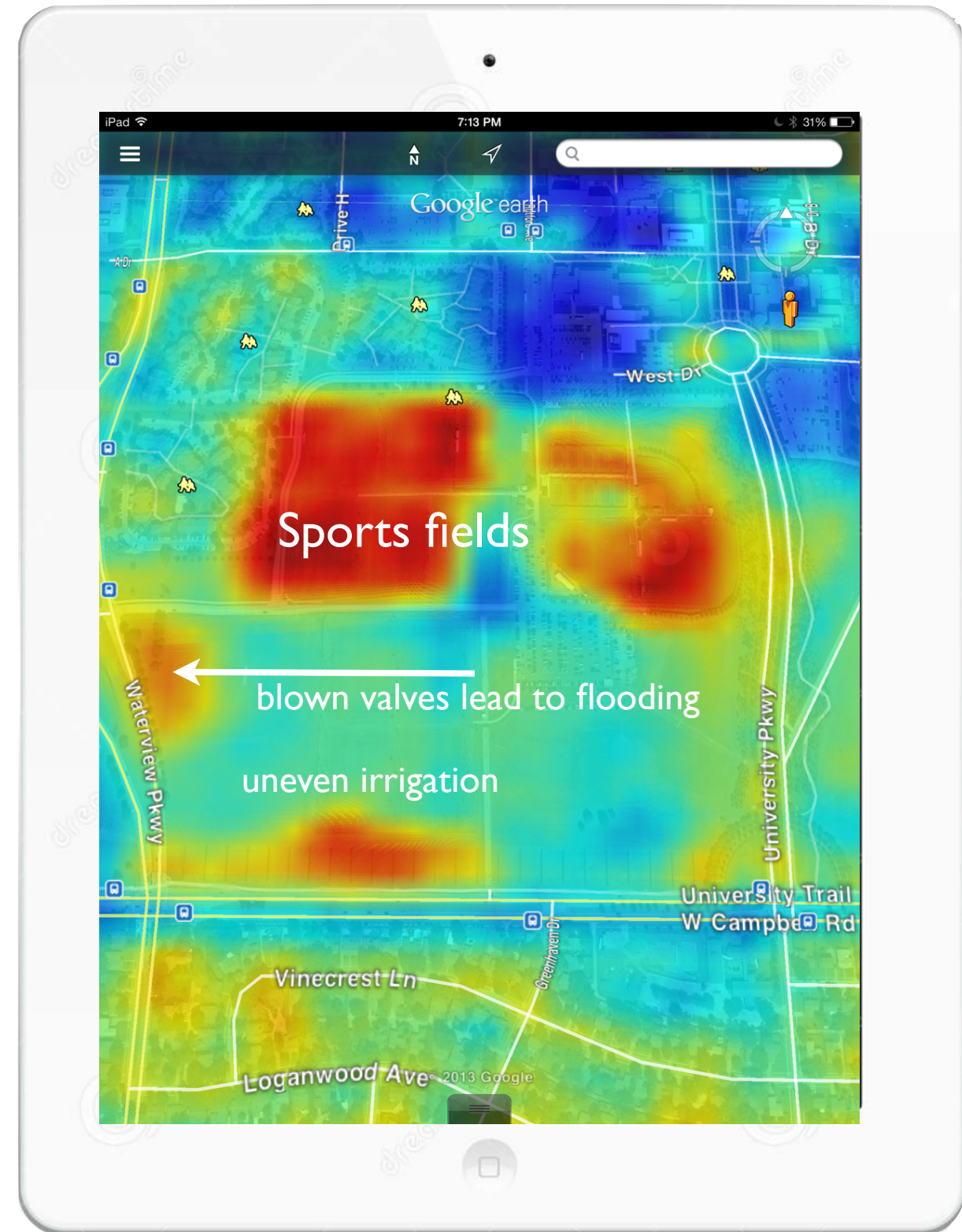
20 lb Airborne 385 channel hyperspectral imaging system

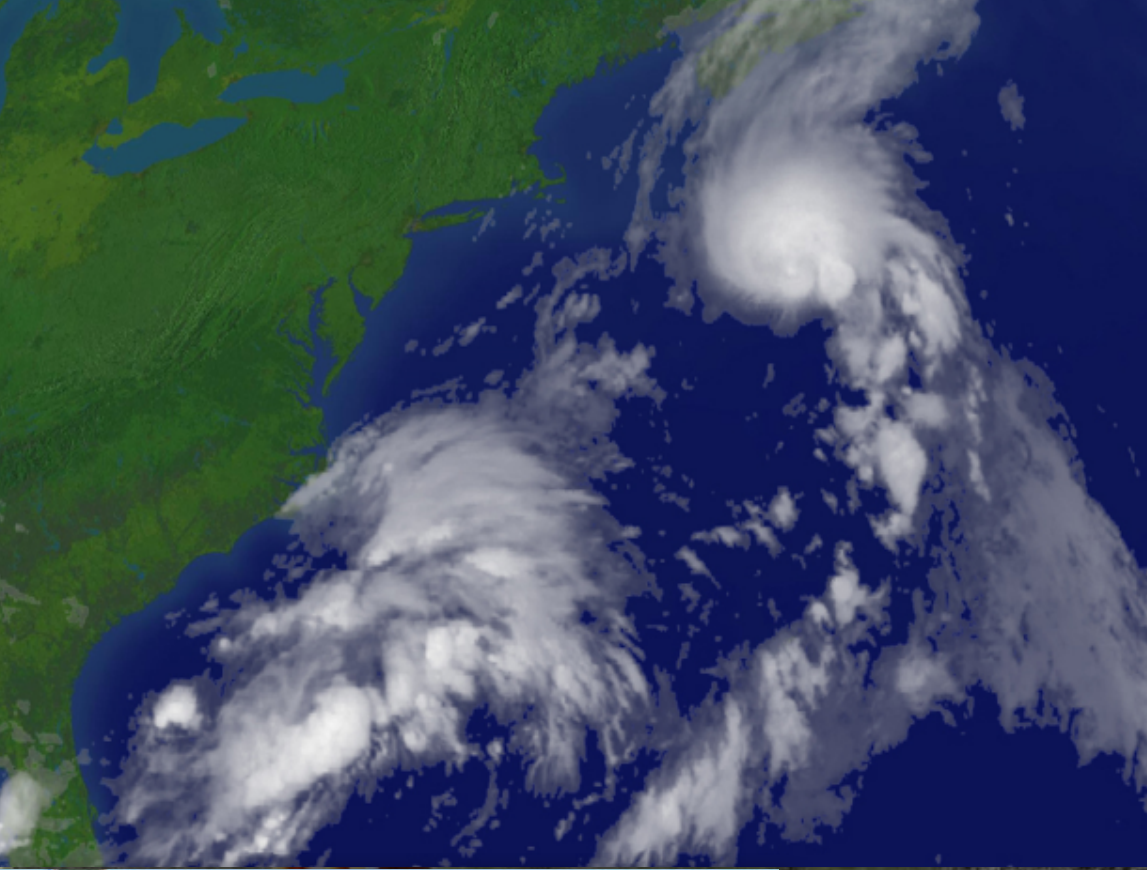


Next Generation of High Speed Networks to Facilitate the Next Generation of Smart Water Management Applications



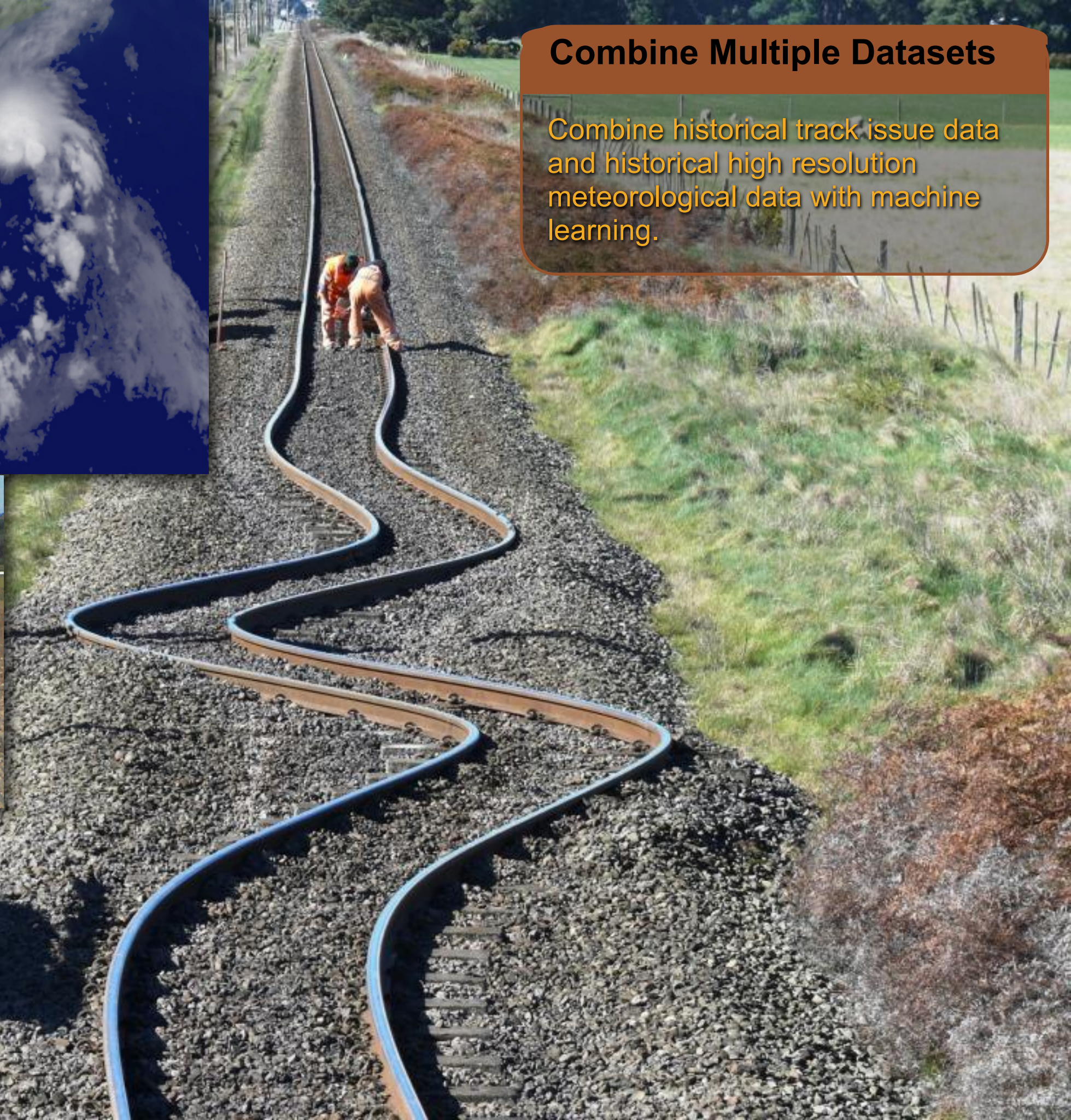
With Drought Disaster Declarations in 11 western and central states, smart water management is now more critical than ever for sustainable water conservation and US Food Security. Coupling high resolution remote sensing from satellites, with machine learning, and the next generation of high speed low latency networks is facilitating the next generation of smart water management systems. These systems will benefit individual home owners, farmers, corporate campuses, golf courses, etc. and allow optimum monitoring and control of irrigation using mobile devices.





Combine Multiple Datasets

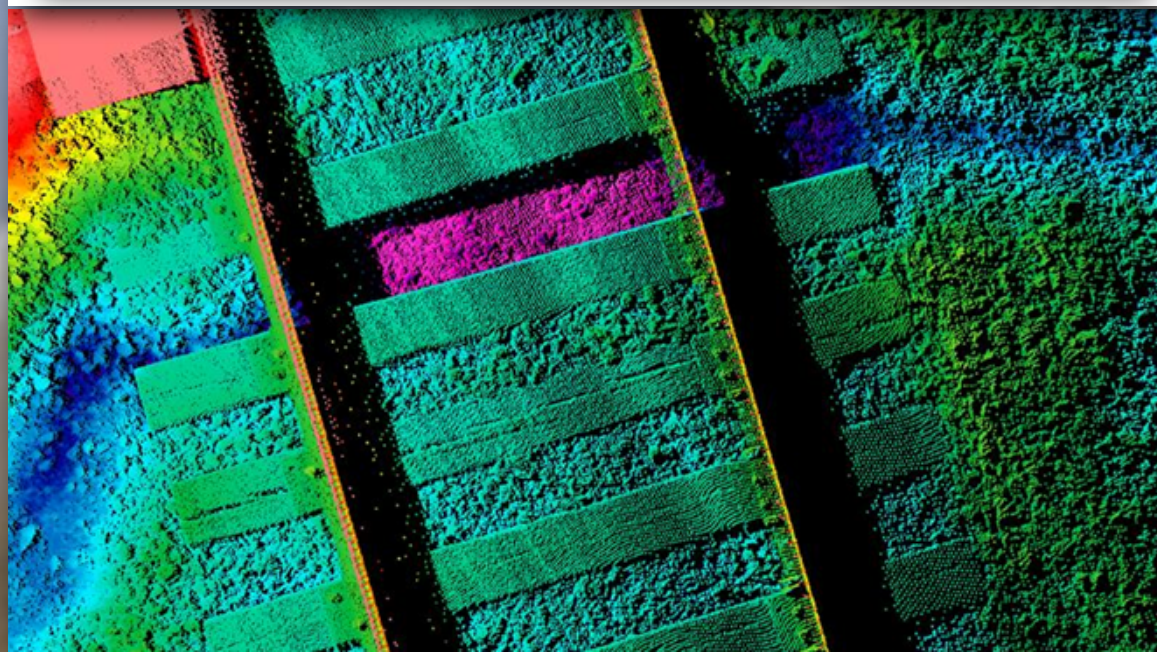
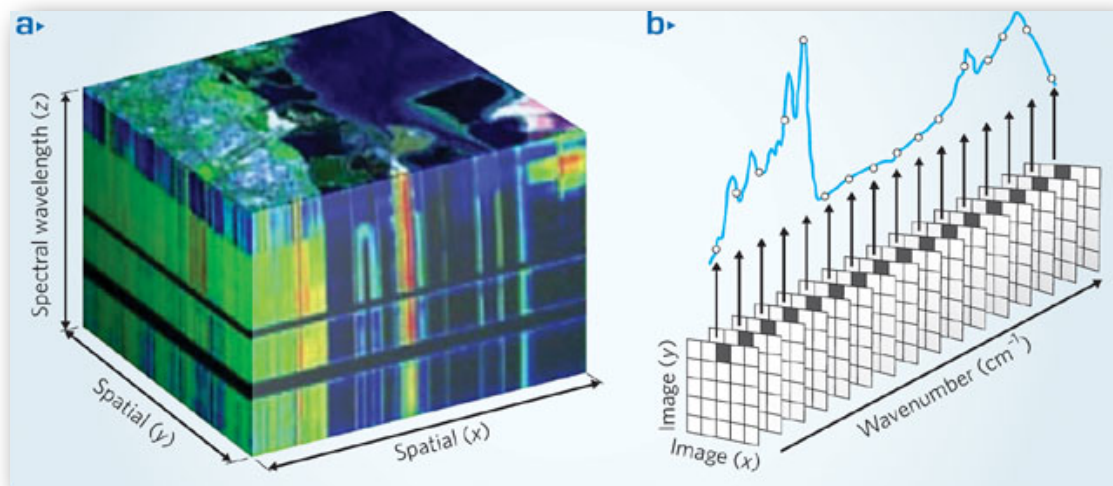
Combine historical track issue data and historical high resolution meteorological data with machine learning.



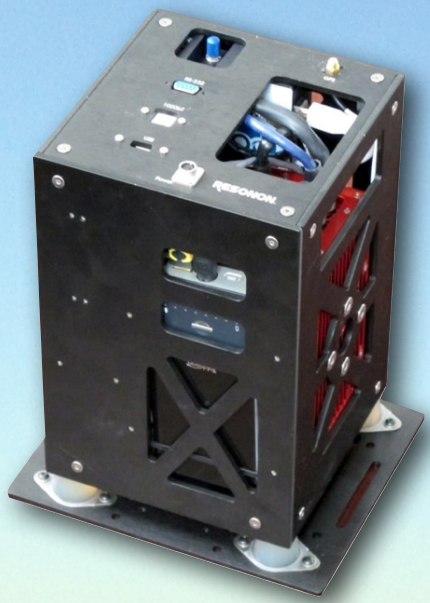
Hyperspectral Data

Hyperspectral data can give insights into the state of the ballast and surrounding ground.

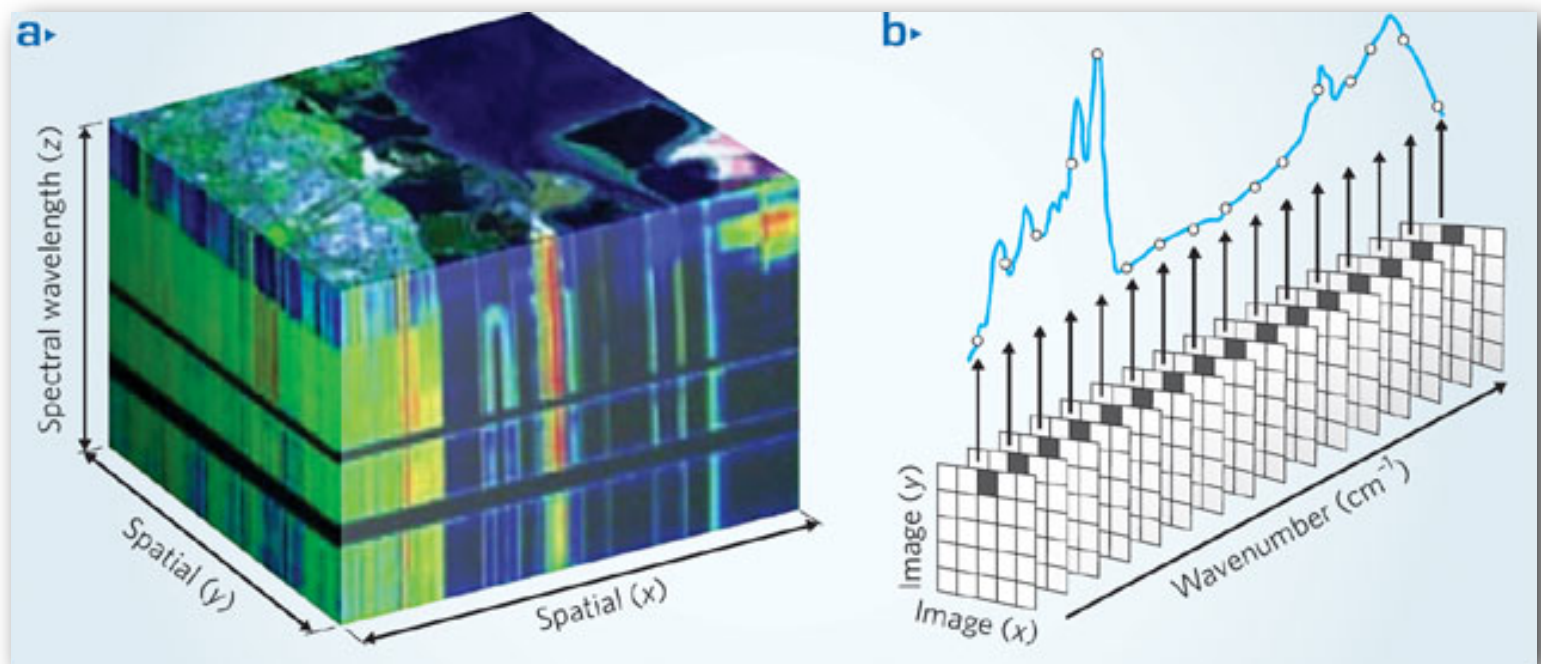
Hyperspectral data cube



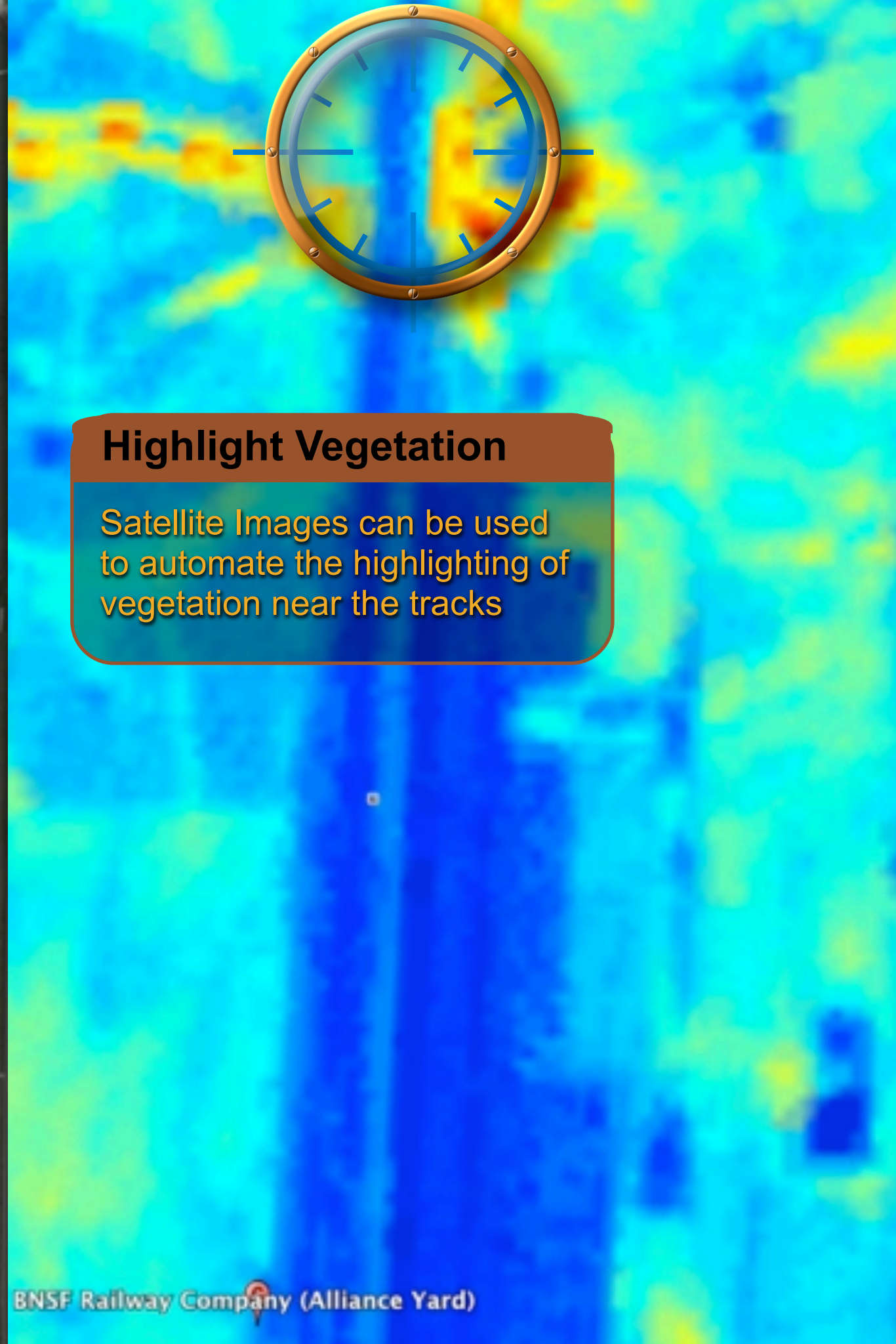
20 lb Airborne hyperspectral imaging system
385 channels between 400-1,700 nm



Hyperspectral data cube







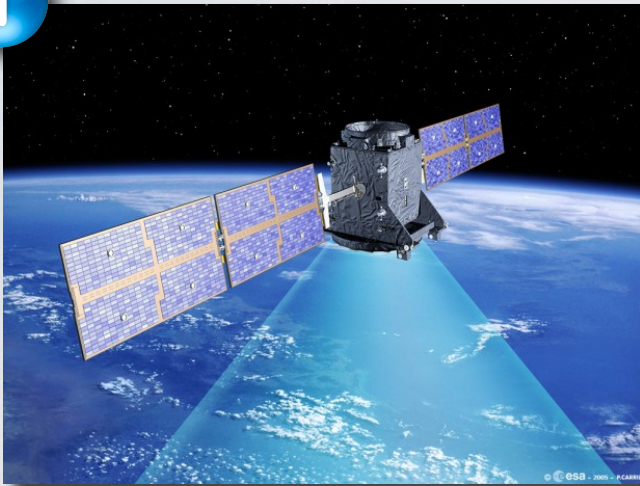
Highlight Vegetation

Satellite Images can be used to automate the highlighting of vegetation near the tracks

THRIVE

TRACK HEALTH INDICATORS USING REMOTE & IN-SITU OBSERVATIONS FOR THE VITALITY OF THE ENVIRONMENT

1



Routine satellite acquisition of multispectral and SAR imagery

2



Periodic high resolution ground truth from aerial surveys

3

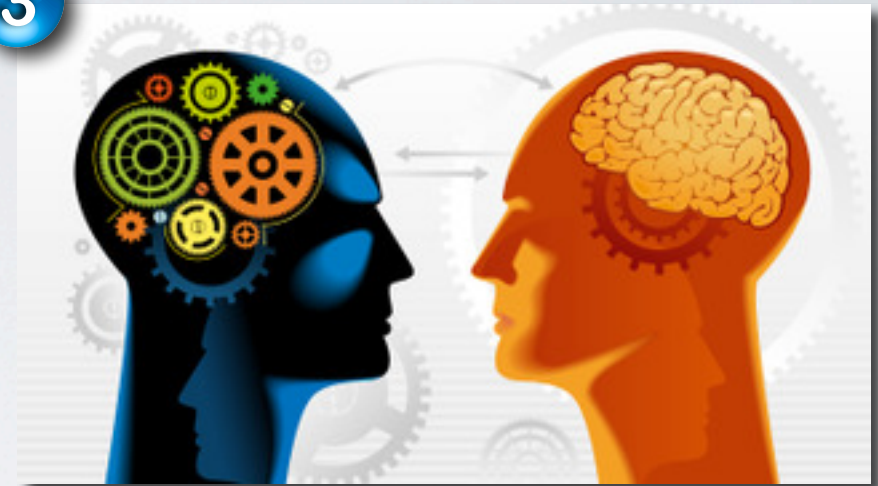


Image processing & Machine Learning

Preparing for Routine Decision Support

The synergy between routine satellite imagery, periodic high resolution ground truth surveys and automated machine learning and image processing is a powerful combination for decision support.

4



BNSF Decision Support

Using Zero-Emission Aerial Vehicles in Support of the ACE Mission

Hanson Center for Space Sciences
Prof. David Lary





Using Zero Emission Aerial Vehicles in Support of ACE

PI: David Lary, University of Texas - Dallas

Objective

Address a key gap in existing validation capabilities for ACE by measuring the size distribution and vertical profiles in the boundary layer in the 100m closest to the surface using a small aerial vehicle. The project will

- Demonstrate feasibility of using zero emissions remote control aircraft for satellite validation
- Determine if a key gap in existing validation capabilities for the Aerosols, Cloud systems, ocean Ecosystems (ACE) can be filled with this technology
- Develop proper size distribution and vertical profiles of aerosols in the boundary layer 100m closest to the surface for ACE mission



The model aircraft is equipped with a full suite of meteorological instruments for temperature, pressure, humidity, wind speed and direction as well as an EPA certified Grimm Model 1.109 Aerosol Spectrometer & 1.320 Nano Check which provides extremely precise size distributions within the size range 12 nm - T 32 μm in 43 size channels.

Approach

Major tasks include:

- Characterize surface variability of aerosol size distribution and abundance across the ACE footprint (250 m resolution) using a Grimm Model 1.109 Aerosol Spectrometer & 1.320 Nano Check and a full weather station measuring temperature, pressure, humidity, dew point, and wind speed and direction
- Integrate the Grimm Spectrometers and full weather station into the model aircraft
- Fly at a range of locations and times to demonstrate the ability to characterize the aerosol size distribution and vertical profiles in the boundary layer in the 100 m closest to the surface

Co-Is/Partners

None

Key Milestones

- Characterize surface variability of aerosol size distribution and abundance across the ACE footprint 8/14
- Integrate aerosol spectrometer into the model aircraft 10/14
- Fly at a range of locations and times to demonstrate the ability to characterize the aerosol size distribution and vertical profiles 6/15

TRL_{in} = 5

TRL_{current} = 5



Flight Photos



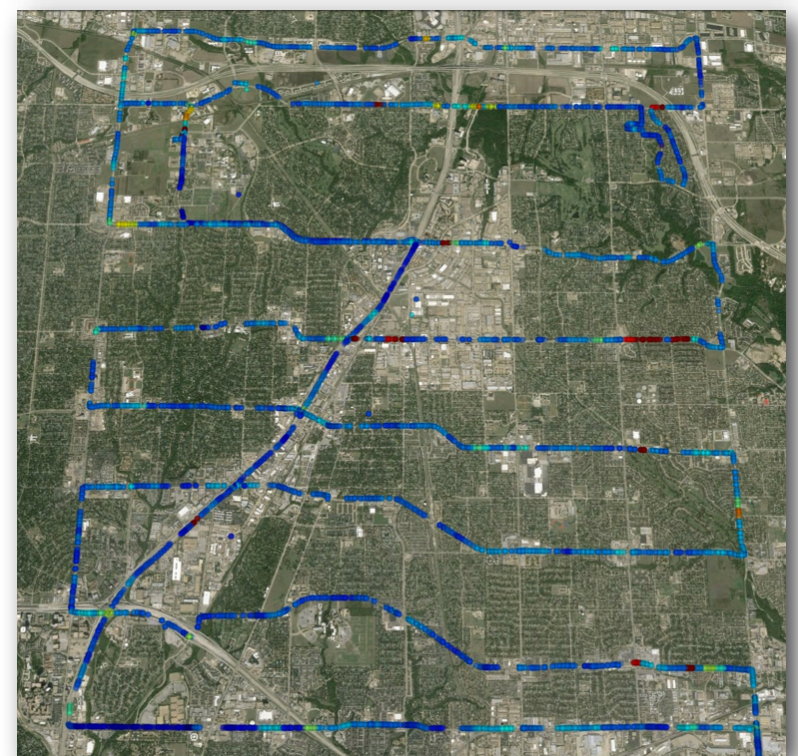
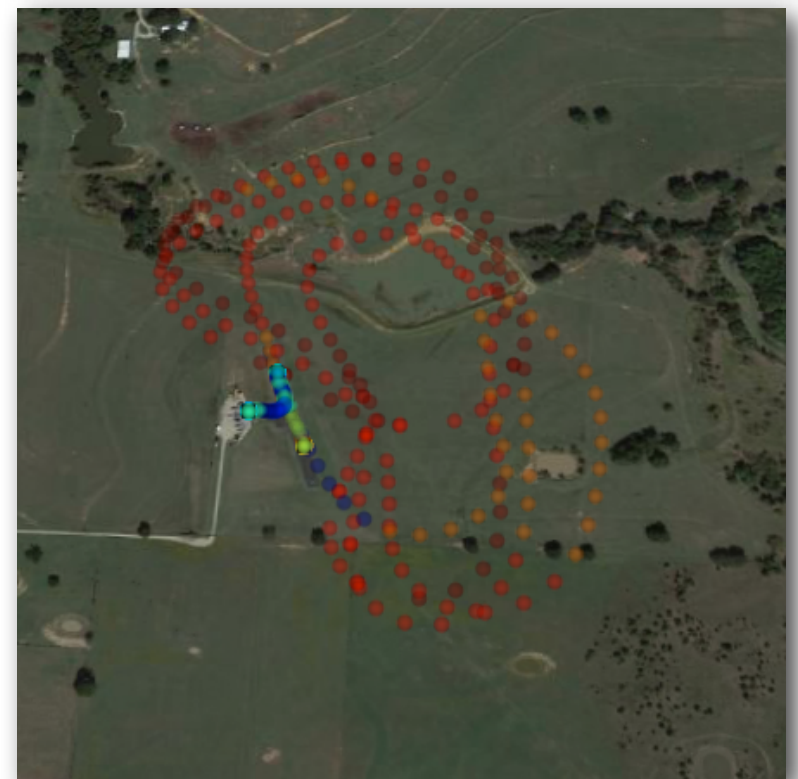
Flight Photos



Accomplishments

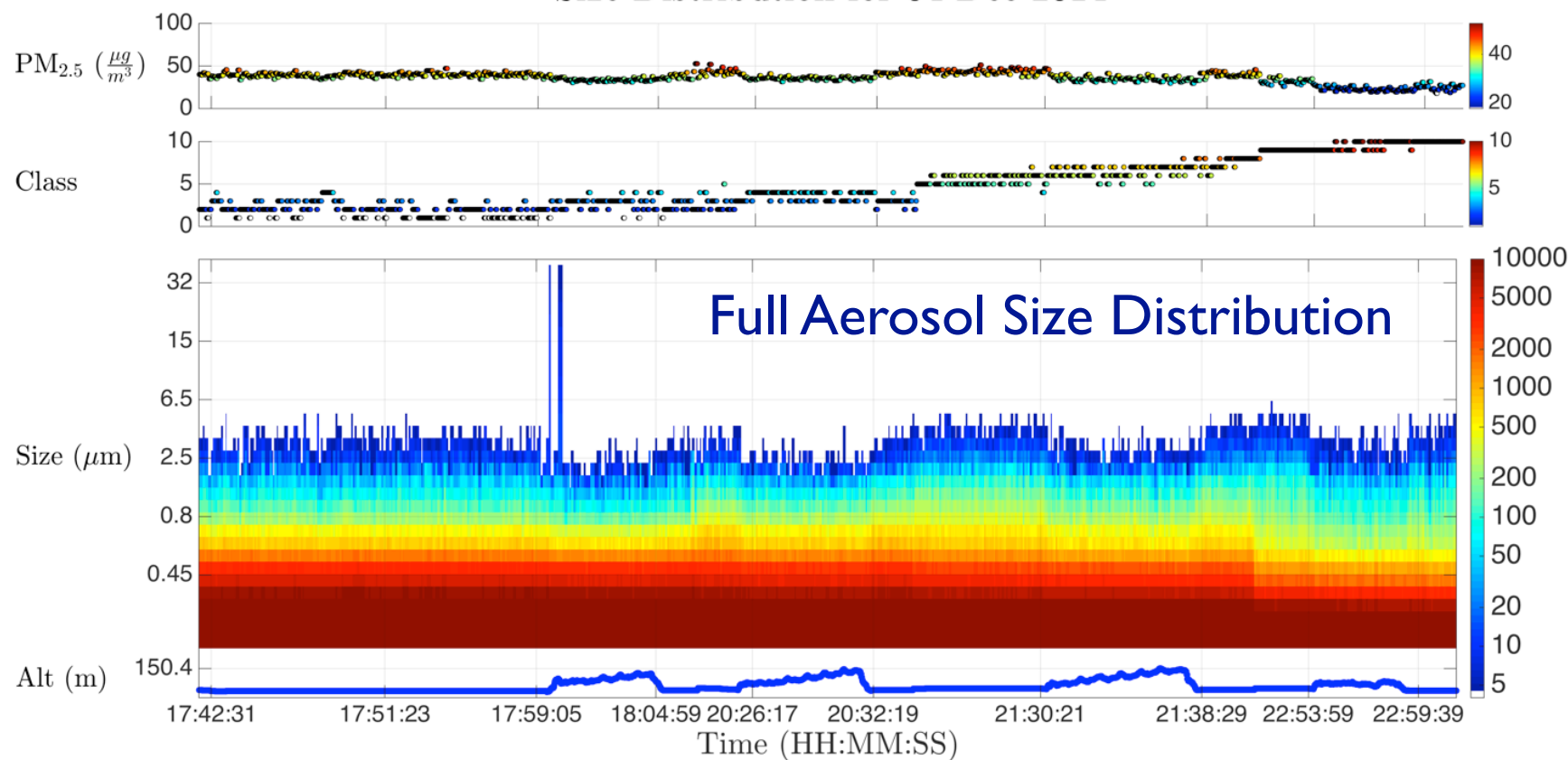
To the best of our knowledge the *first time* the **full sub-pixel aerosol size distribution has been characterized at high spatial resolution** (sub meter) **and high temporal resolution** (every second) using:

- A zero emission, low cost, electric remote control model aircraft at multiple vertical levels in the lower most 100 m of the atmosphere.
- A car driving daily across a 10 km pixel over an extended period.



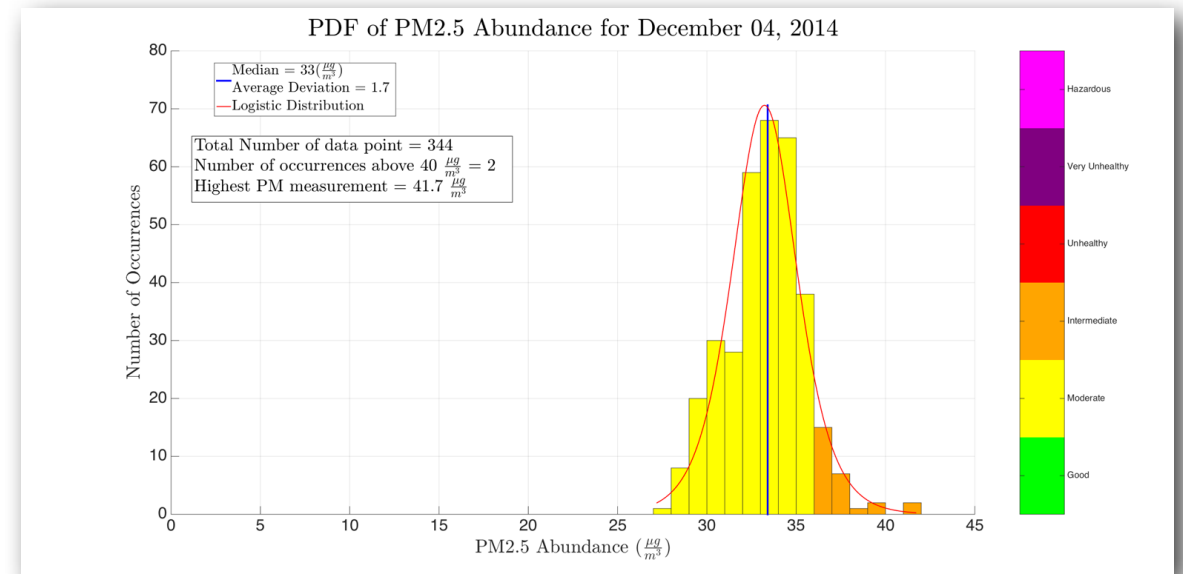
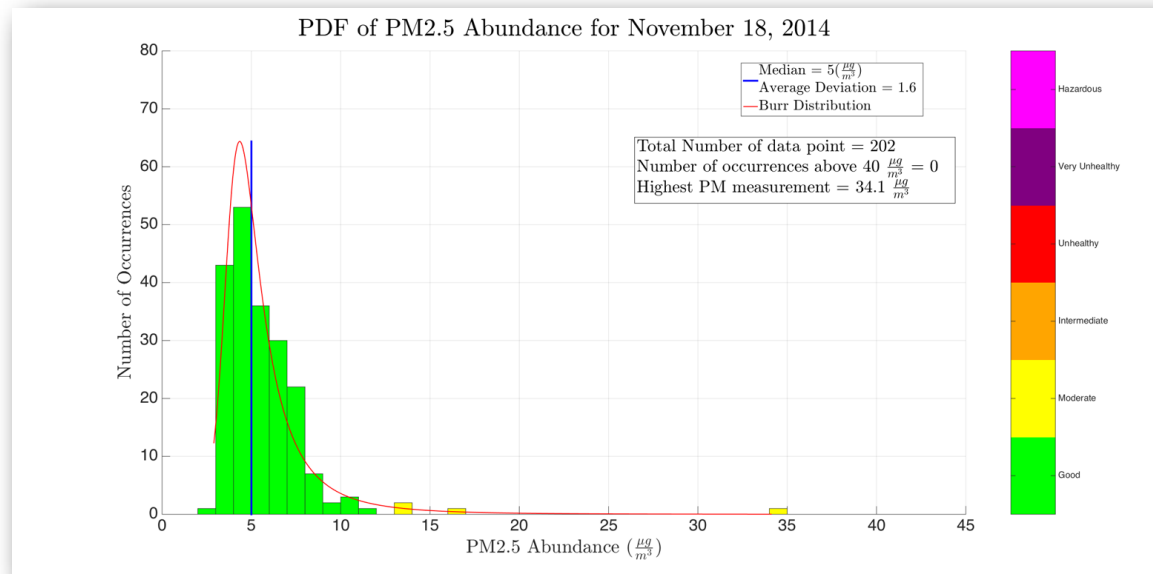
← Satellite Pixel →

Size Distribution for 04-Dec-2014

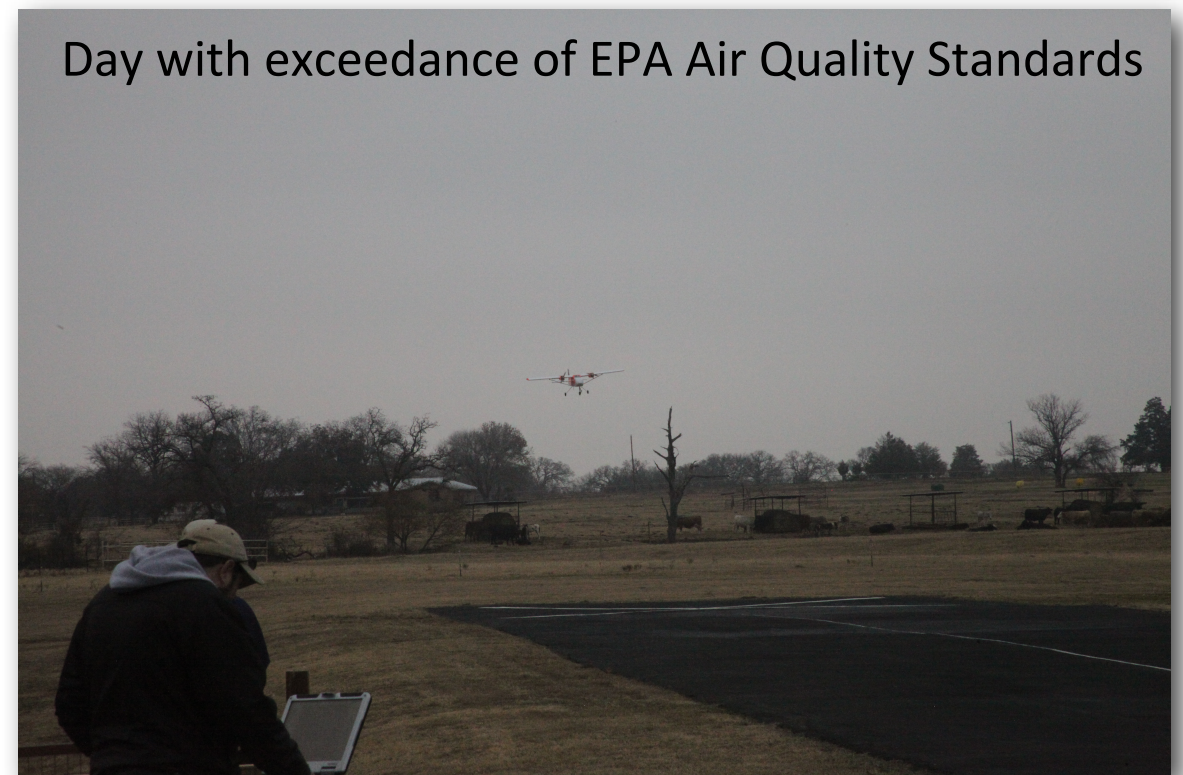


PM_{2.5} Air Quality Standards

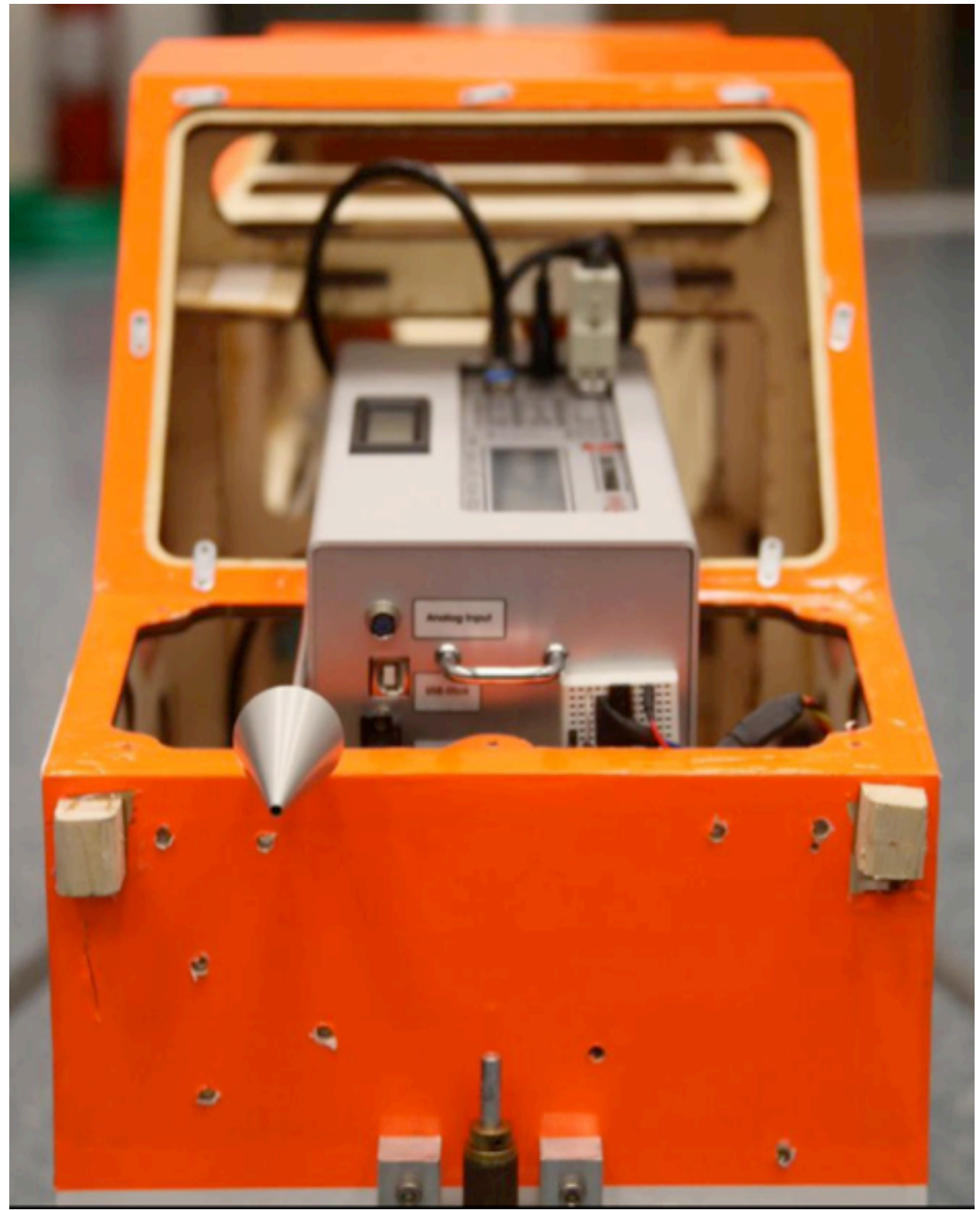
Japan	USA	WHO/EU
Annual Avg. : 15 $\mu\text{g}/\text{m}^3$	Annual Avg. : 12 $\mu\text{g}/\text{m}^3$	Annual Avg. : 25 $\mu\text{g}/\text{m}^3$
24 hour Avg. : 35 $\mu\text{g}/\text{m}^3$	24 hour Avg. : 35 $\mu\text{g}/\text{m}^3$	Annual Avg. : 20 $\mu\text{g}/\text{m}^3$



Flight on Nov 18, 2014 clear skies

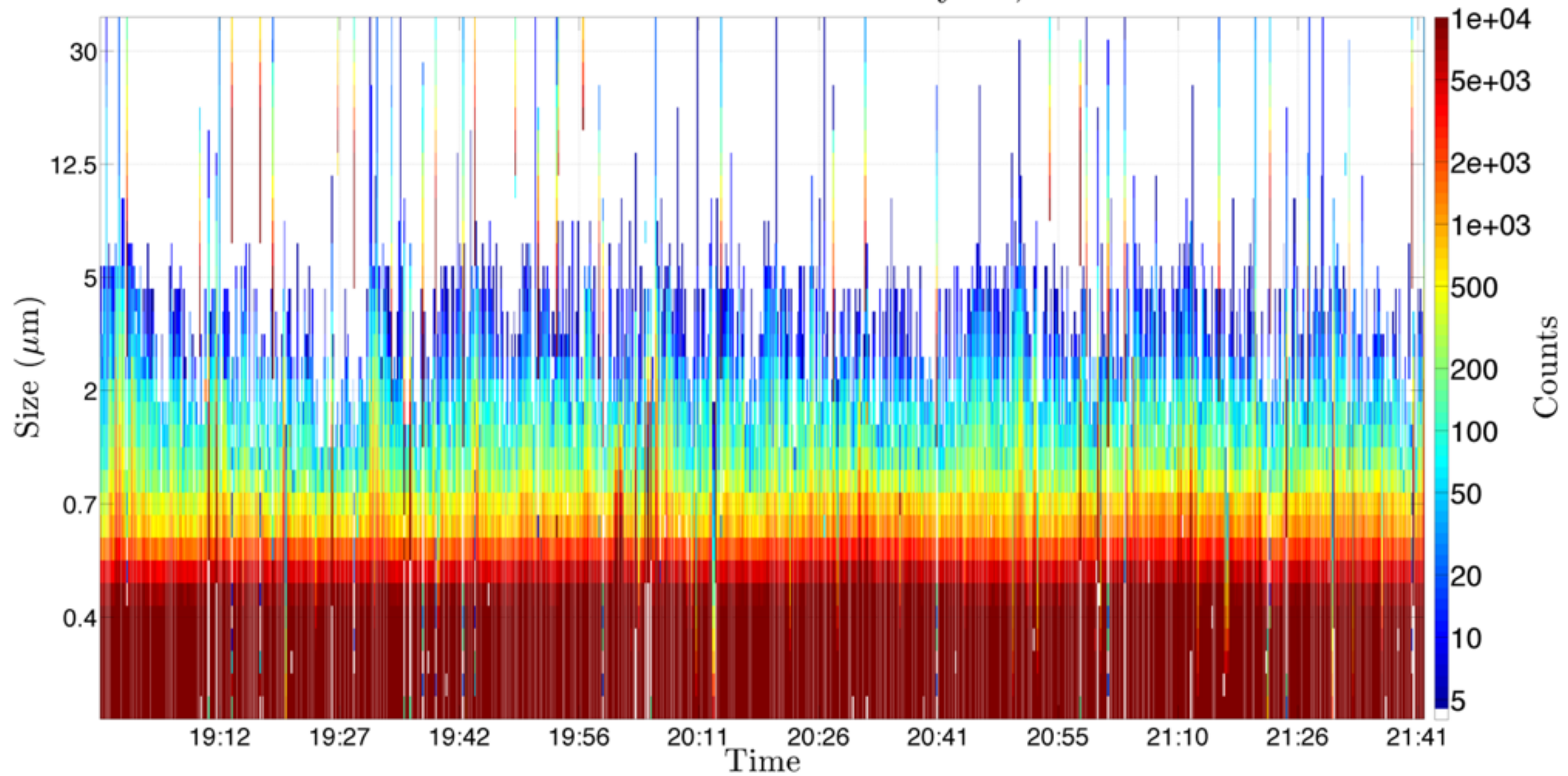


Flight on Dec 04, 2014 hazy/overcast

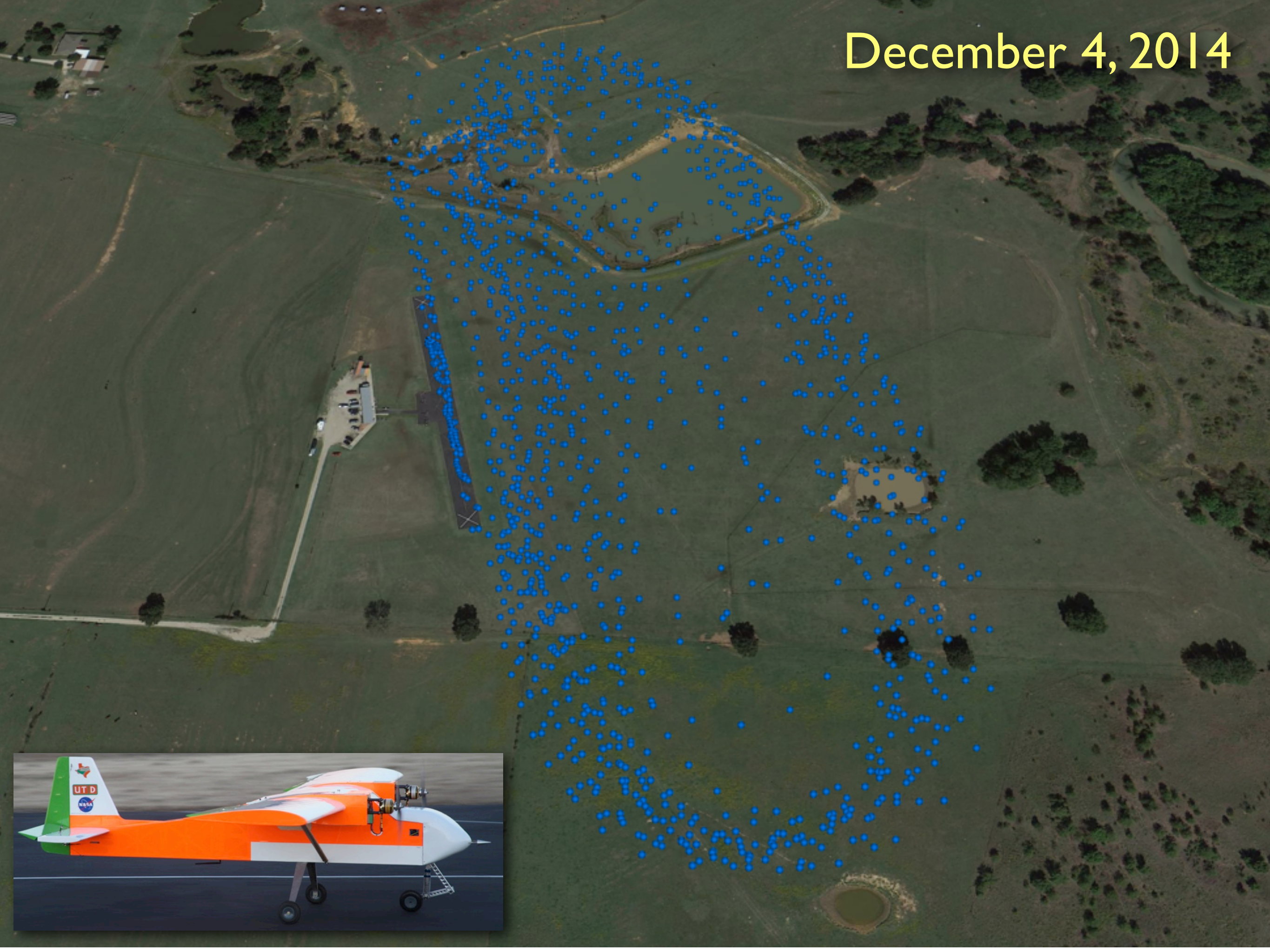


**Small scale variability in
the horizontal &
vertical**

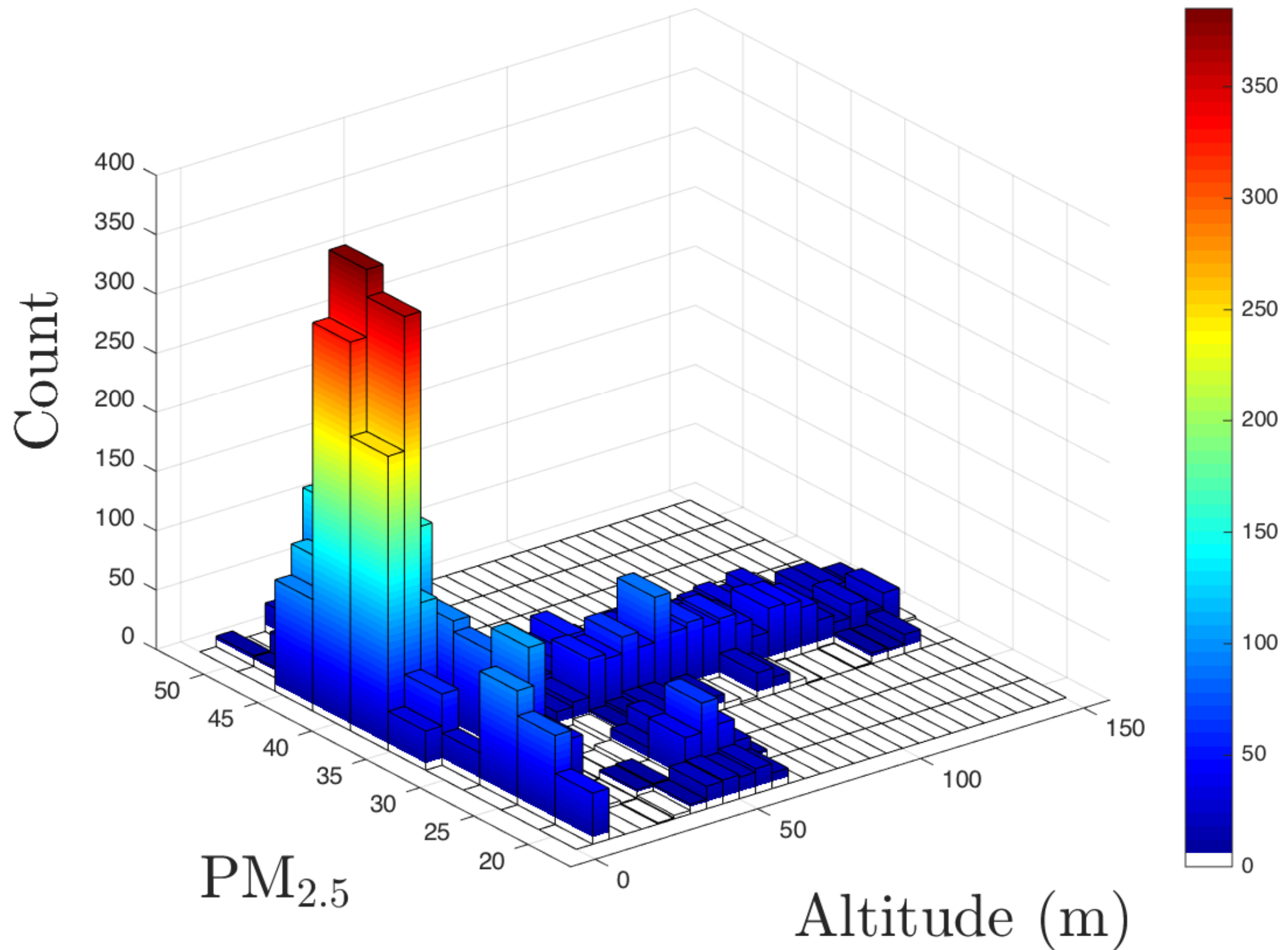
Size Distribution for February 03, 2014



December 4, 2014

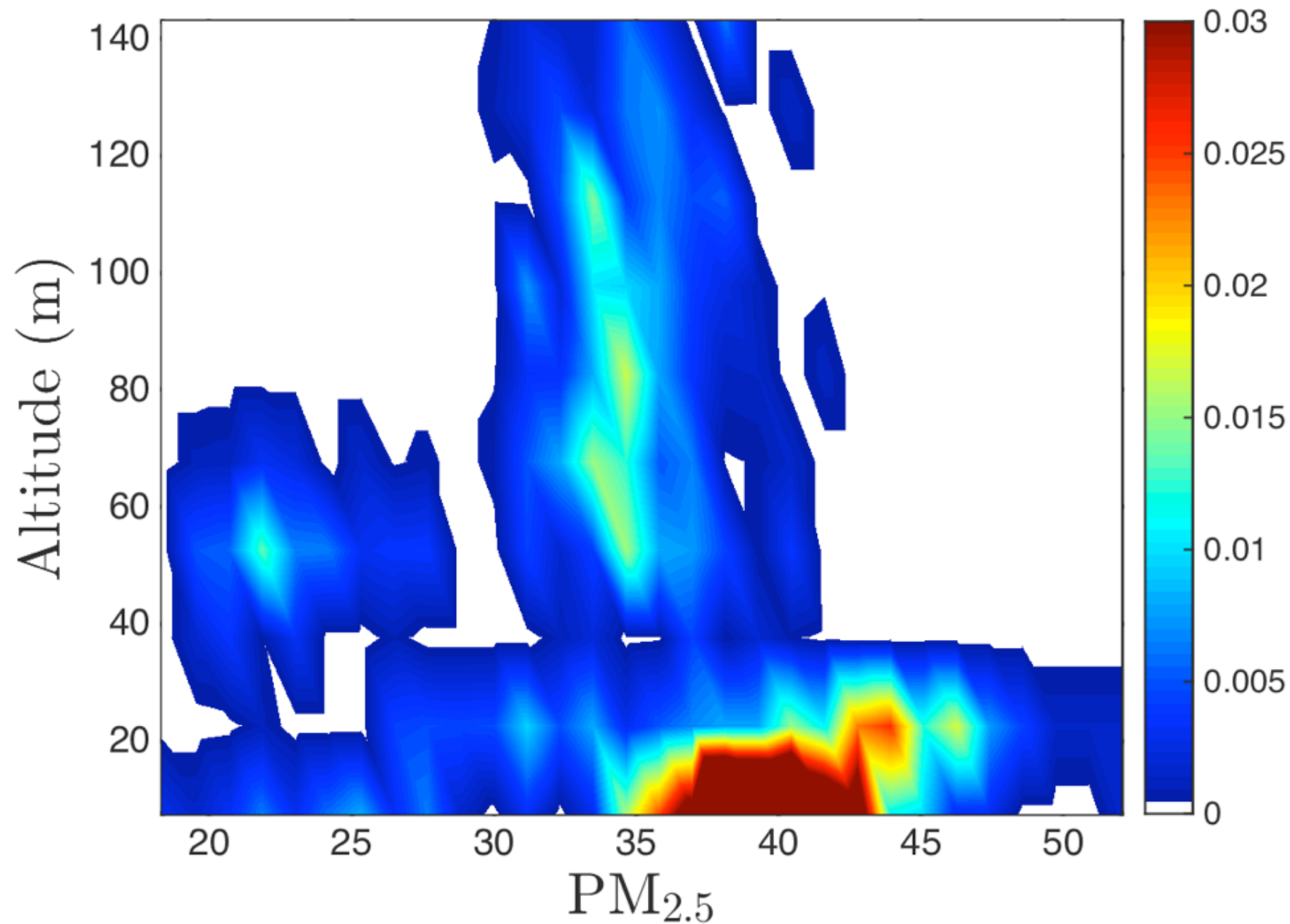


Spatial Variability Across A Satellite Pixel



Spatial Variability Across A Satellite Pixel

Aerosol Probability Density



7 million deaths annually linked to air pollution





In new estimates released, WHO reports that in 2012 around 7 million people died - one in eight of total global deaths – as a result of air pollution exposure. This finding more than doubles previous estimates and confirms that air pollution is now the world's largest single environmental health risk. Reducing air pollution could save millions of lives.

[Read the news release on air pollution attributable deaths](#)

[Read the feature story on air pollution](#)

↓ [FAQs on air pollution and health](#)  pdf, 169kb 

↓ [Air pollution estimates](#)
 pdf, 1.16Mb
Summary of results and method descriptions 



3.7 million deaths

attributable to ambient air pollution

[Mortality from ambient air pollution for 2012 - summary of results](#)
pdf, 293kb



4.3 million deaths

attributable to household air pollution

[Mortality from household air pollution 2012 - summary of results.](#)
pdf, 558kb



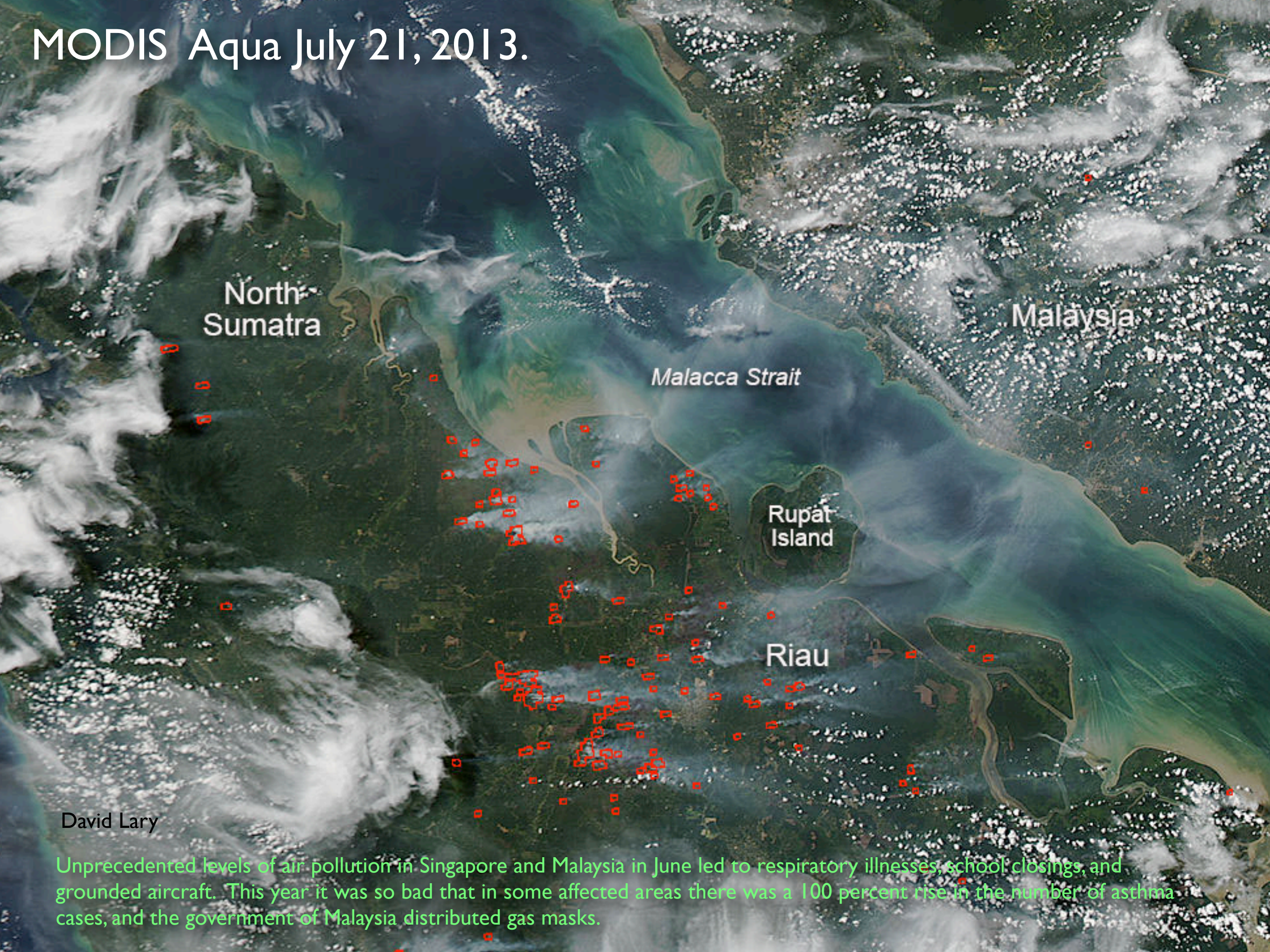
1600 cities

worldwide are reporting air pollution levels

[Air quality in cities database – summary of results](#)
pdf, 304kb



MODIS Aqua July 21, 2013.



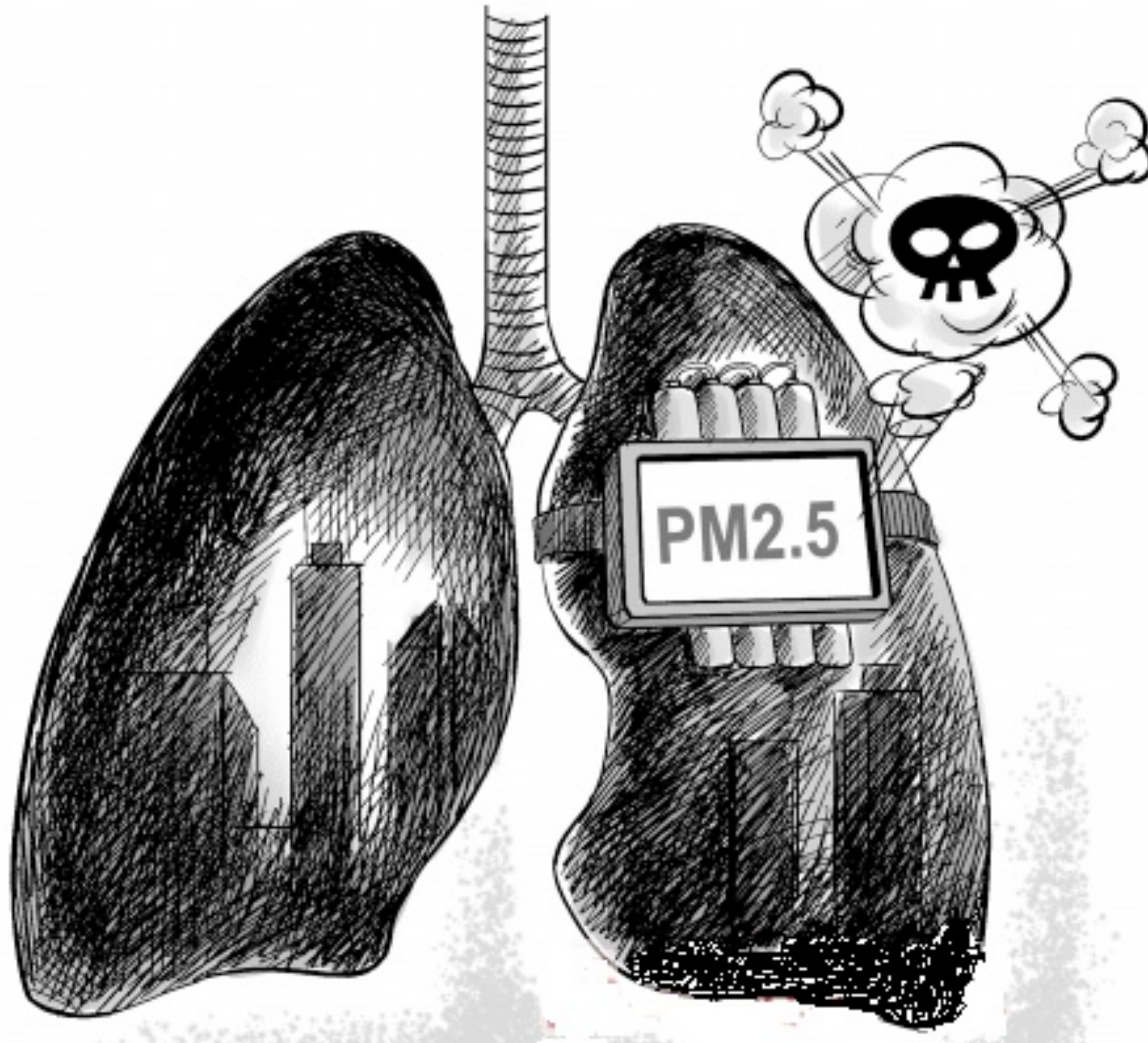
David Lary

Unprecedented levels of air pollution in Singapore and Malaysia in June led to respiratory illnesses, school closings, and grounded aircraft. This year it was so bad that in some affected areas there was a 100 percent rise in the number of asthma cases, and the government of Malaysia distributed gas masks.

Air pollution in Ulaanbaatar, Mongolia

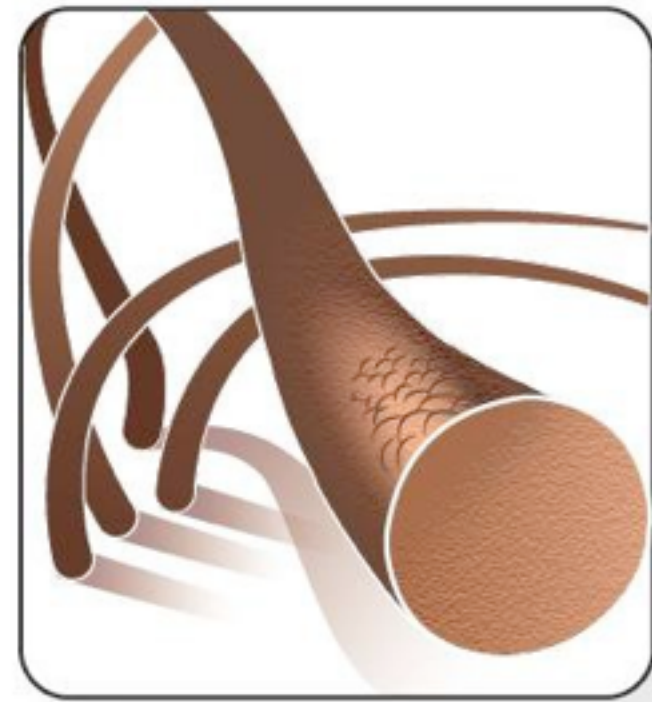


PM2.5 Invisible Killer

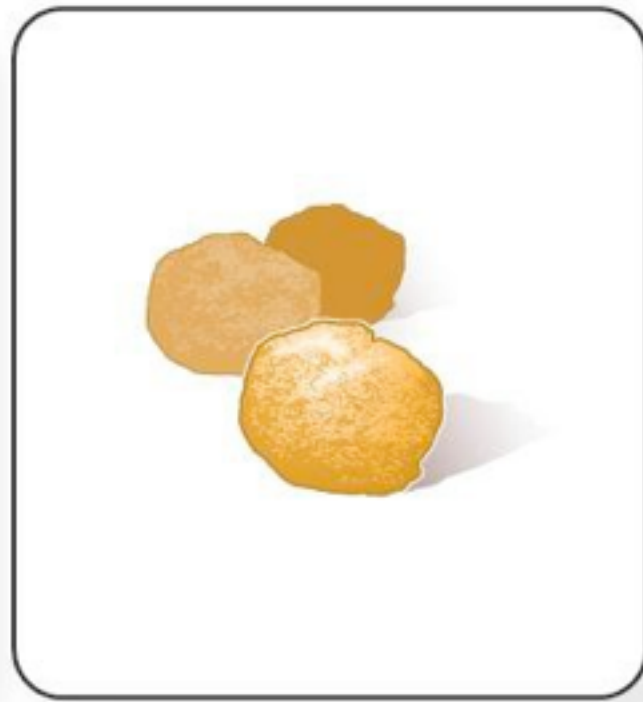




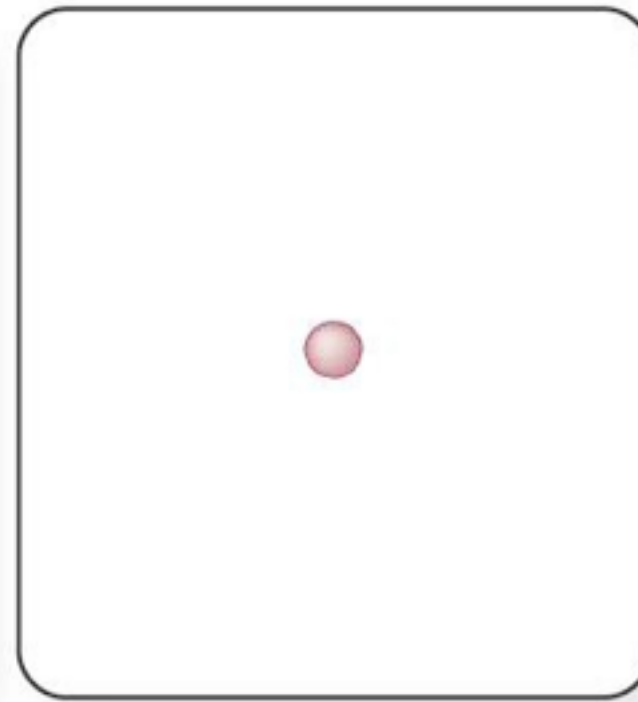
Fine Particulate Matter Size Comparison



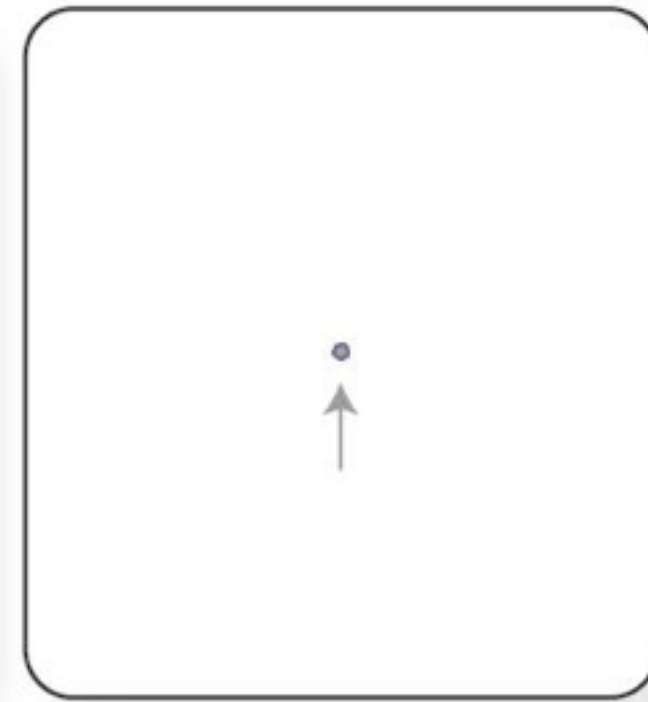
Human hair (about $70\mu\text{m}$ wide)



Grain of sand (about $50\mu\text{m}$ wide)

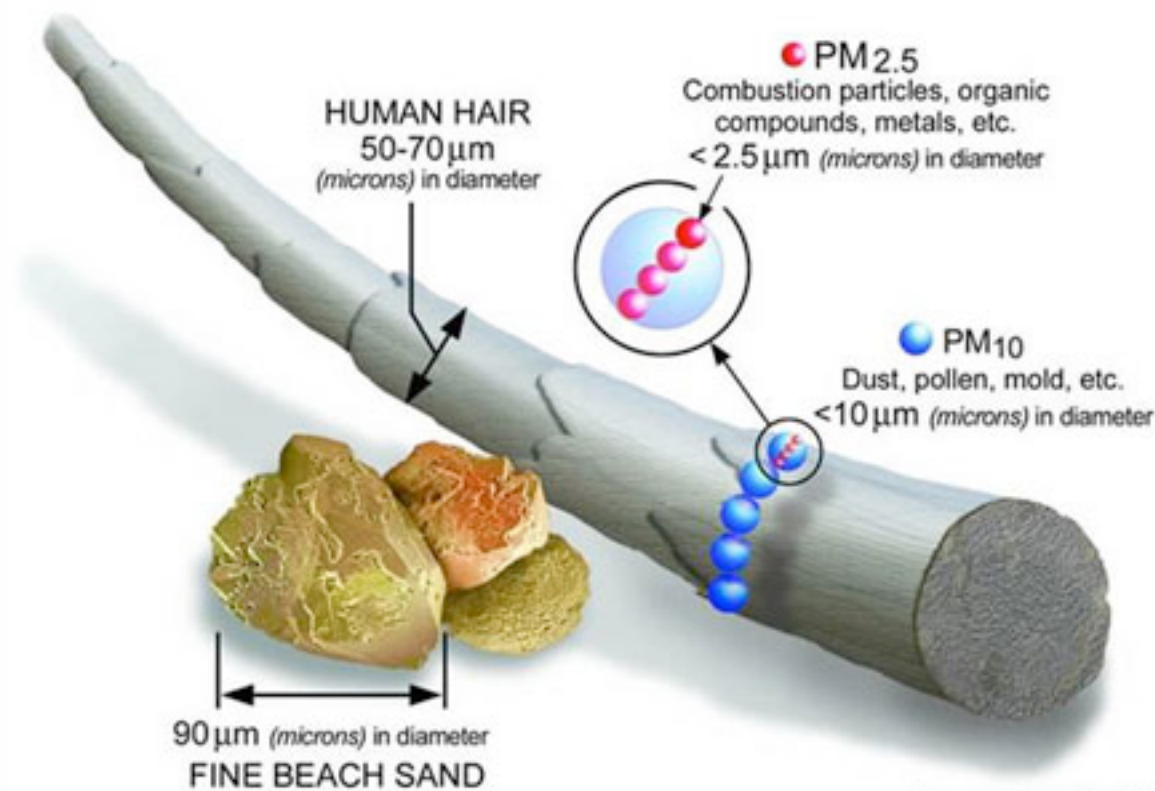


PM_{10} (less than $10\mu\text{m}$ wide)



$\text{PM}_{2.5}$ (less than $2.5\mu\text{m}$ wide)

μm = micrometer



Decreased Lung Function < 10 μm

Cardiovascular Disease < 0.1 μm

Skin & Eye Disease < 2.5 μm

Tumors < 1 μm

0.1 mm

1 mm

0.0001 μm

0.001 μm

0.01 μm

0.1 μm

1 μm

10 μm

100 μm

1000 μm

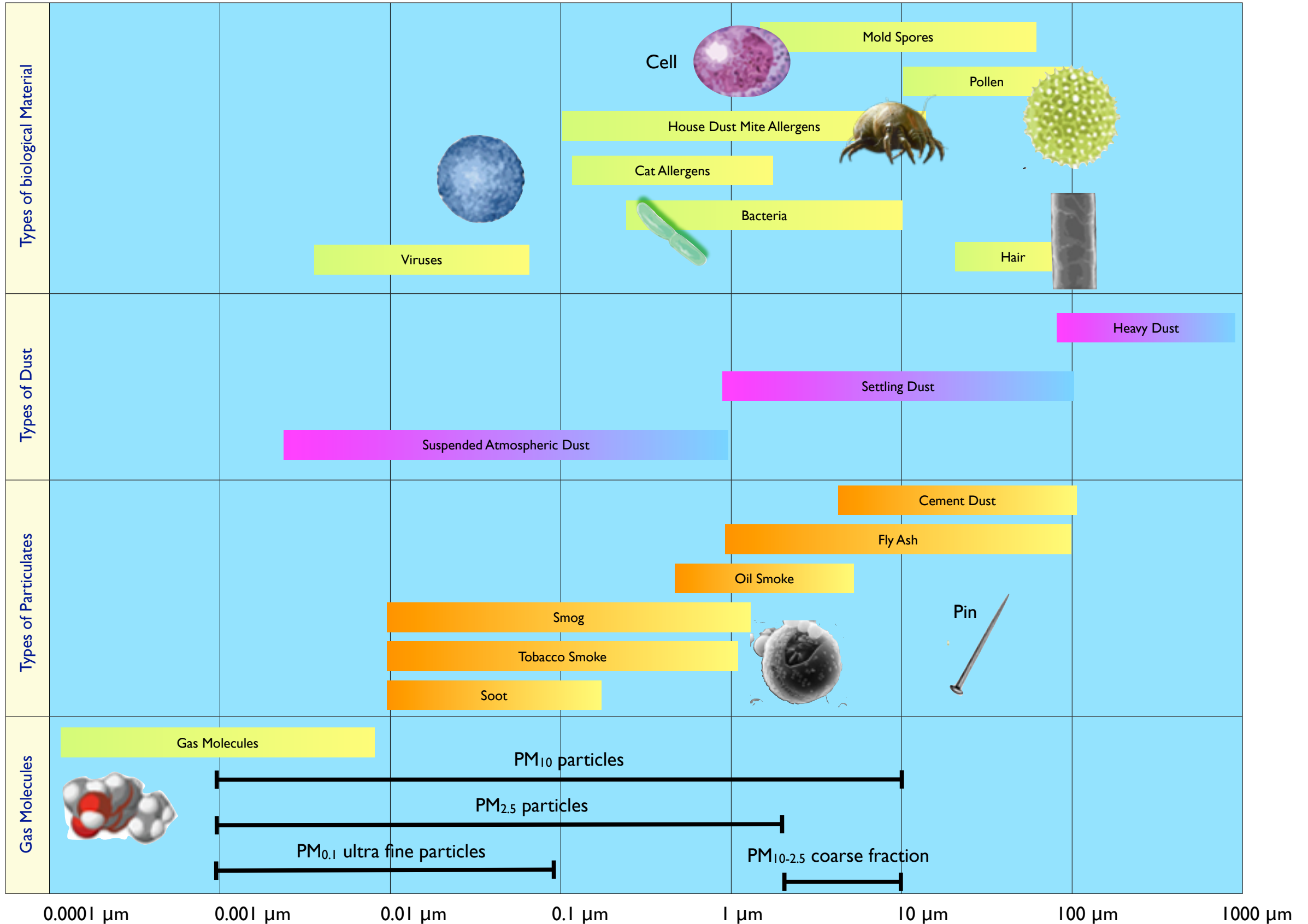
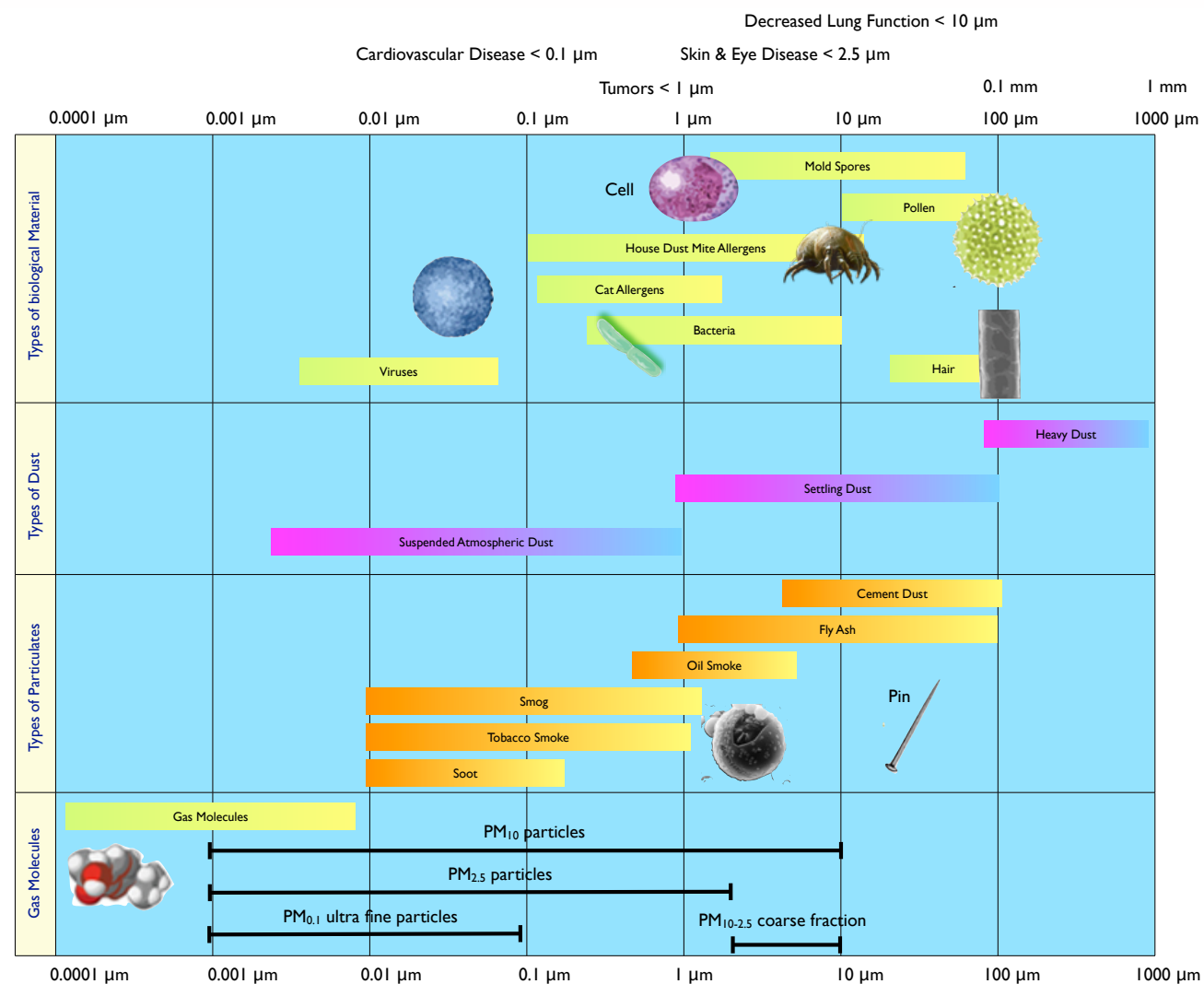


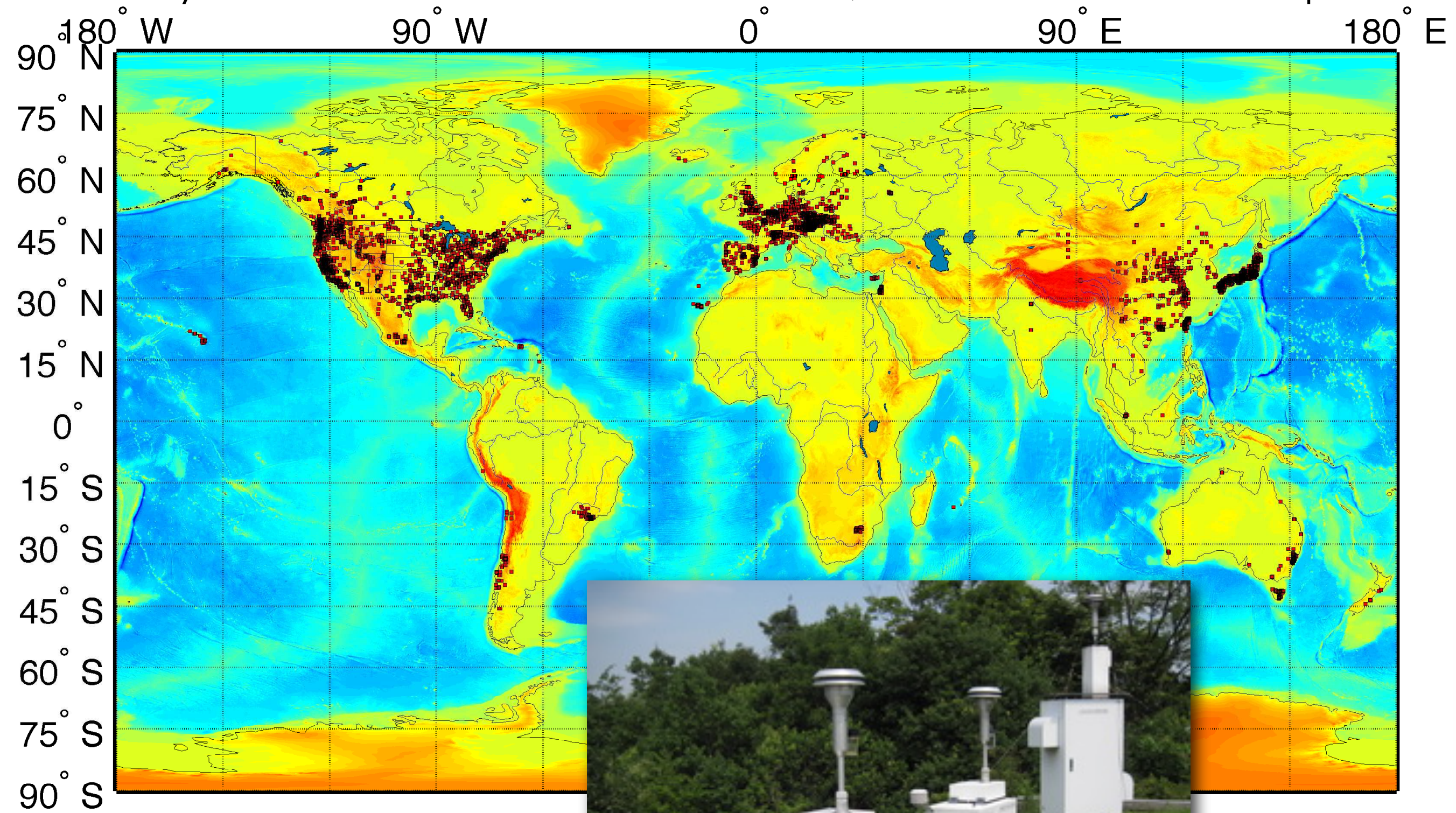
Table 1. PM and health outcomes (modified from Ruckerl et al. (2006)).

Health Outcomes	Short-term Studies			Long-term Studies		
	PM10	PM2.5	UFP	PM10	PM2.5	UFP
Mortality						
All causes	xxx	xxx	x	xx	xx	x
Cardiovascular	xxx	xxx	x	xx	xx	x
Pulmonary	xxx	xxx	x	xx	xx	x
Pulmonary effects						
Lung function, e.g., PEF	xxx	xxx	xx	xxx	xxx	
Lung function growth				xxx	xxx	
Asthma and COPD exacerbation						
Acute respiratory symptoms		xx	x	xxx	xxx	
Medication use			x			
Hospital admission	xx	xxx	x			
Lung cancer						
Cohort				xx	xx	x
Hospital admission				xx	xx	x
Cardiovascular effects						
Hospital admission	xxx	xxx		x	x	
ECG-related endpoints						
Autonomic nervous system	xxx	xxx	xx			
Myocardial substrate and vulnerability		xx	x			
Vascular function						
Blood pressure	xx	xxx	x			
Endothelial function	x	xx	x			
Blood markers						
Pro inflammatory mediators	xx	xx	xx			
Coagulation blood markers	xx	xx	xx			
Diabetes	x	xx	x			
Endothelial function	x	x	xx			
Reproduction						
Premature birth	x	x				
Birth weight	xx	x				
IUR/SGA	x	x				
Fetal growth						
Birth defects	x					
Infant mortality	xx	x				
Sperm quality	x	x				
Neurotoxic effects						
Central nervous system		x	xx			

x, few studies; xx, many studies; xxx, large number of studies.



Hourly Measurements from 55 countries and more than 8,000 measurement sites from 1997-present



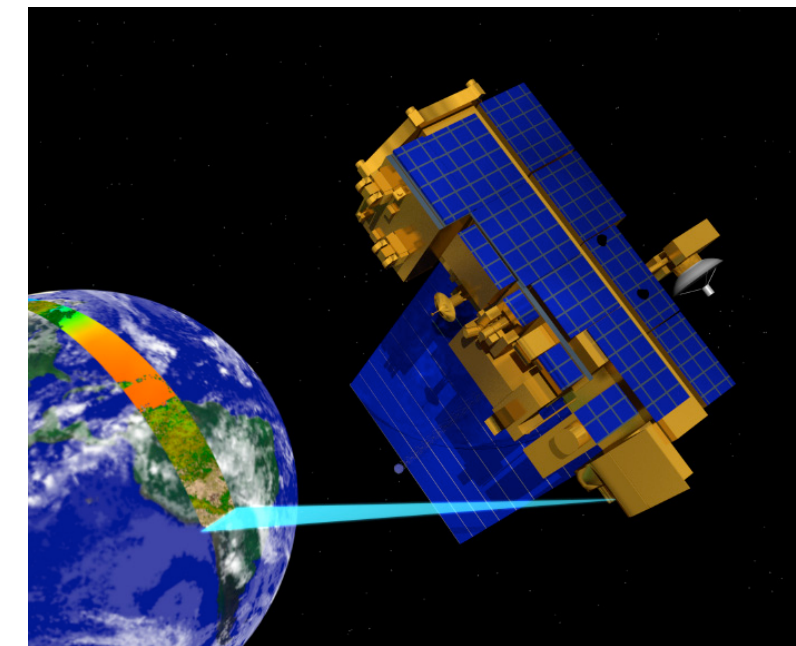
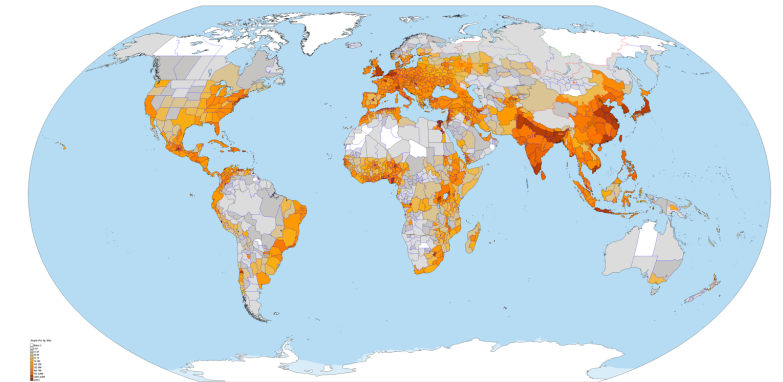
Virtual Sensors

Comes out of CAL/VAL
Inter-Instrument Inter Comparison

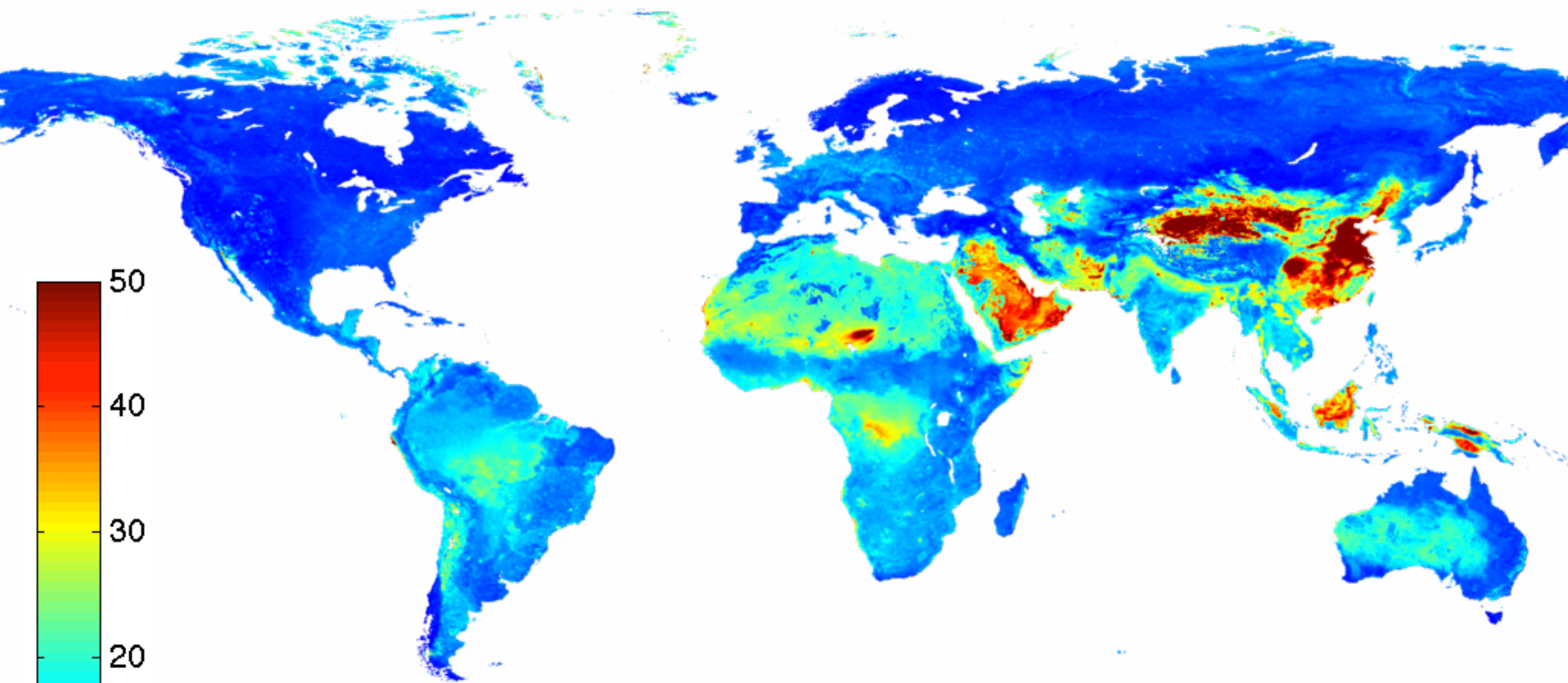
Terra DeepBlue



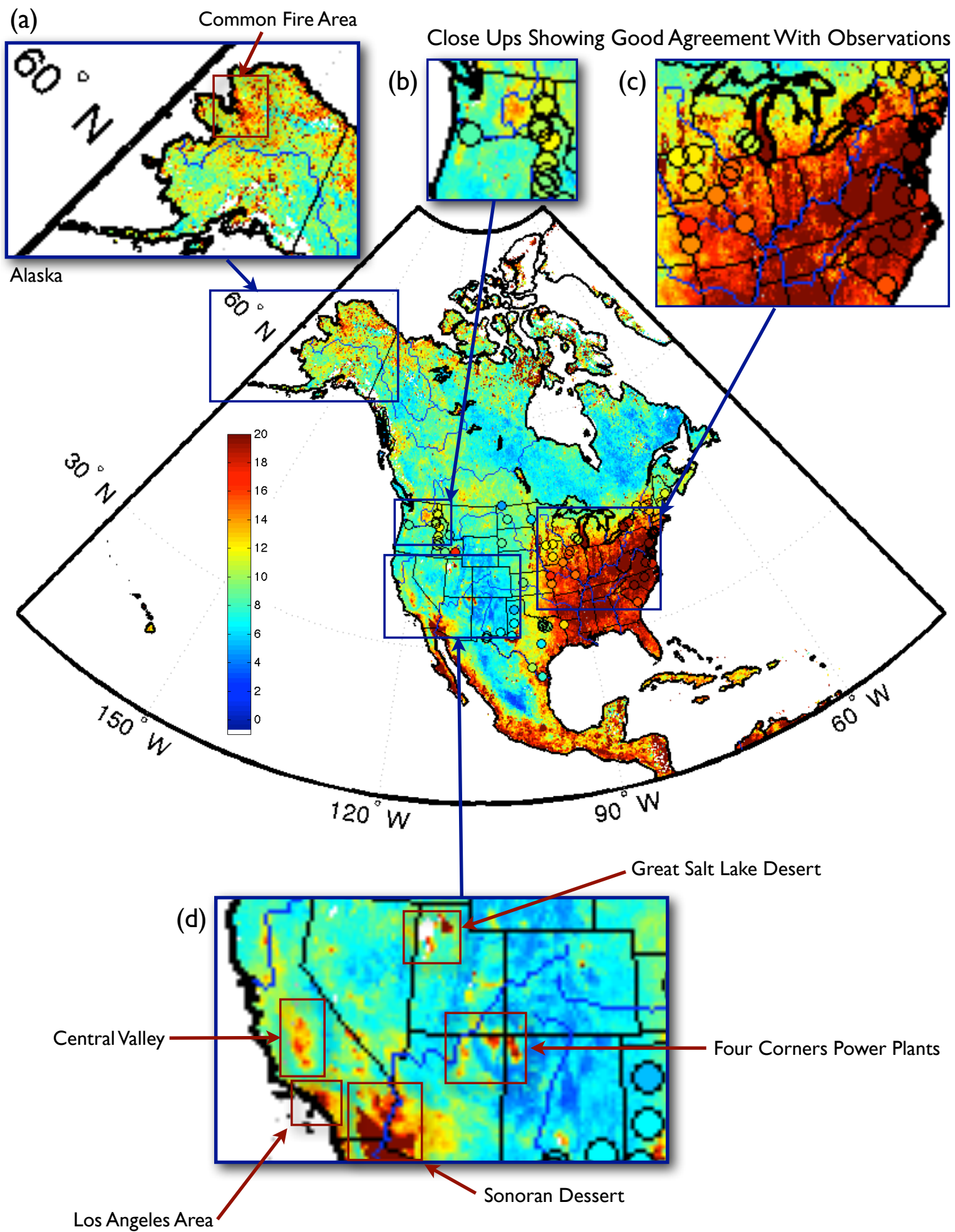
Rank	Source	Variable	Type
1		Population Density	Input
2	Satellite Product	Tropospheric NO ₂ Column	Input
3	Meteorological Analyses	Surface Specific Humidity	Input
4	Satellite Product	Solar Azimuth	Input
5	Meteorological Analyses	Surface Wind Speed	Input
6	Satellite Product	White-sky Albedo at 2,130 nm	Input
7	Satellite Product	White-sky Albedo at 555 nm	Input
8	Meteorological Analyses	Surface Air Temperature	Input
9	Meteorological Analyses	Surface Layer Height	Input
10	Meteorological Analyses	Surface Ventilation Velocity	Input
11	Meteorological Analyses	Total Precipitation	Input
12	Satellite Product	Solar Zenith	Input
13	Meteorological Analyses	Air Density at Surface	Input
14	Satellite Product	Cloud Mask Qa	Input
15	Satellite Product	Deep Blue Aerosol Optical Depth 470 nm	Input
16	Satellite Product	Sensor Zenith	Input
17	Satellite Product	White-sky Albedo at 858 nm	Input
18	Meteorological Analyses	Surface Velocity Scale	Input
19	Satellite Product	White-sky Albedo at 470 nm	Input
20	Satellite Product	Deep Blue Angstrom Exponent Land	Input
21	Satellite Product	White-sky Albedo at 1,240 nm	Input
22	Satellite Product	Scattering Angle	Input
23	Satellite Product	Sensor Azimuth	Input
24	Satellite Product	Deep Blue Surface Reflectance 412 nm	Input
25	Satellite Product	White-sky Albedo at 1,640 nm	Input
26	Satellite Product	Deep Blue Aerosol Optical Depth 660 nm	Input
27	Satellite Product	White-sky Albedo at 648 nm	Input
28	Satellite Product	Deep Blue Surface Reflectance 660 nm	Input
29	Satellite Product	Cloud Fraction Land	Input
30	Satellite Product	Deep Blue Surface Reflectance 470 nm	Input
31	Satellite Product	Deep Blue Aerosol Optical Depth 550 nm	Input
32	Satellite Product	Deep Blue Aerosol Optical Depth 412 nm	Input
	In-situ Observation	PM_{2.5}	Target



Long-Term Average 1997-present



Mobile Sensors
Wearable Sensors

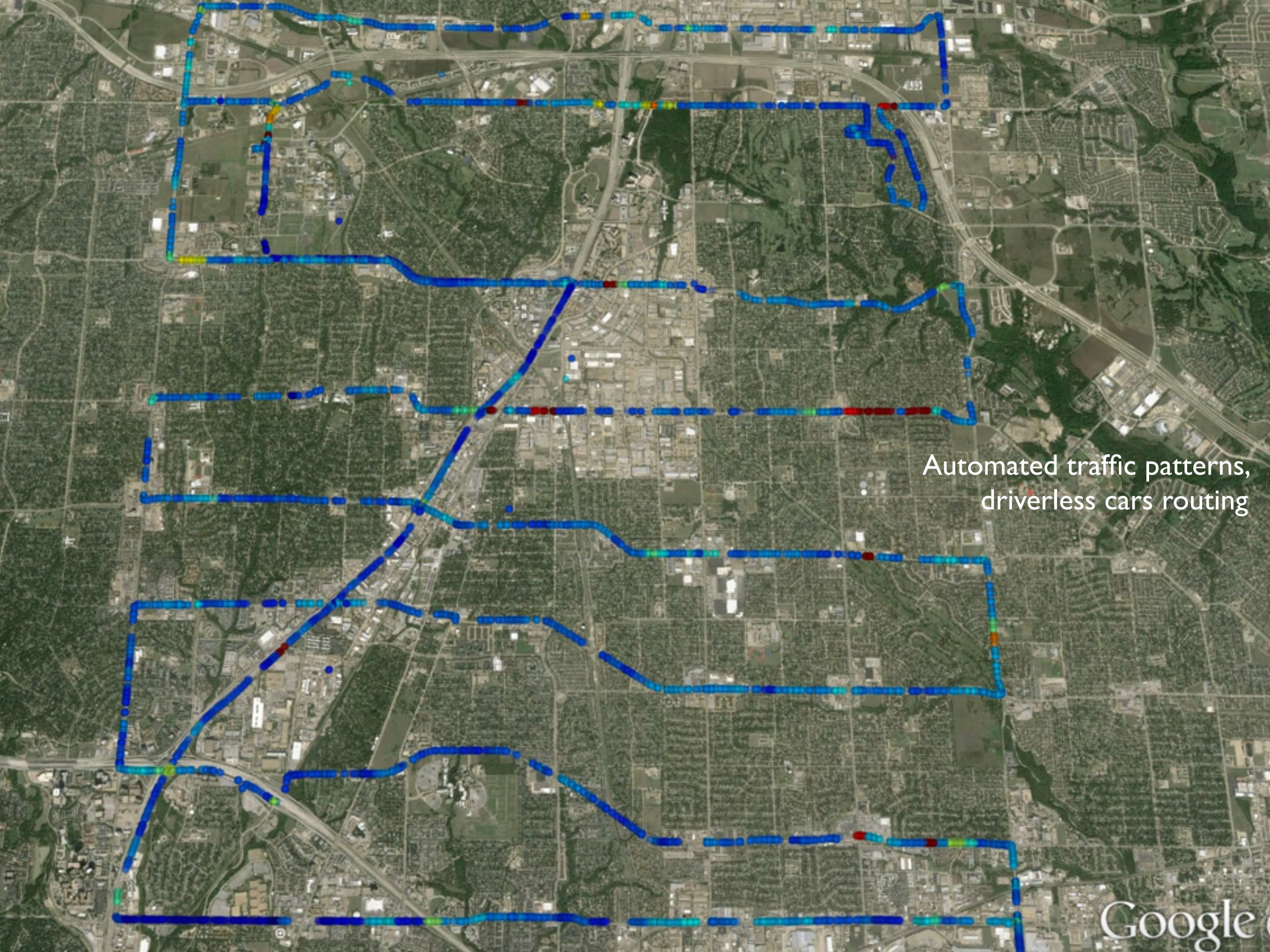


This is a BigData Problem of Great Societal Relevance

- Collecting data in real time from national and global networks requires **bandwidth**.
- With the next generation of wearable sensors and the **internet of things** this data volume will rapidly increase.
- A variety of applications enabled by **BigData**, **higher bandwidth** and **cloud processing**.
- Future finer granularity and **two way** communication will dramatically increase the size of the data bringing air quality to the micro scale, just like weather data.

	Time Taken			
	10 Mbps	20 Mbps	50 Mbps	1 Gbps
40 TB training data	185 days	93 days	37 days	1 day 21 hours
4 Gb update	54m	27m	11m	32s





Automated traffic patterns,
driverless cars routing

VA Decision Support Tools



Personalized Alerts



Dr. Watson



Staffing & Resource Management



THRIVE Medical Environment Analytics Engine



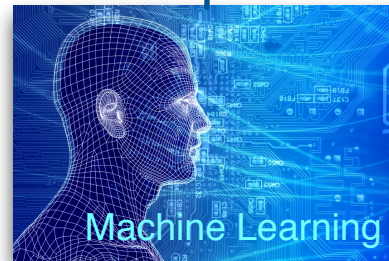
ER Admissions
All ICD Codes



Daily Global Air Quality Estimates



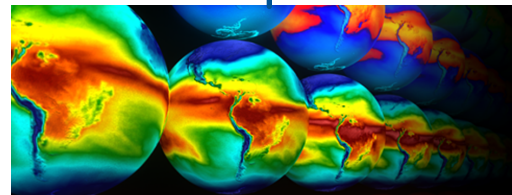
All Prescriptions



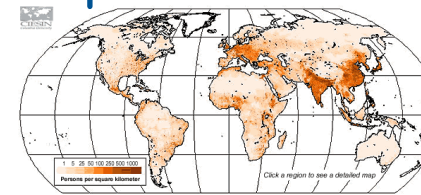
Machine Learning



NASA Earth Observation Data



NASA Earth System Model Products



Population Density and Other Related Products

More Than 40 Data Products from In-situ Observations, NASA Earth Observations, Earth System Models, Population Density & Emission Inventories

Happy Day!



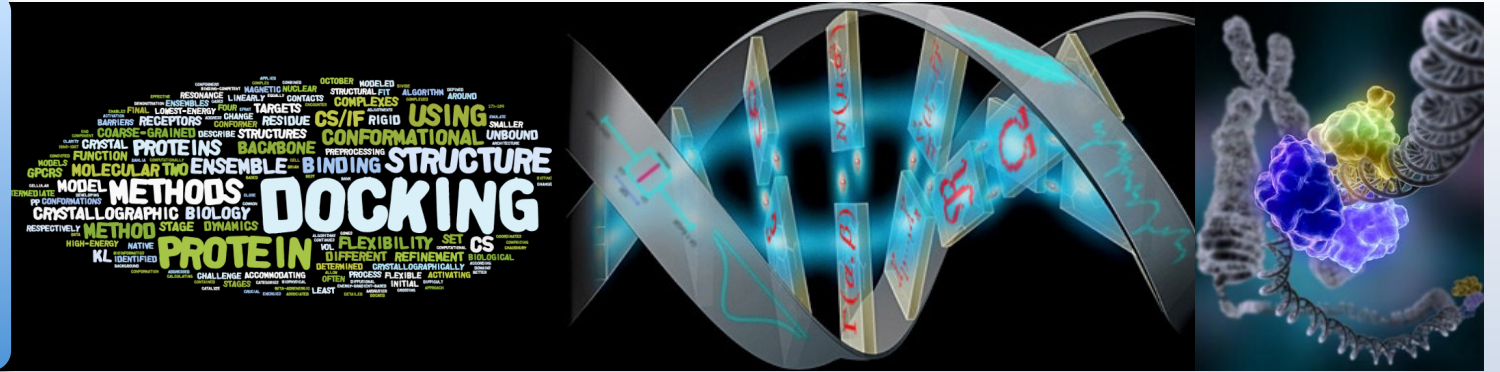




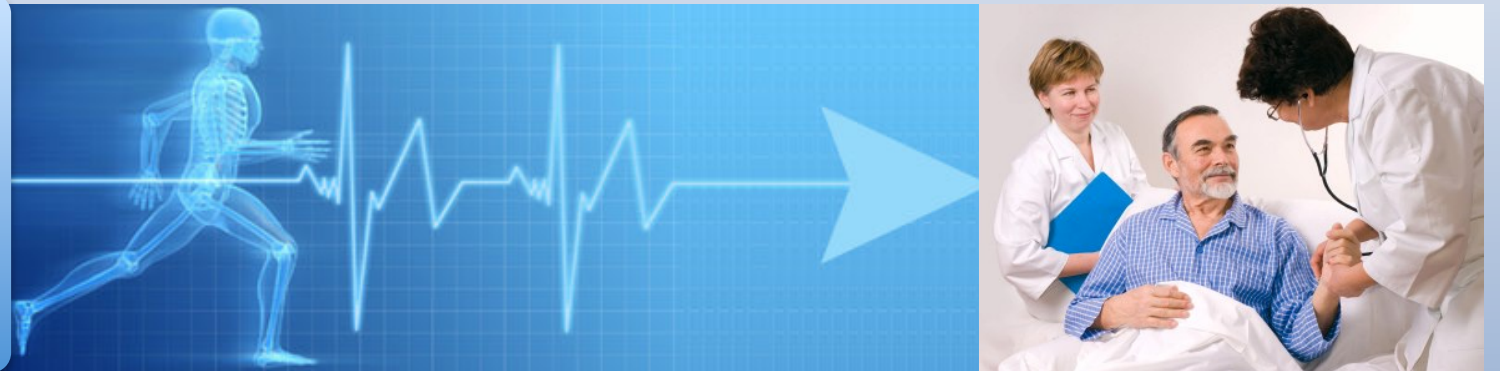
Street View
Pollution View

Think Big: Holistic & Comprehensive Informatics

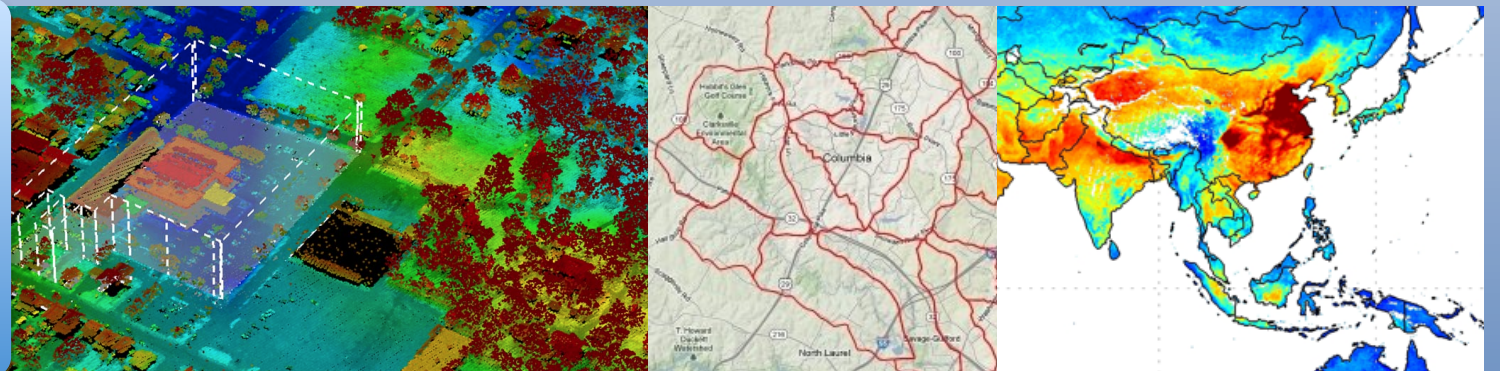
Bio Informatics



Medical Informatics



Environmental Informatics



THRIVE

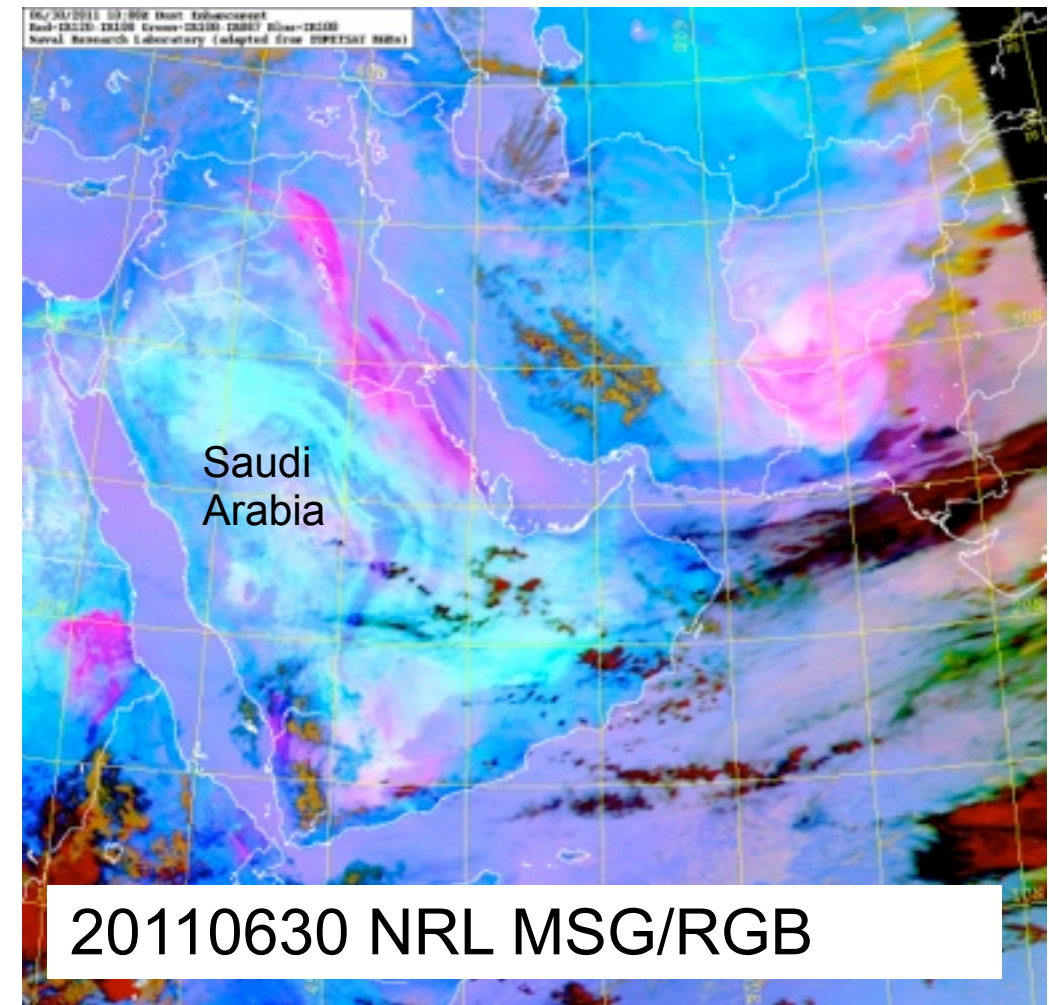
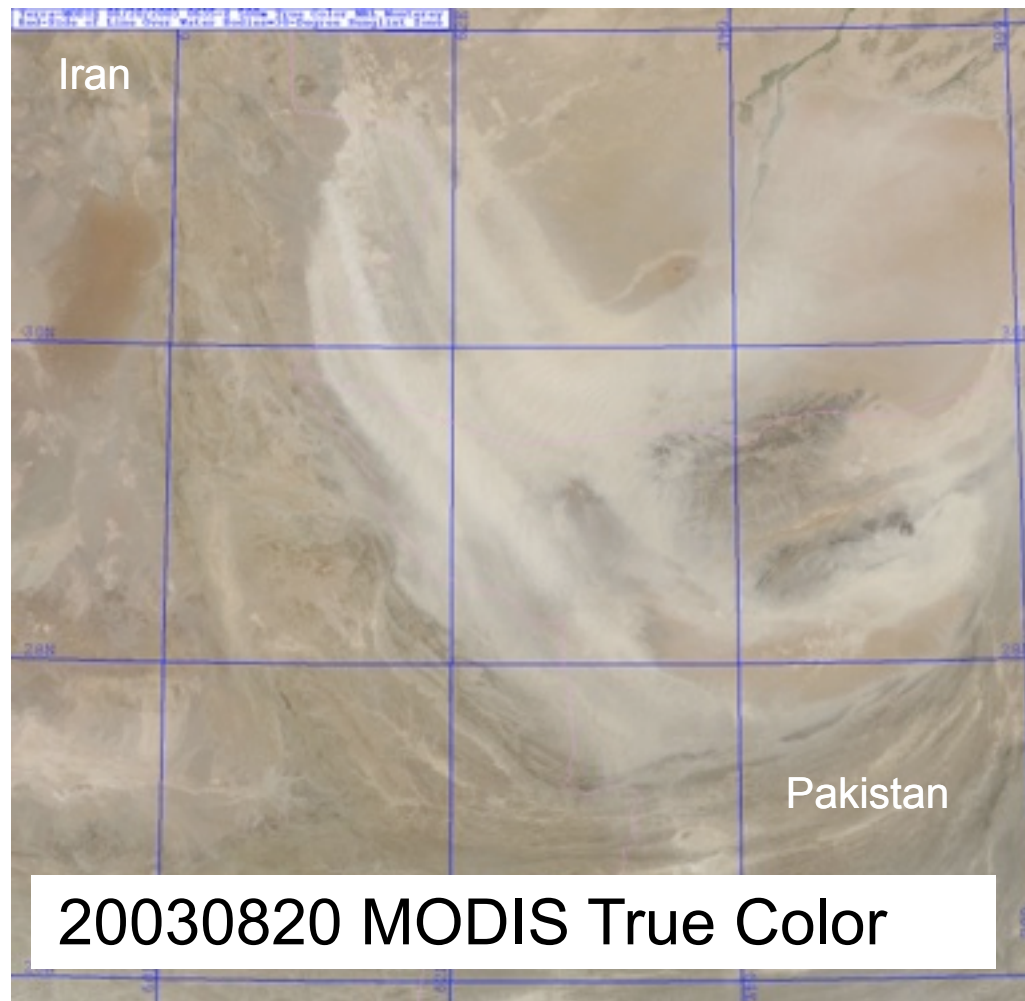
Multiple Big Data + EMR + Social Media + Machine Learning + Causality
A Cross-cutting Platform for Comprehensive Informatics for **Data Driven Decisions in Patient Centered Care** facilitated by *High Speed Low-Latency networks*, multiple massive datasets from large distributed sensor networks, EMR, and *local cloud computing*.

A42A-08

High Resolution Identification of Dust Sources Using Machine Learning and Remote Sensing Data

Annette Walker and David J. Lary

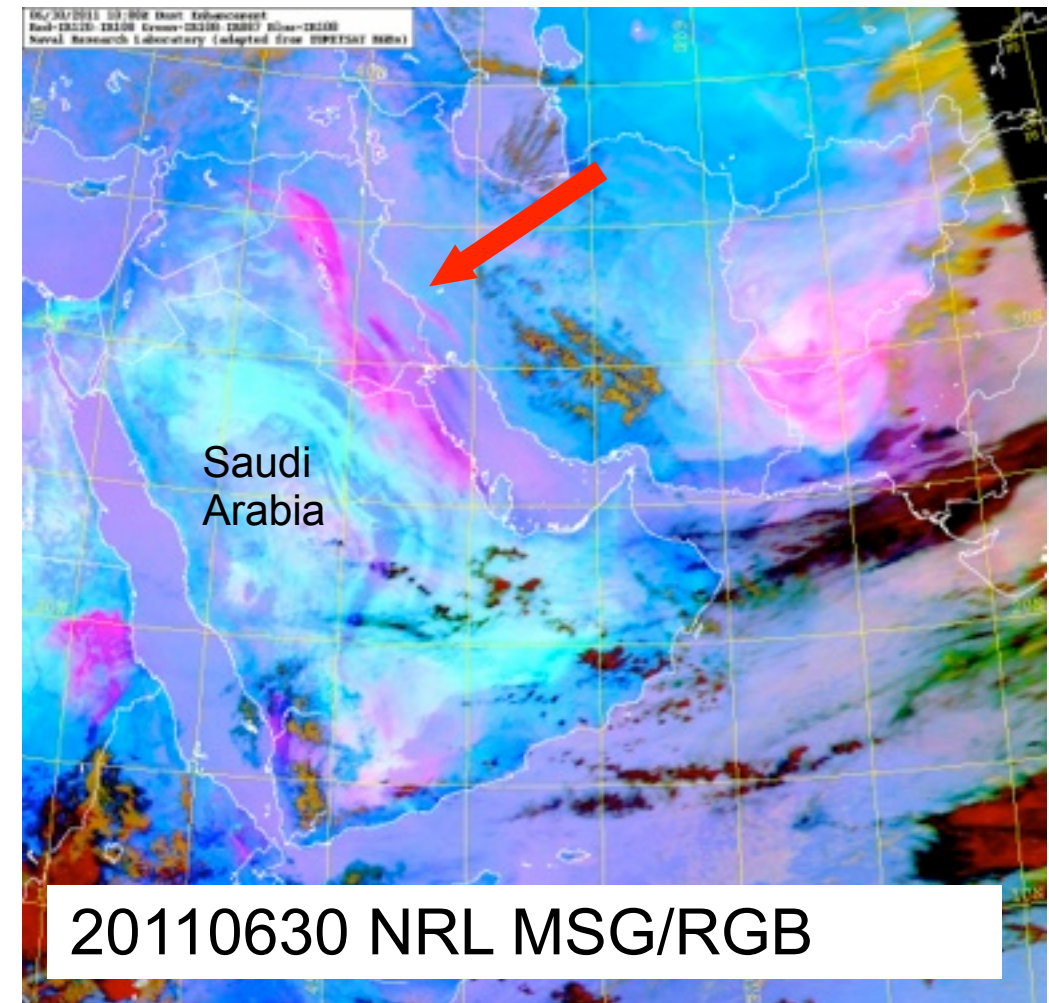
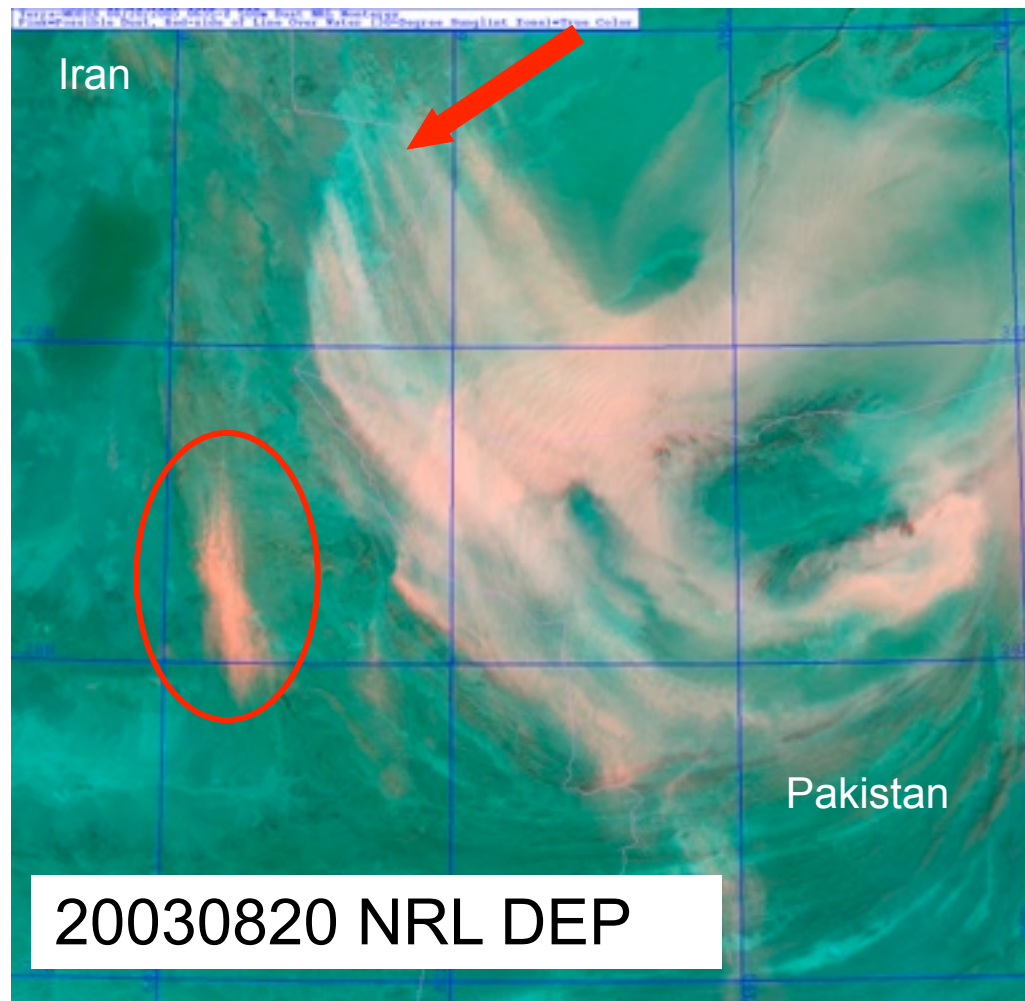
NRL High-resolution Dust Source Database



Approach and Methodology

- **10 years of DEP (2 yr MSG/RGB) imagery**
- COAMPS 10 m wind overlays
- Surface weather plots
- **ENVI (Gis-like software)**
- NGDC topographical 10°X10° tiles
- **Overlay 0.25° grid or use Google Earth (GE)**
- **Dust source area entered into database** (cursor location tool = 1km precision)
- Cross-correlate land and water features using maps, atlases, Landsat images (detailed topographic, geographic, and geomorphic information, **GE**)
- Technical and governmental reports

NRL High-resolution Dust Source Database



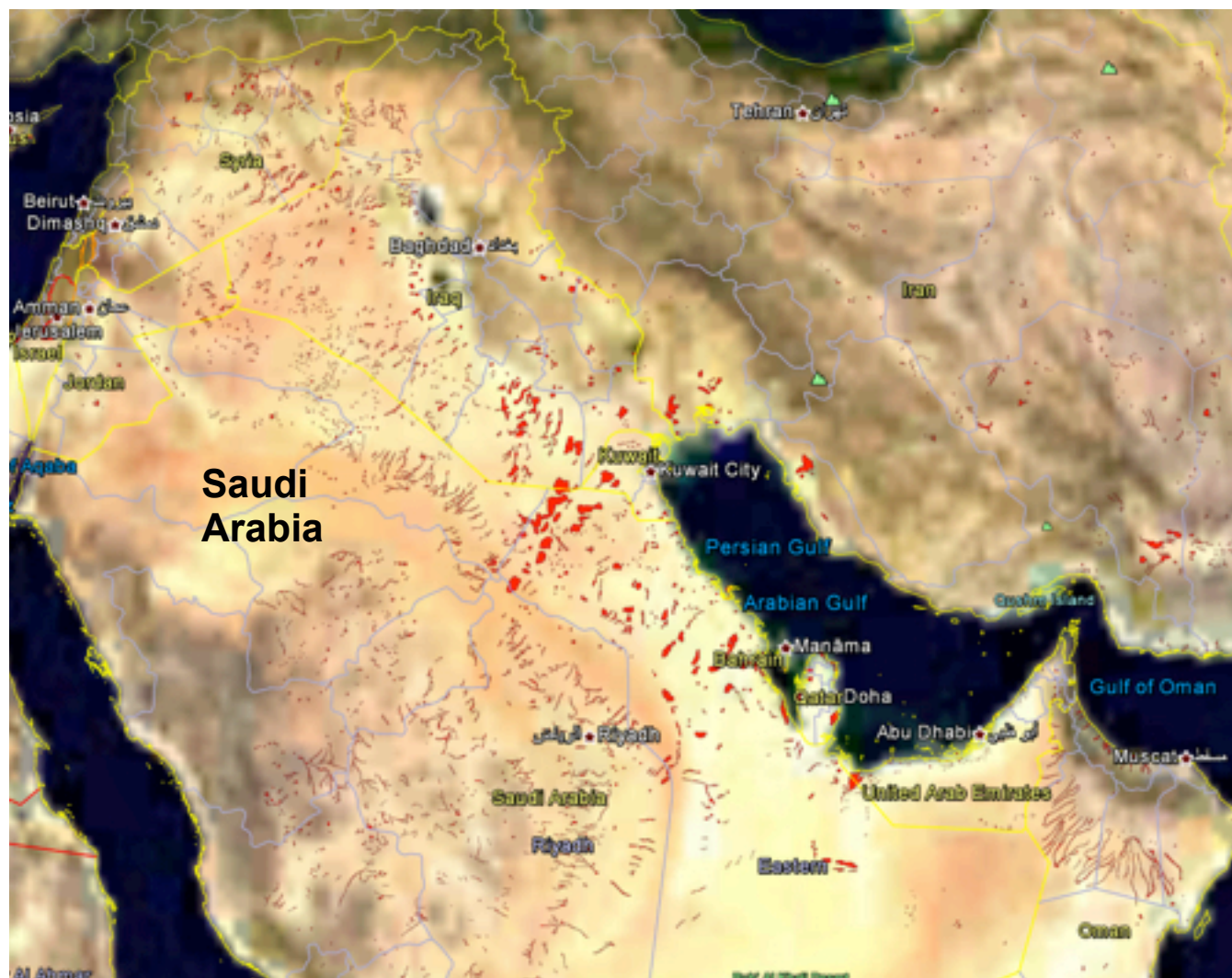
Approach and Methodology

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NRL High-resolution Dust Source Database

Solid red and purple shapes identify dust source areas located using DEP and MSG.

SW Asia DSD



East Asia DSD

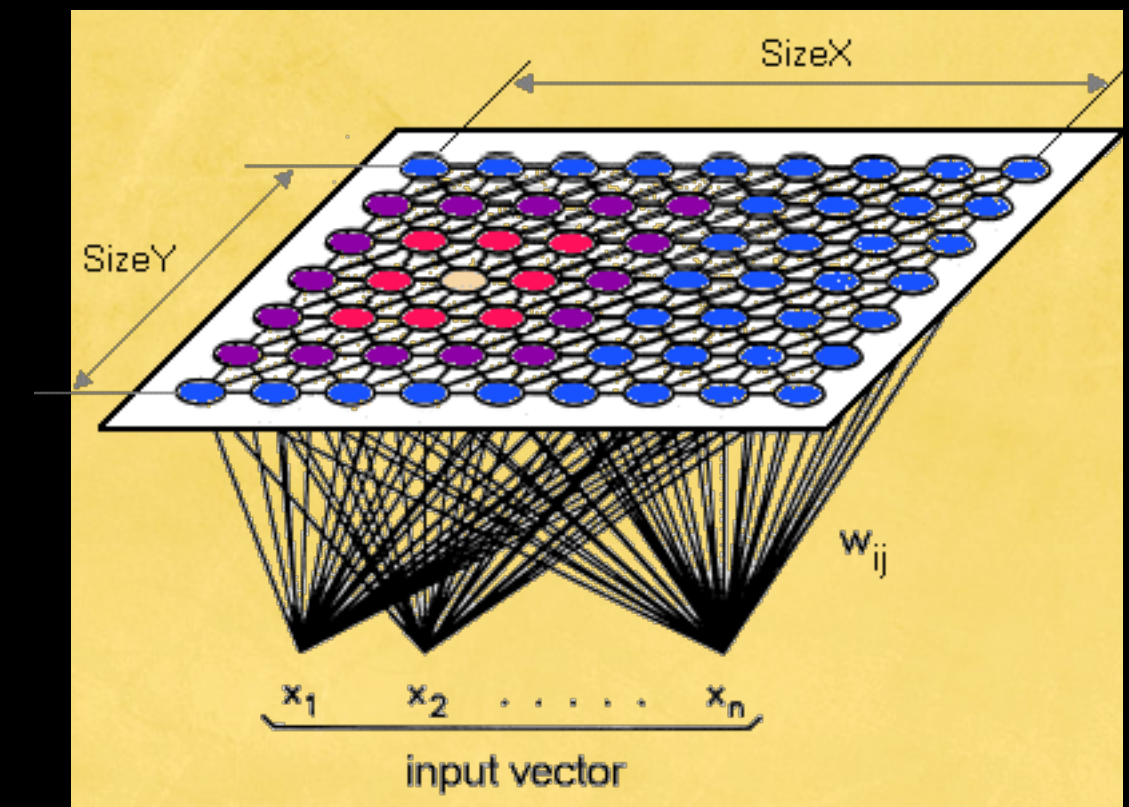
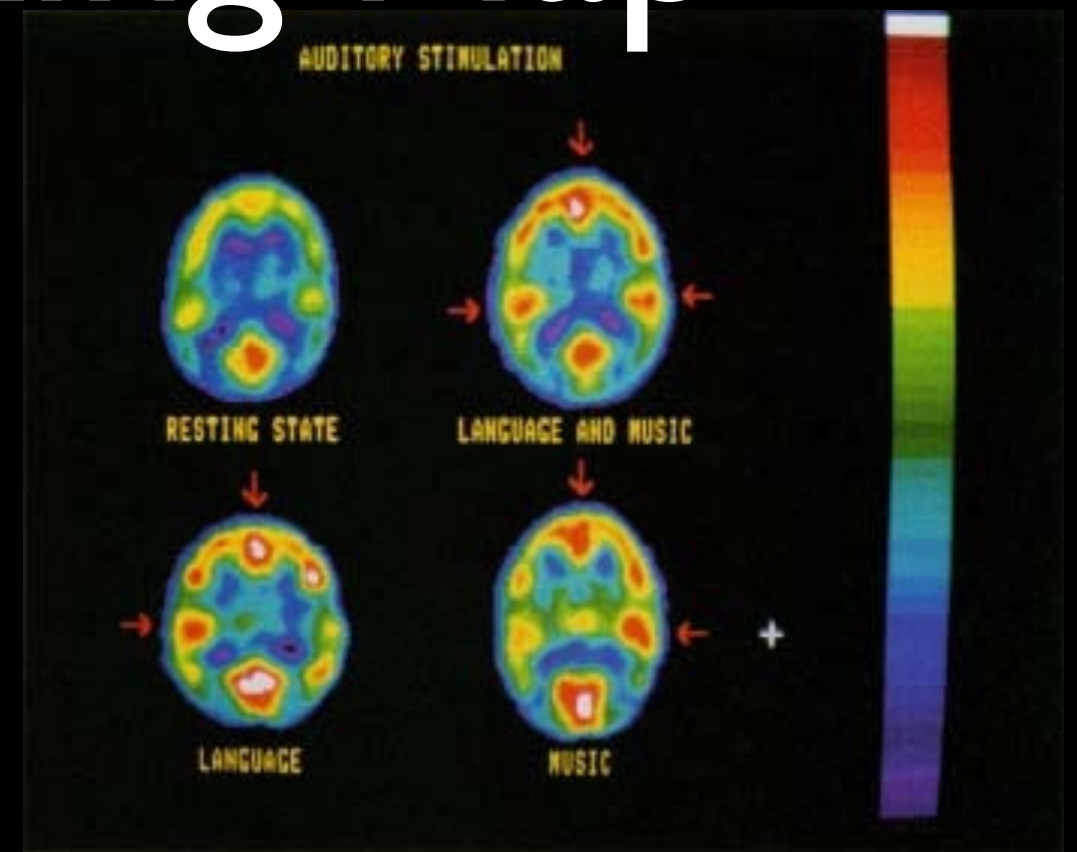


Self-Organizing Map

SOMs reduce dimensionality by producing a map that objectively plots the similarities of the data by grouping similar data items together.

SOMs learn to classify input vectors according to how they are grouped in the input space.

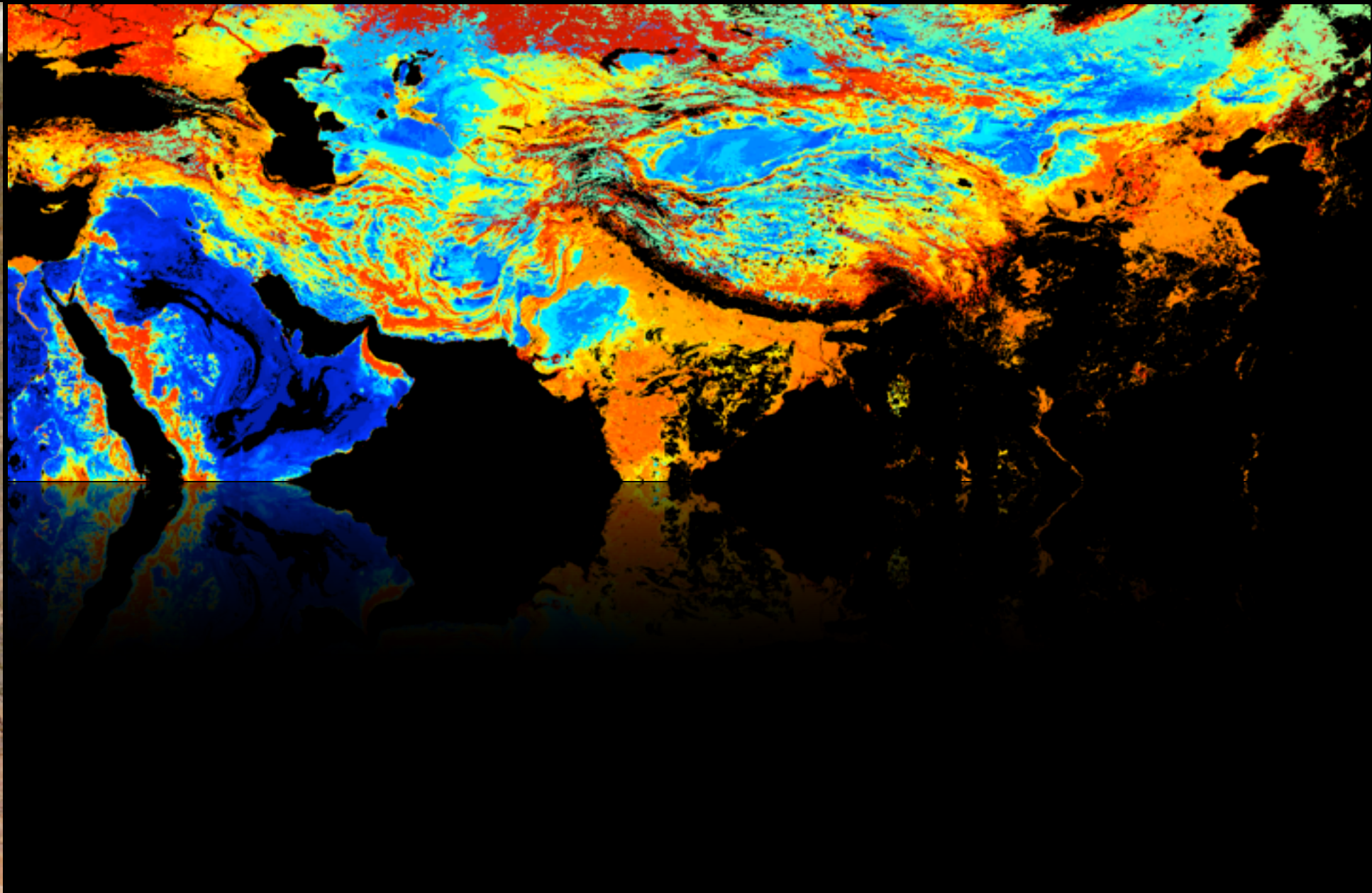
SOMs learn both the distribution and topology of the input vectors they are trained on. This approach allows SOMs to accomplish two things, reduce dimensions and display similarities.



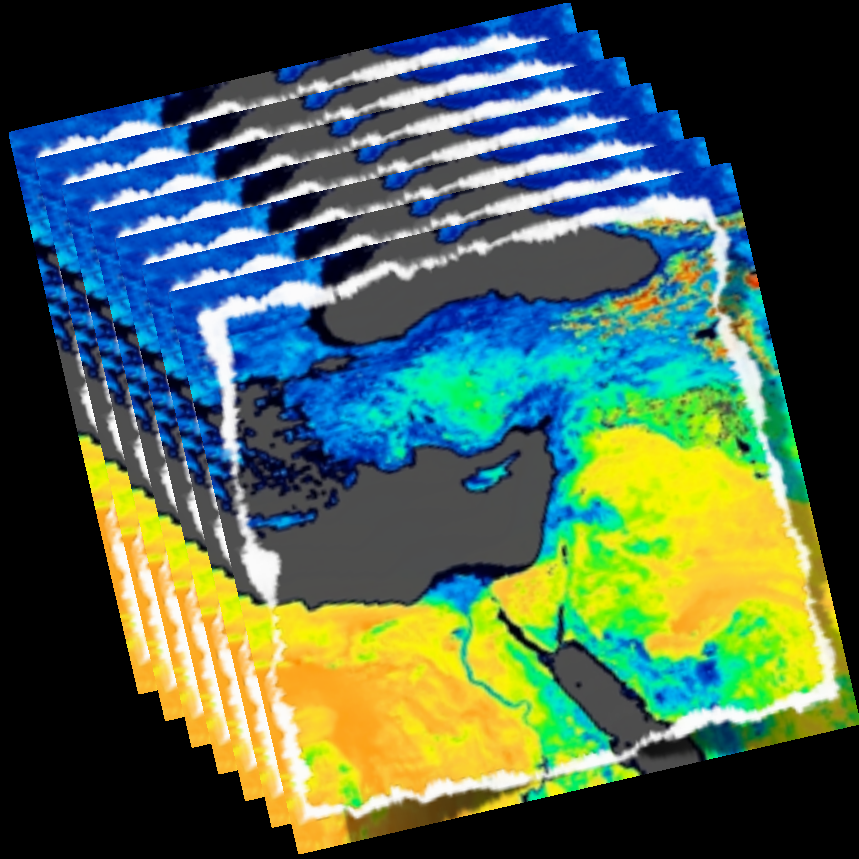
Detecting Dust Sources



Detecting Dust Sources

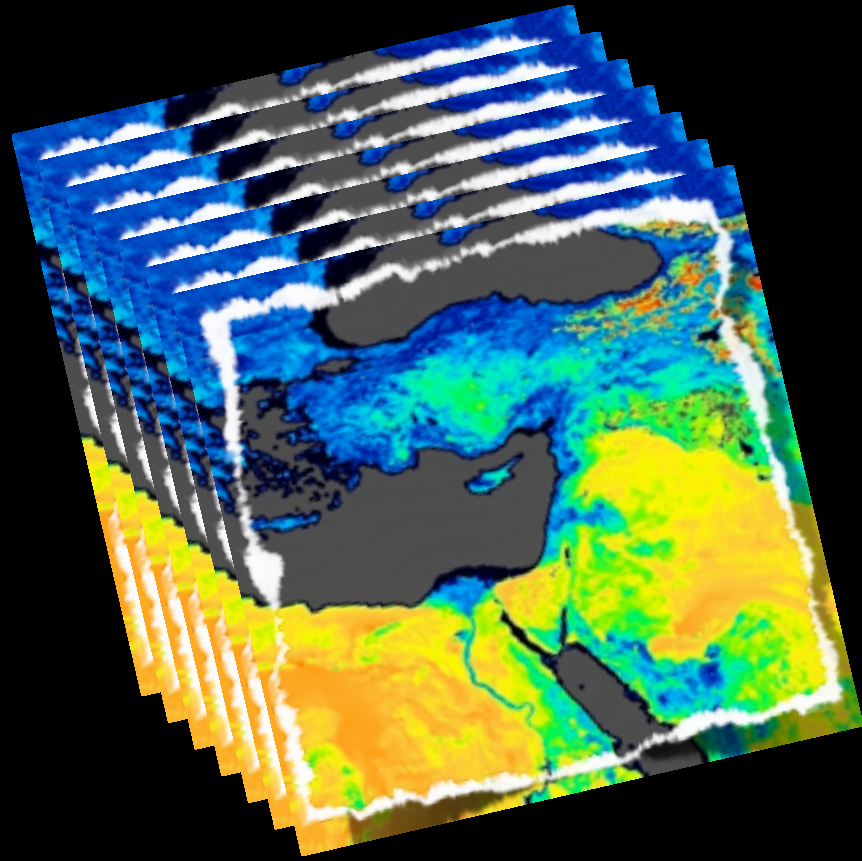


Self Organizing Map Classification

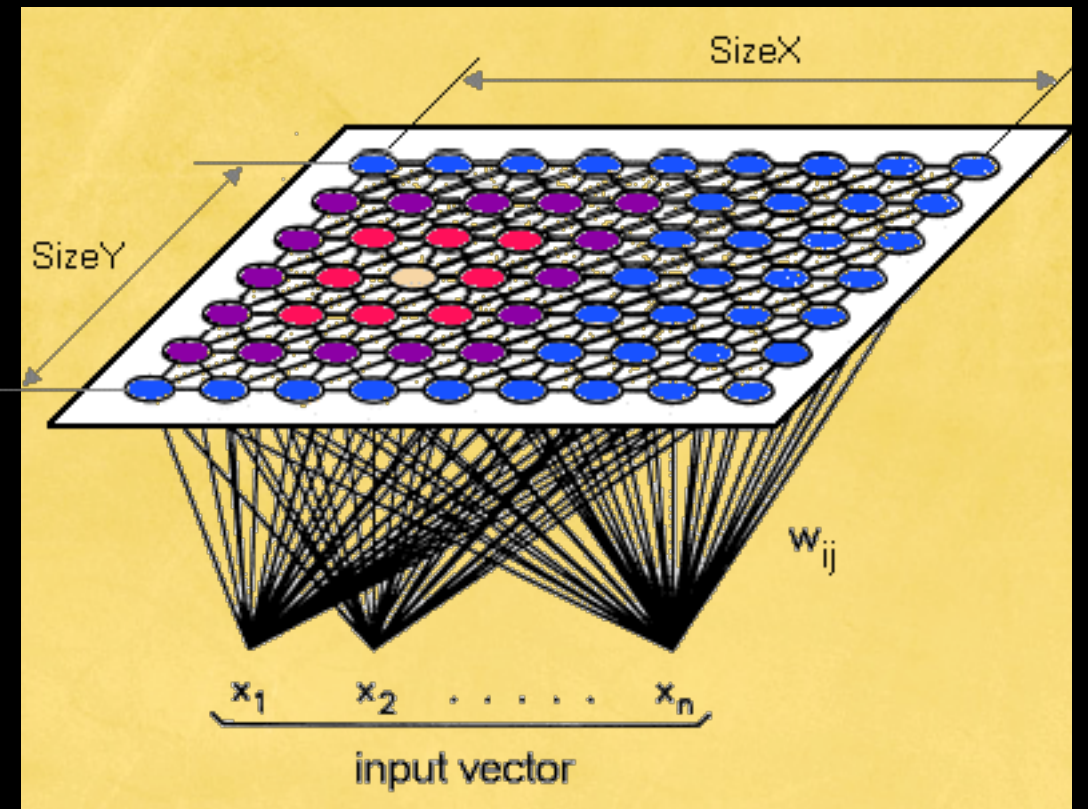


7 Bands
MODIS MCD43C3
bihemispherical reflectance

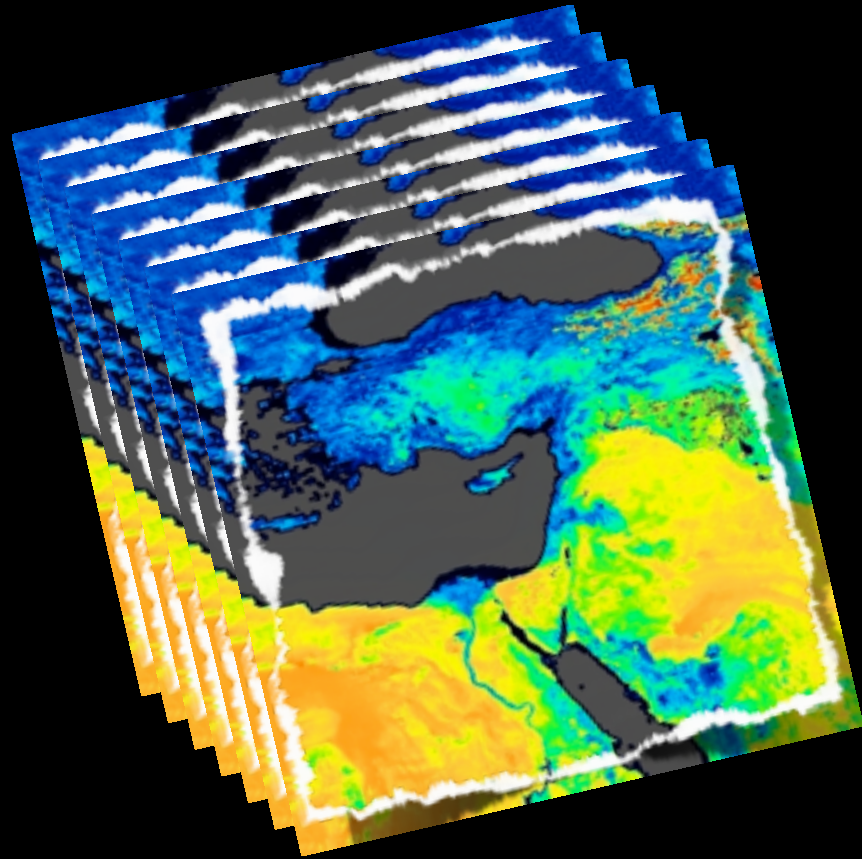
Self Organizing Map Classification



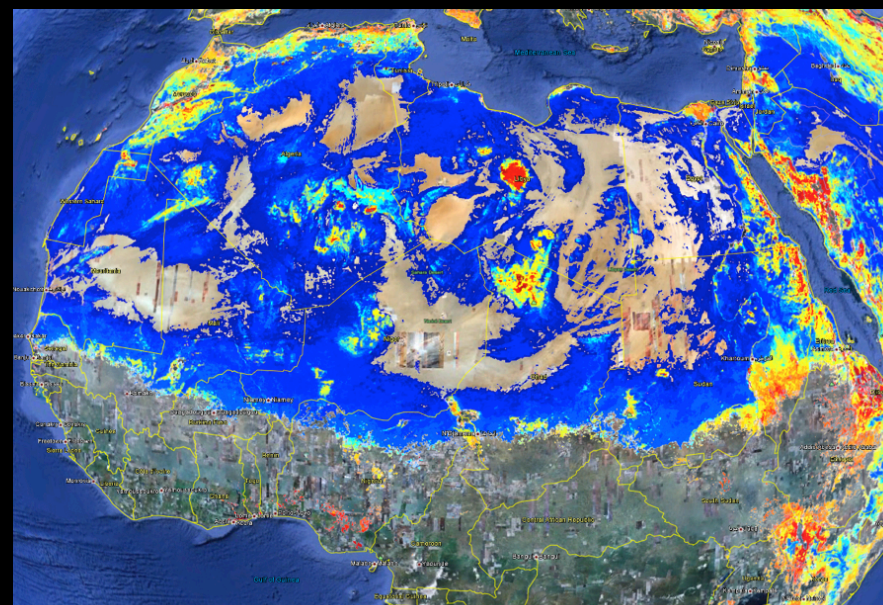
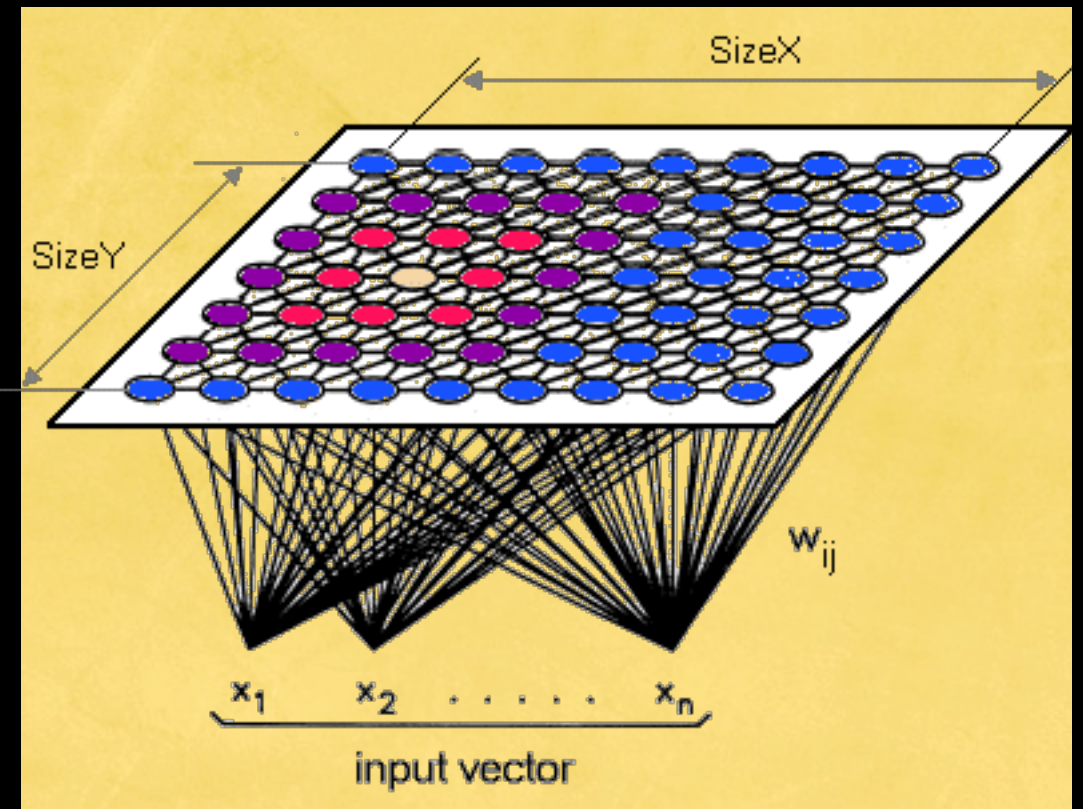
7 Bands
MODIS MCD43C3
bihemispherical reflectance



Self Organizing Map Classification



7 Bands
MODIS MCD43C3
bihemispherical reflectance



Libyan Dust Event: May 9, 2010 (8Z – 12Z)

Jabal al Akhdar (الجبل الأخضر *Al Ġabal al 'Aḥḍar*, English: *Green Mountains*)

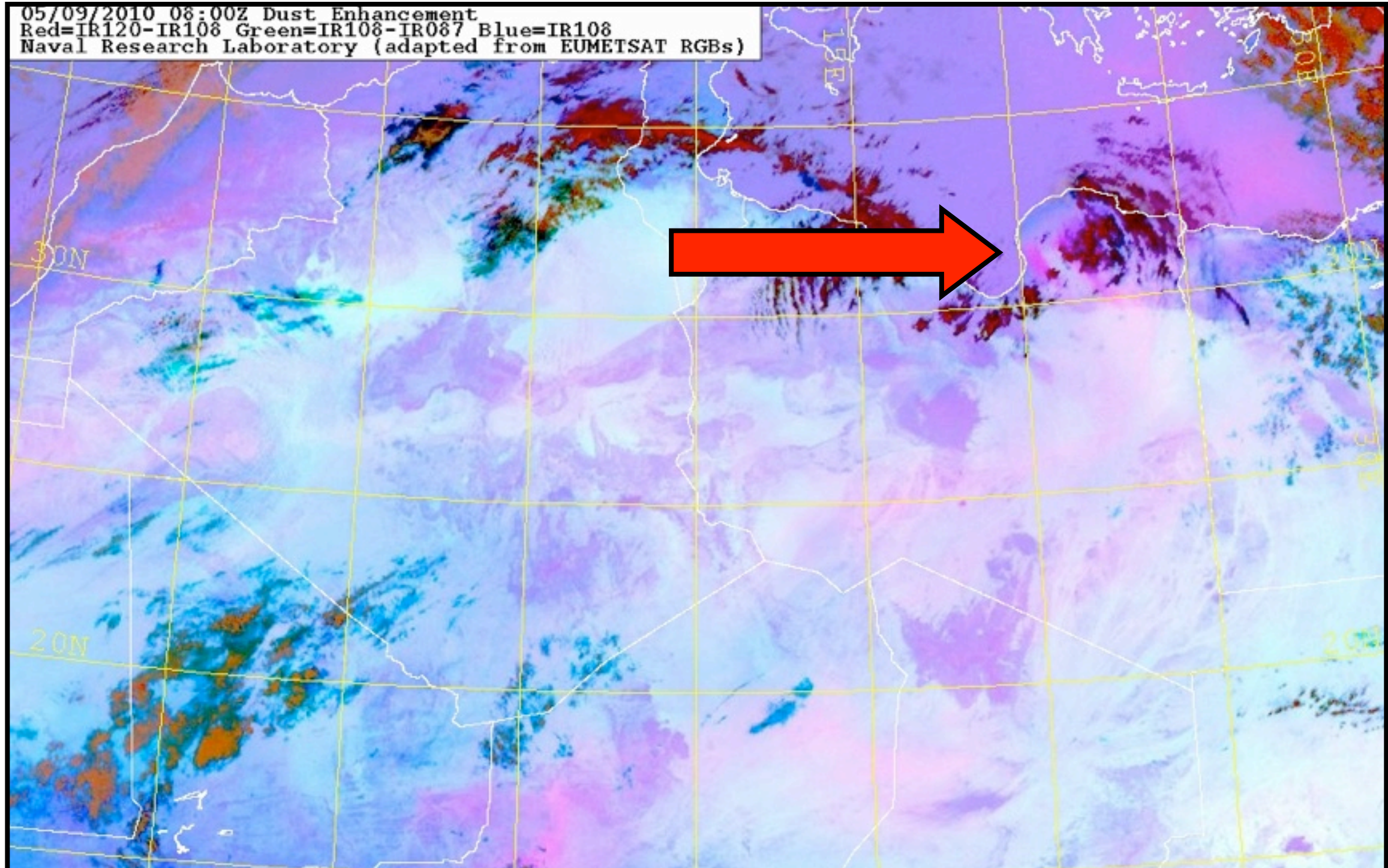
A coastal mountain range with height 1.0-1.5 km.



Libyan Dust Event: May 9, 2010 (8Z – 12Z)

Jabal al Akhdar (الجبل الأخضر *Al Ġabal al 'Aḥḍar*, English: *Green Mountains*)

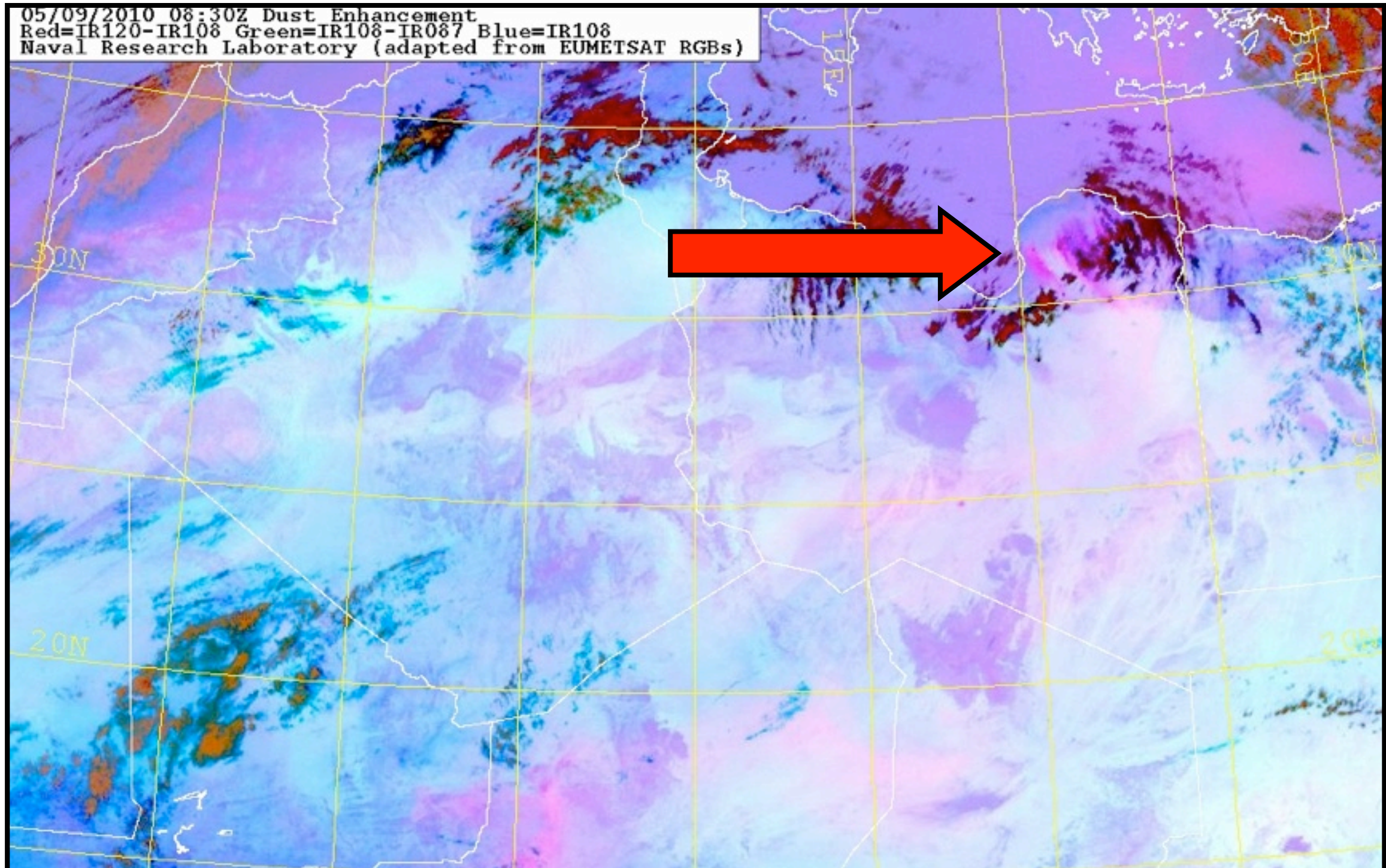
A coastal mountain range with height 1.0-1.5 km.



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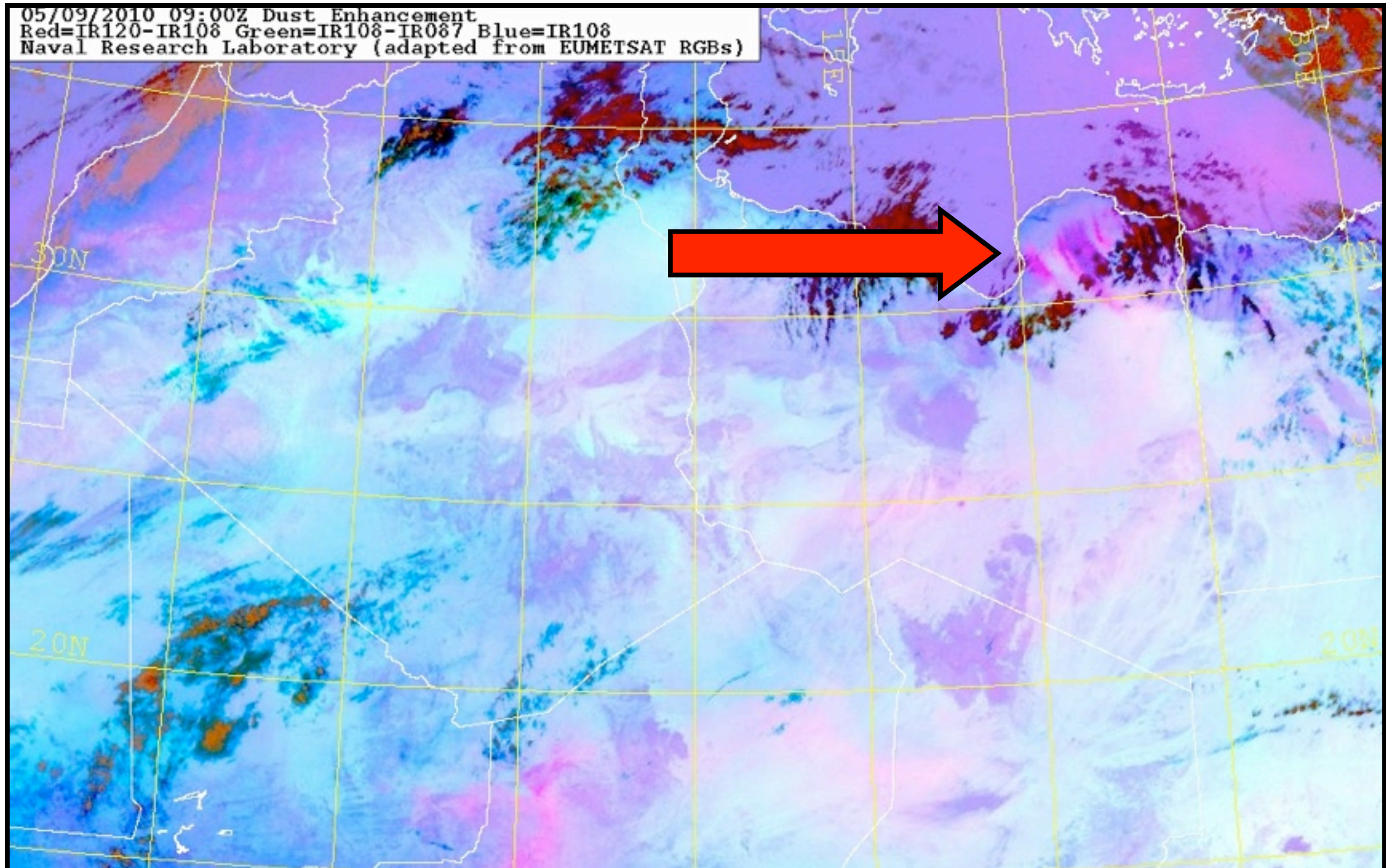
A coastal mountain range with height 1.0-1.5 km.



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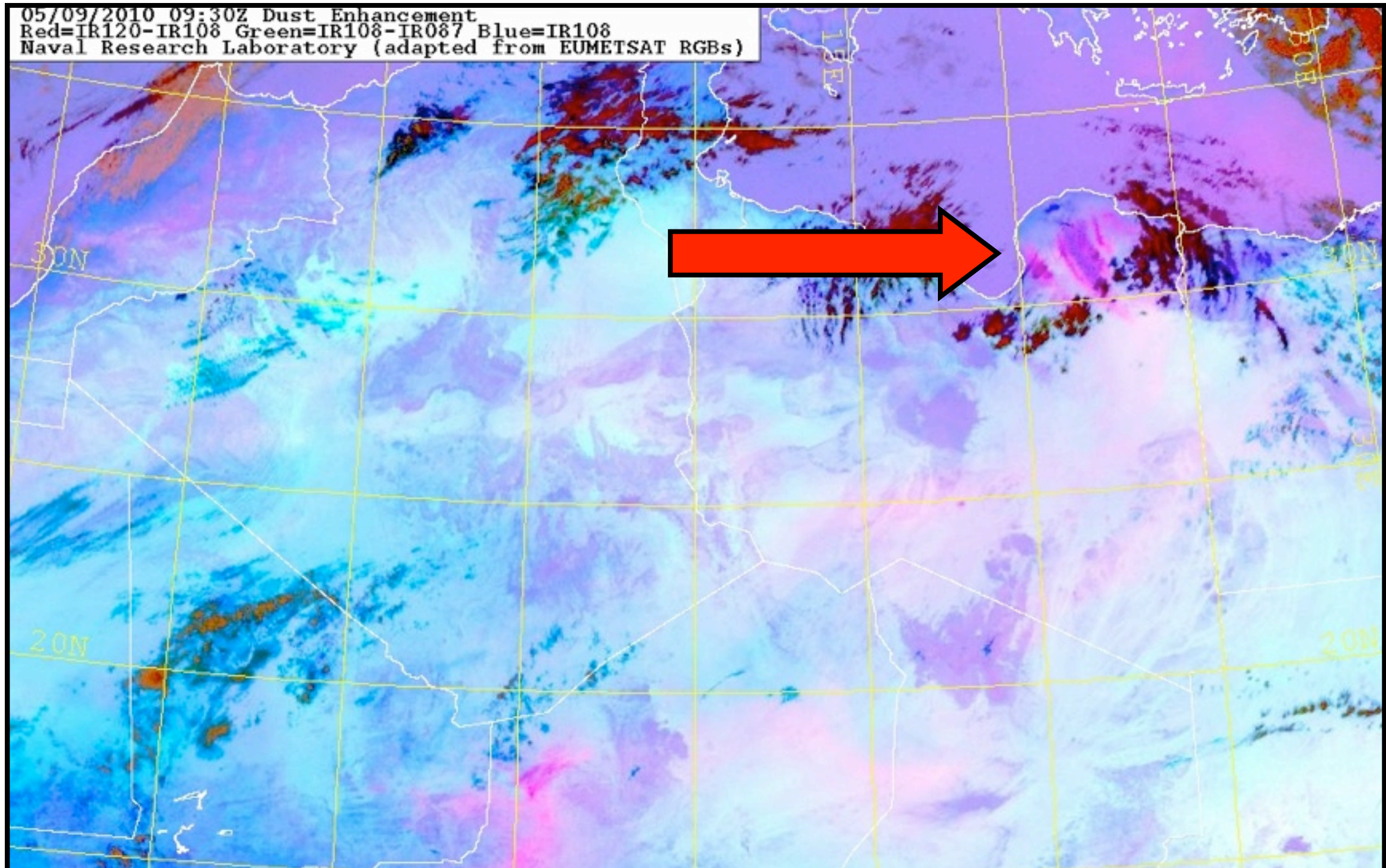
A coastal mountain range with height 1.0-1.5 km.



Libyan Dust Event: May 9, 2010 (8Z – 12Z)

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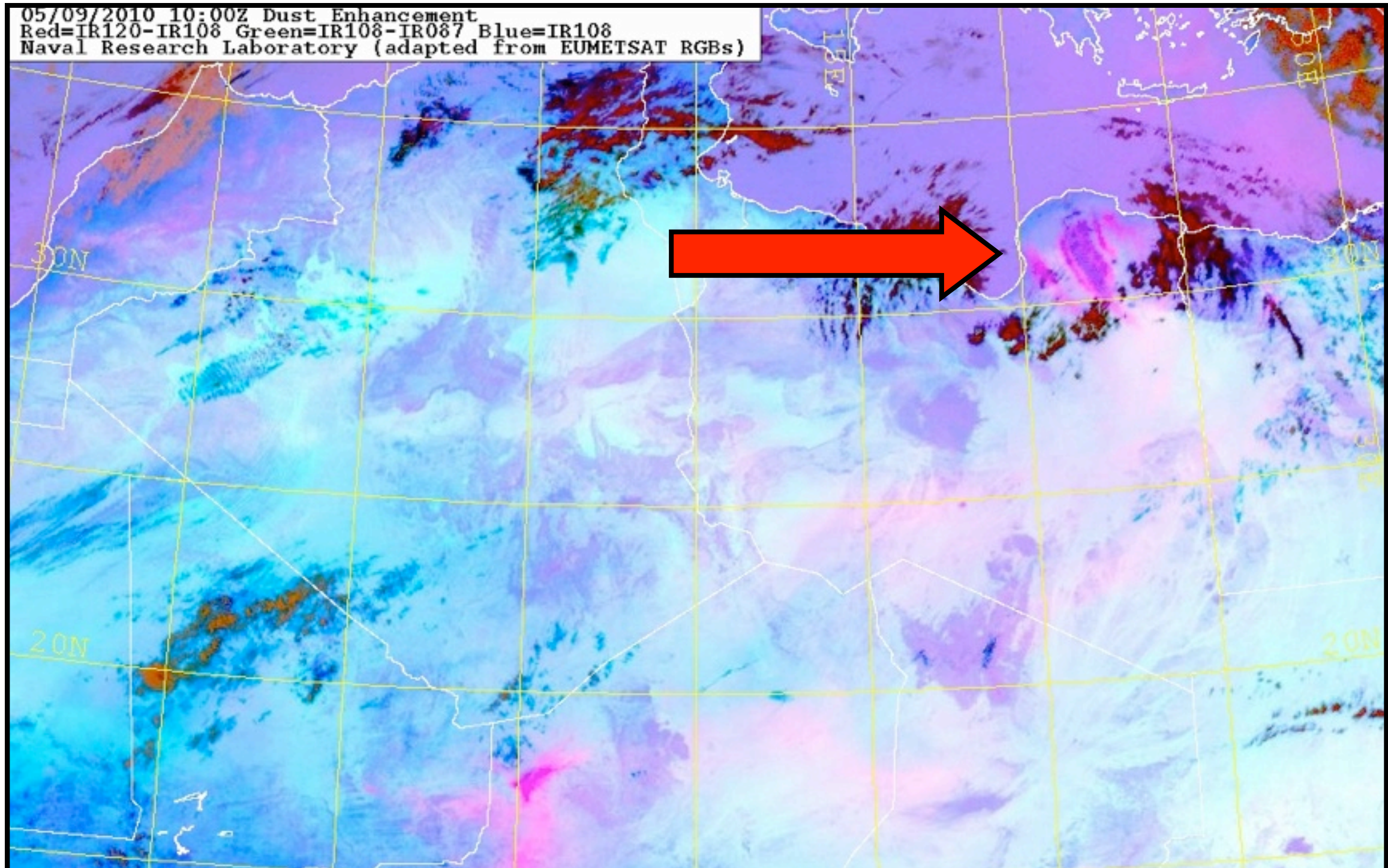
A coastal mountain range with height 1.0-1.5 km.



Libyan Dust Event: May 9, 2010 (8Z – 12Z)

Jabal al Akhdar (الجبل الأخضر *Al Ġabal al 'Aḥḍar*, English: *Green Mountains*)

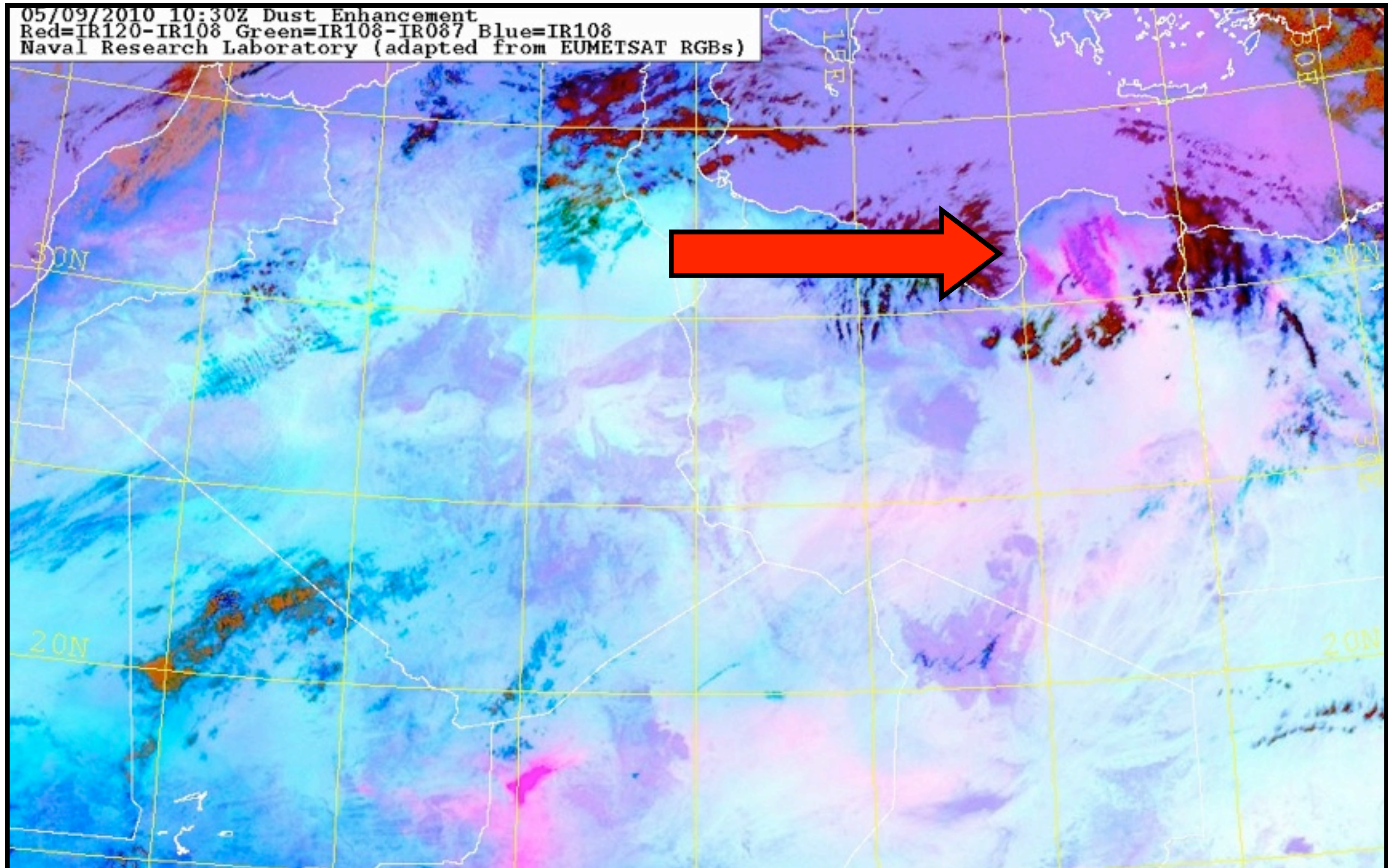
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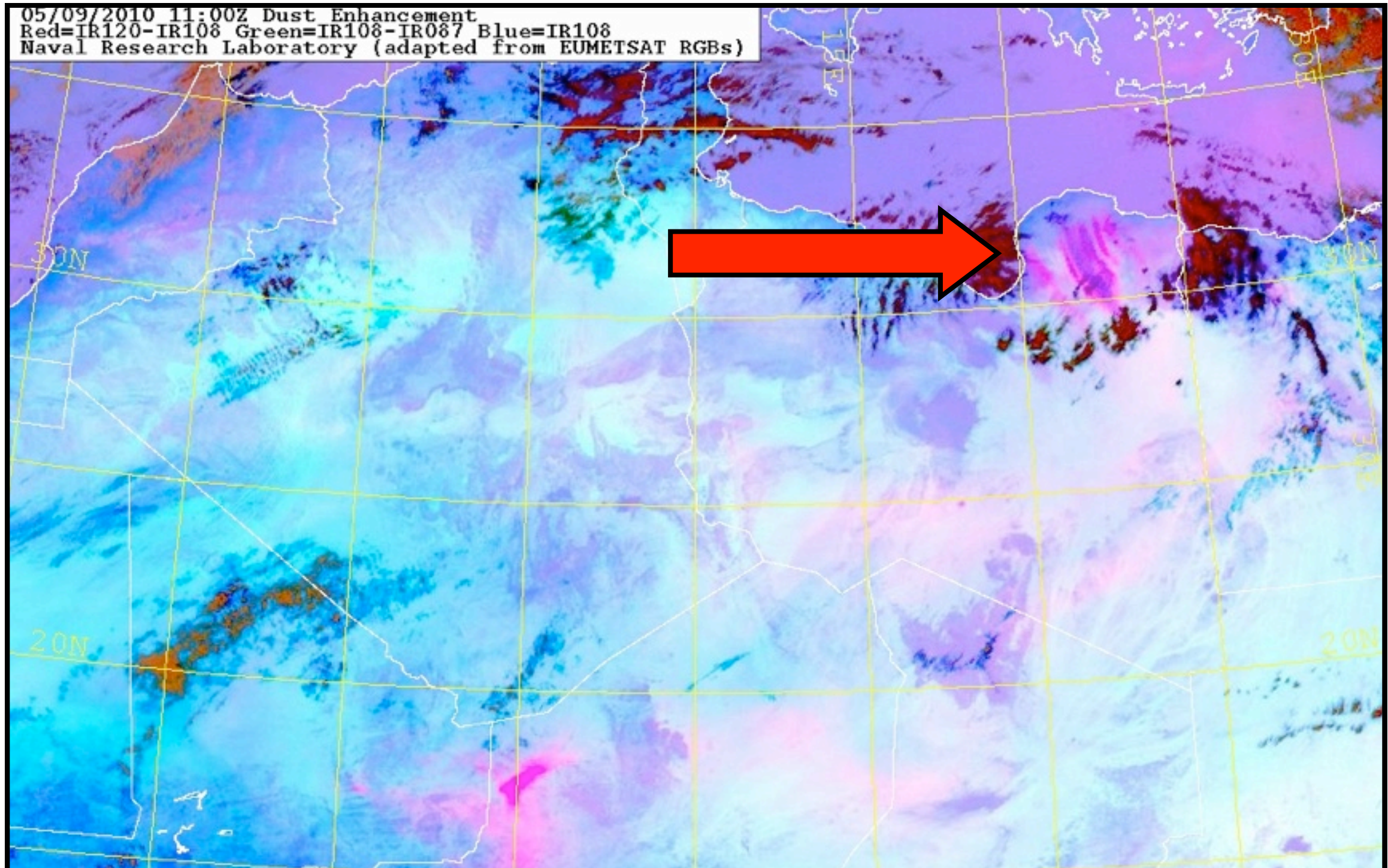
A coastal mountain range with height 1.0-1.5 km.



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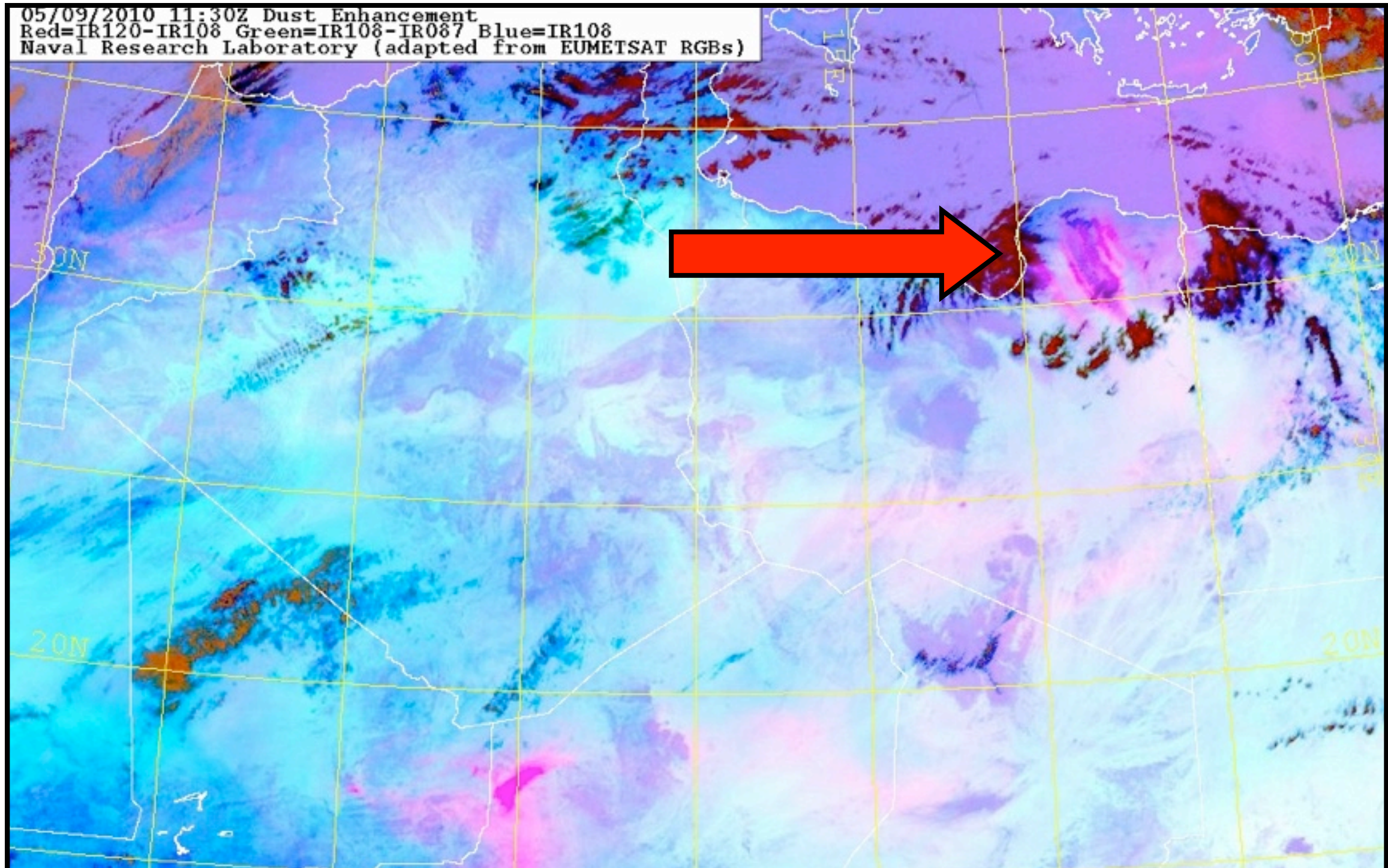
A coastal mountain range with height 1.0-1.5 km.



Libyan Dust Event: May 9, 2010 (8Z – 12Z)

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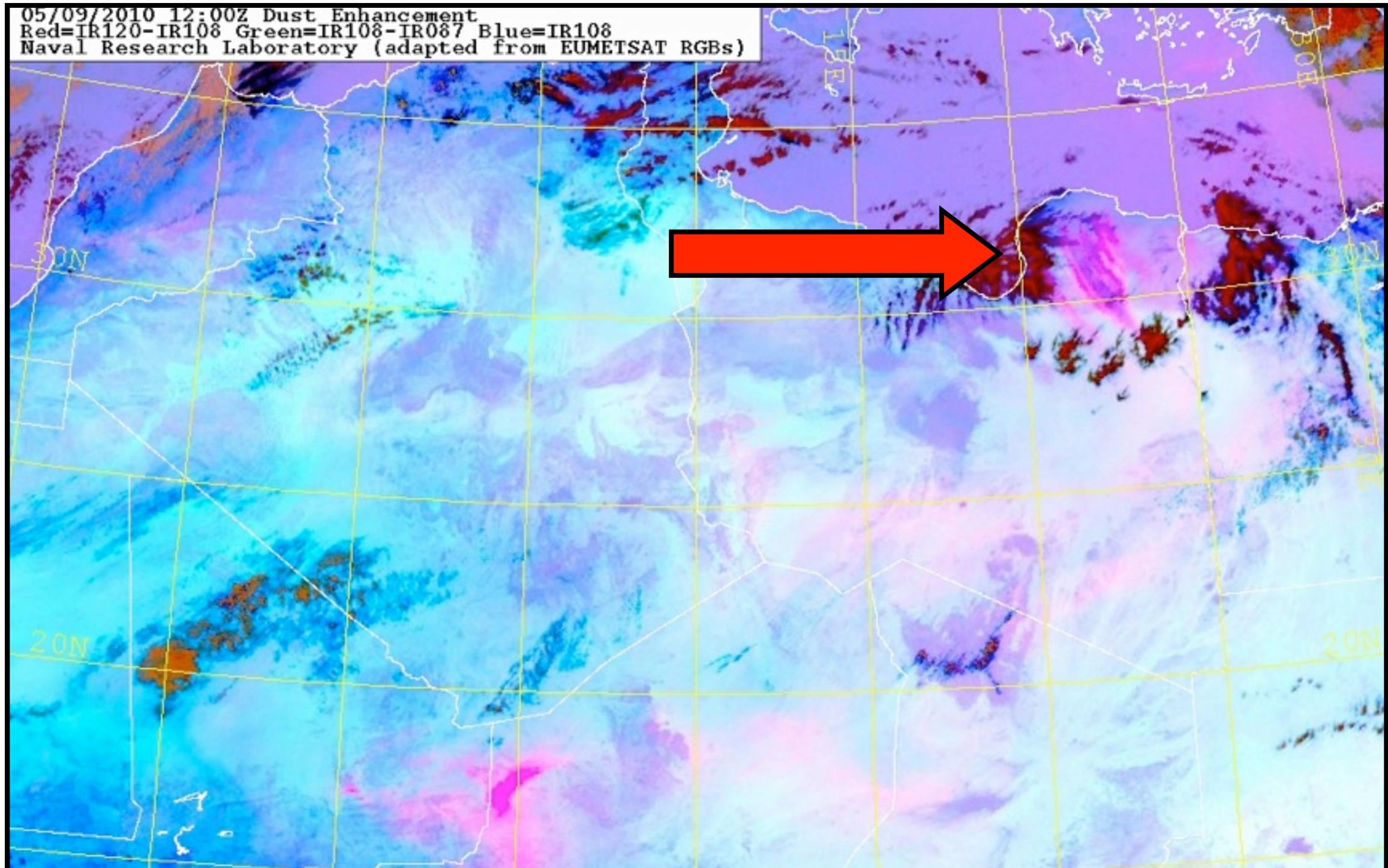
A coastal mountain range with height 1.0-1.5 km.



Libyan Dust Event: May 9, 2010 (8Z – 12Z)

Jabal al Akhdar (الجبل الأخضر *Al Ġabal al 'Aḥḍar*, English: *Green Mountains*)

A coastal mountain range with height 1.0-1.5 km.



Libyan Dust Event: May 9, 2010 (6Z – 8Z)

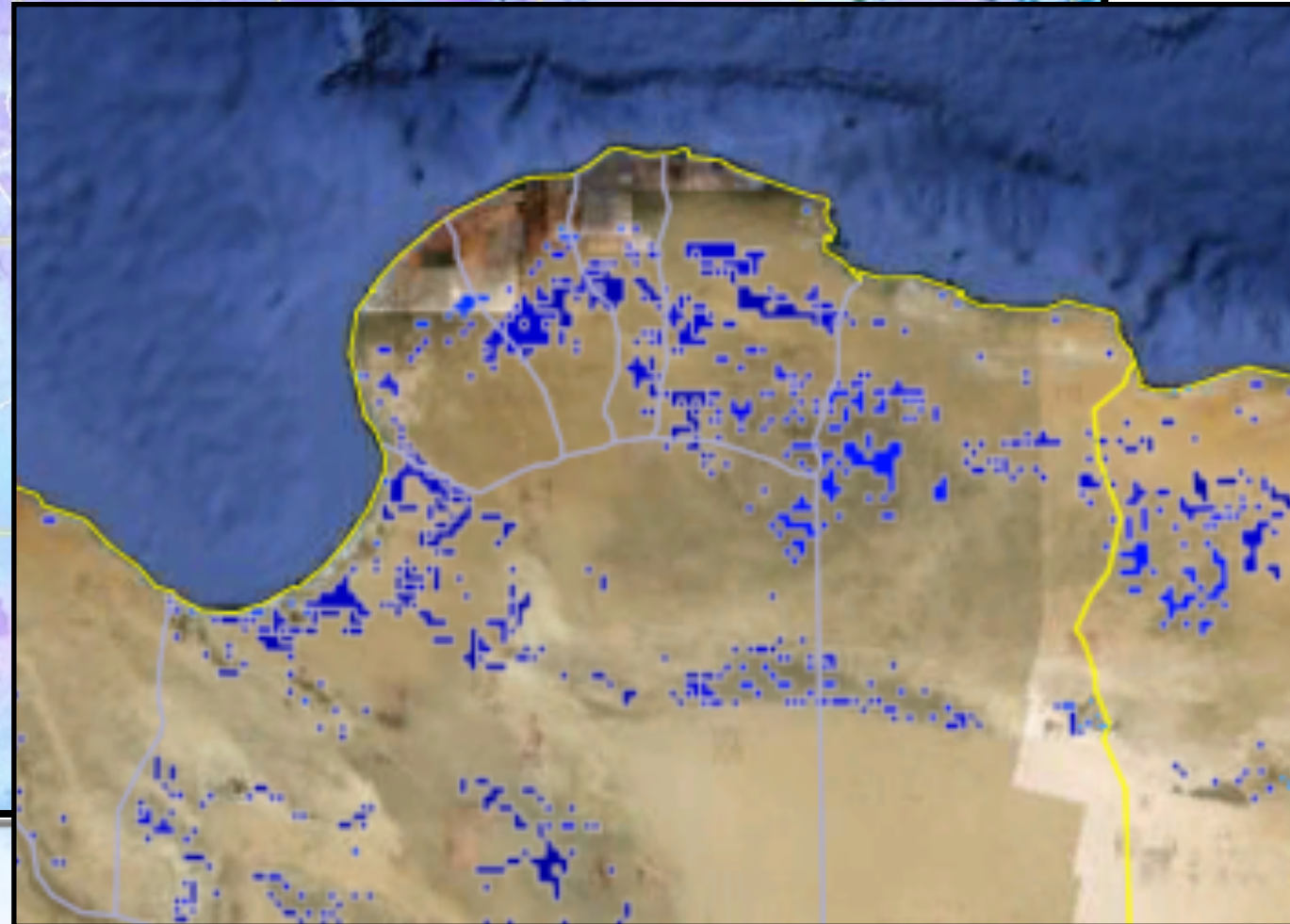
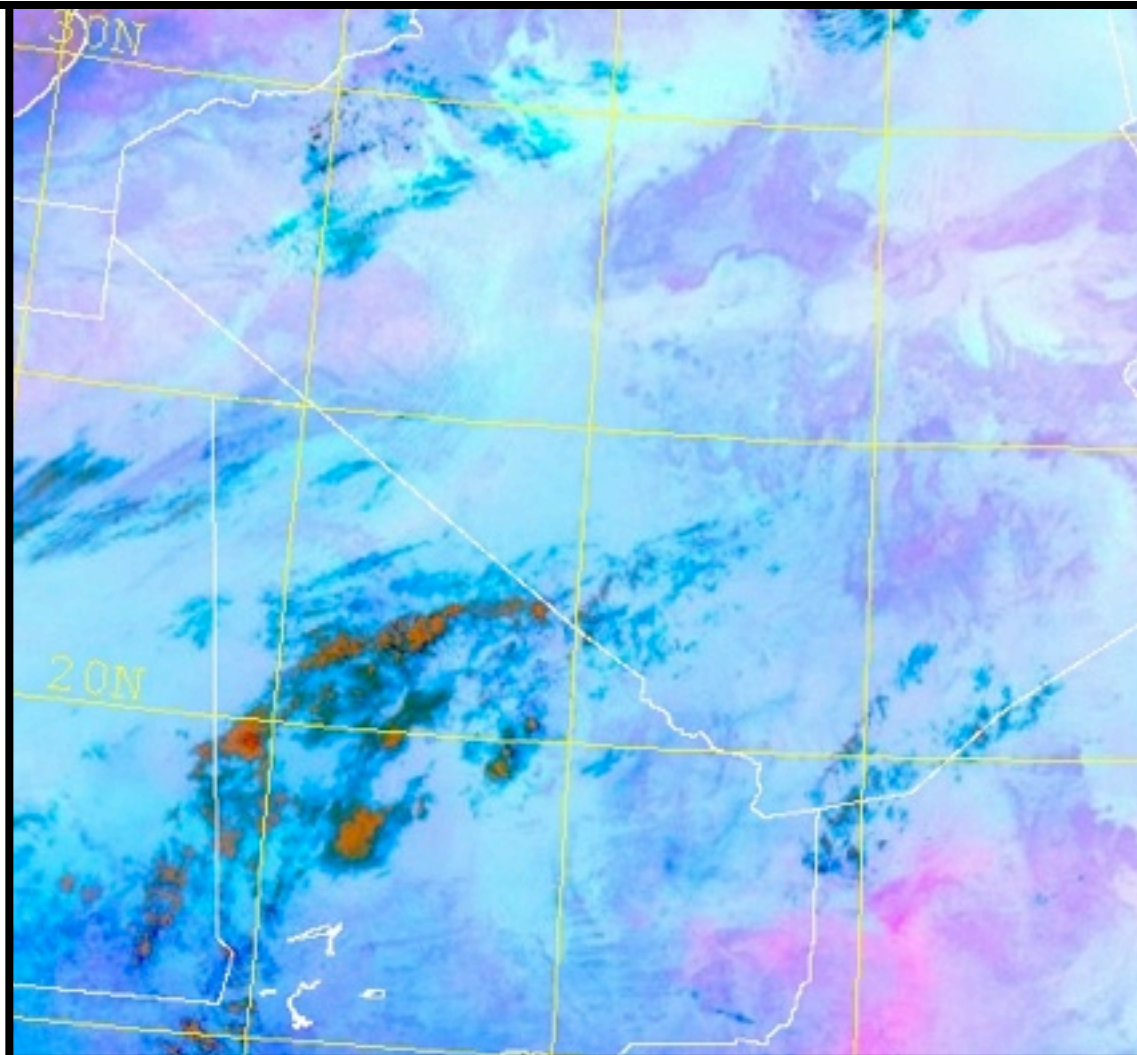
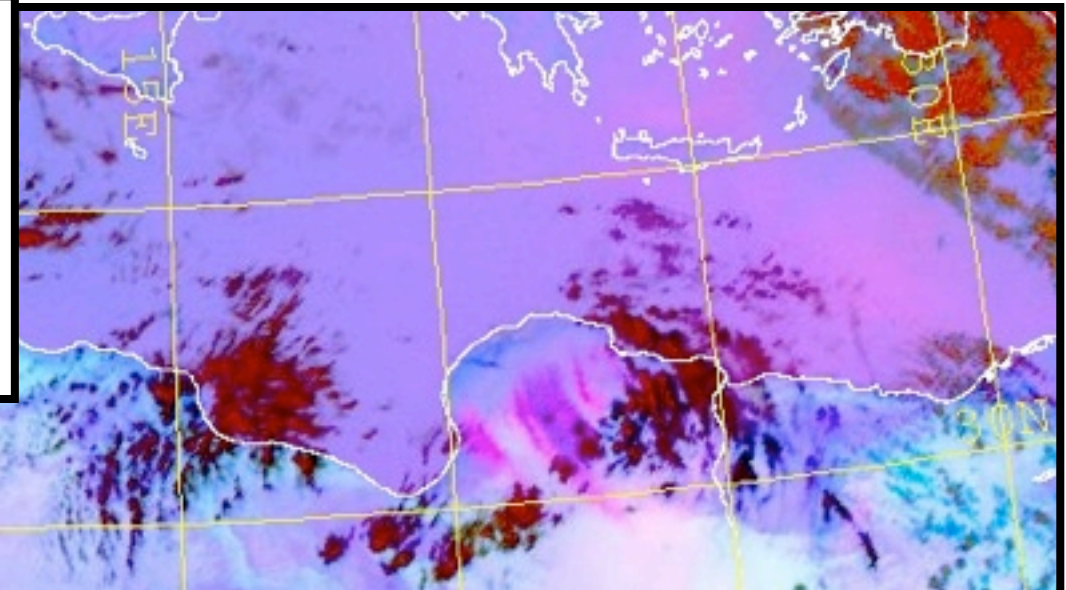
Jabal al Akhdar (الجبل الأخضر *Al Ġabal al 'Aḥḍar*, English: *Green Mountains*)

A coastal mountain range with height 1.0-1.5 km.



Plumes originate on leeward side of Al Jabal al Akhdar where drainage occurs along slopes.

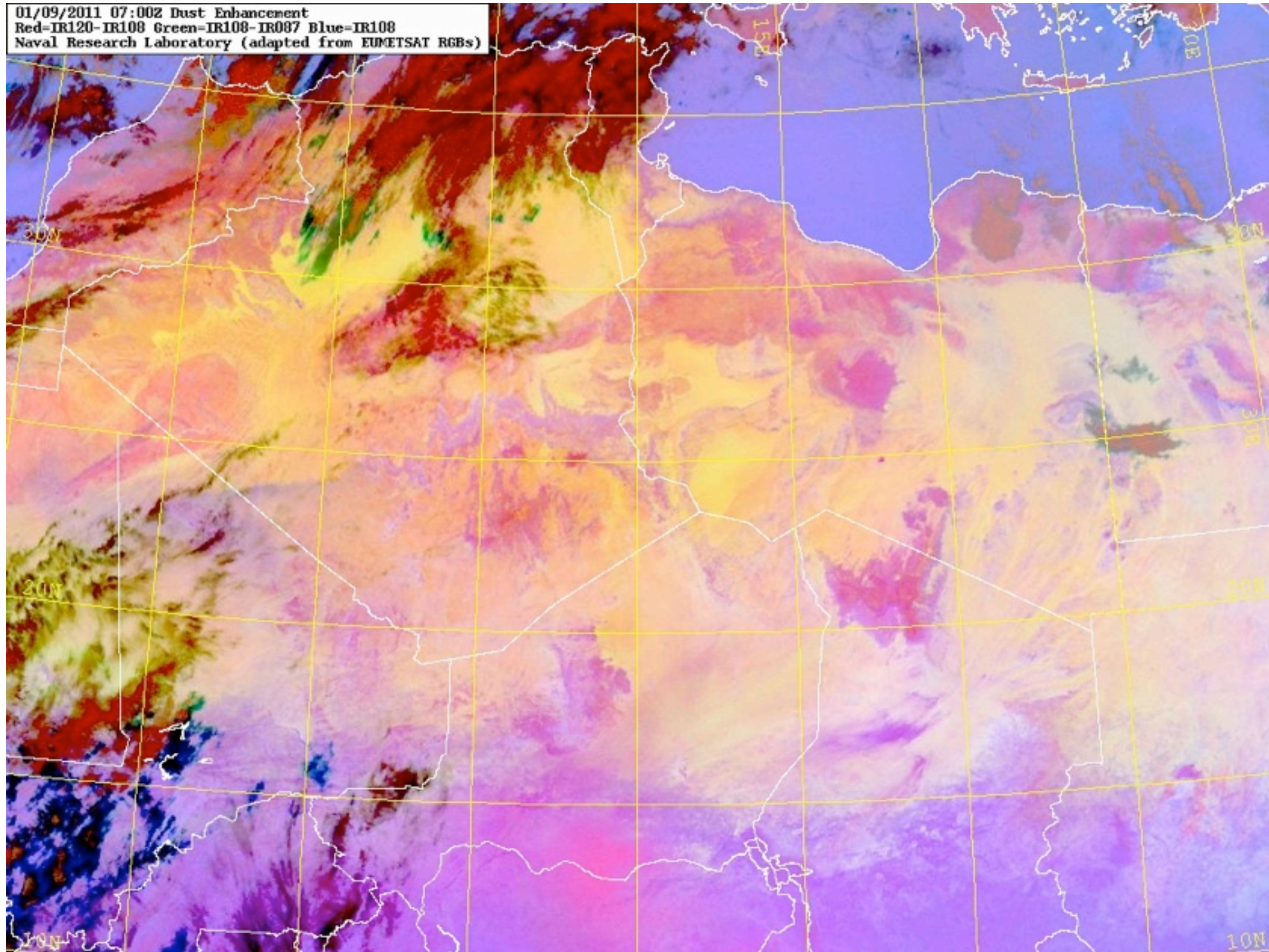
Corresponding SOM-Classes: 49, 93, 94



Chad: Bodélé Depression

Dust Event: March 16, 2010 (7Z -12Z)

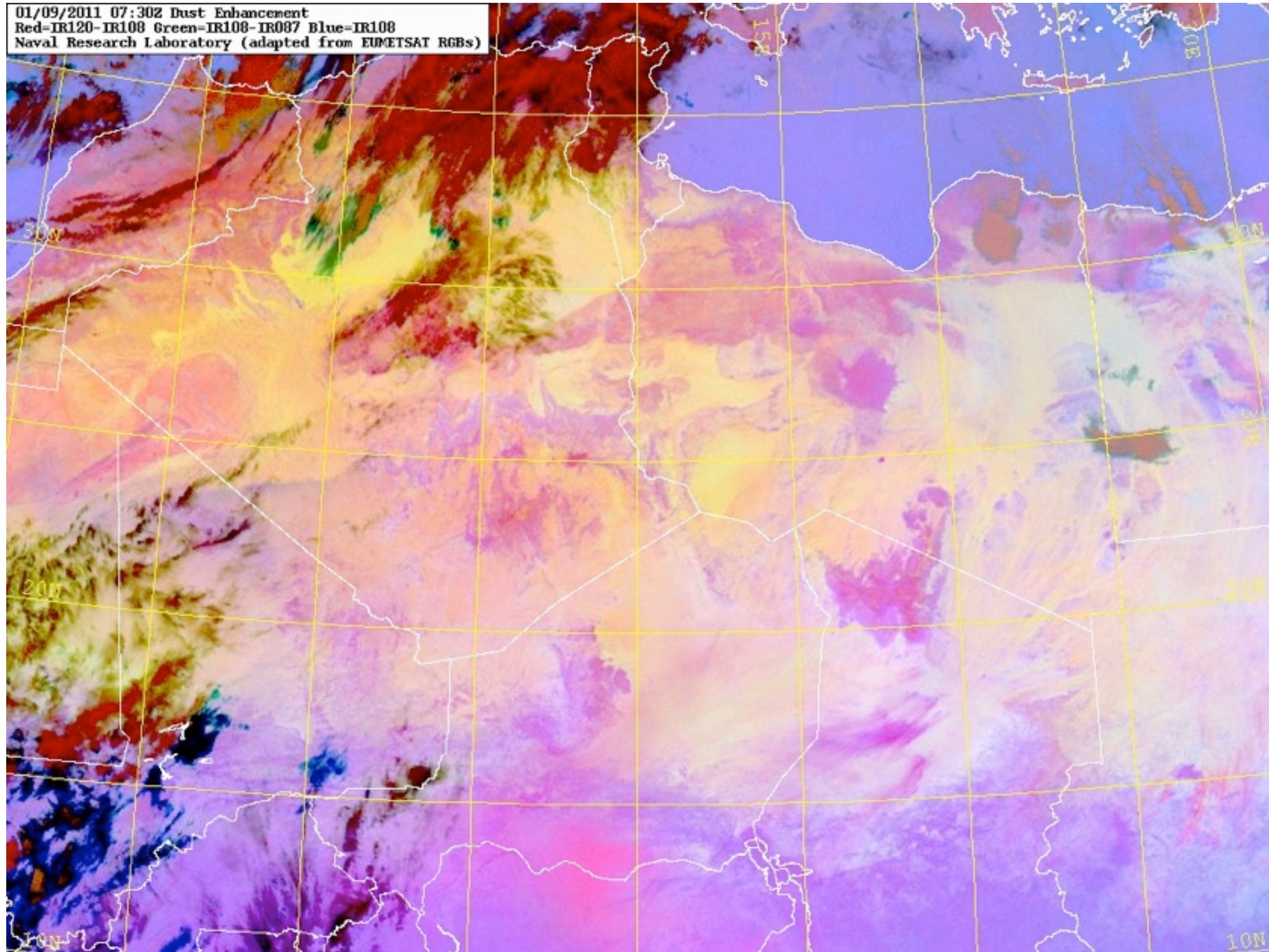
Located at the southern edge of the Sahara Desert in north central Africa, is the lowest point in Chad. Dust storms from the Bodélé Depression occur on average about 100 days per year. The Bodélé depression is a single spot in the Sahara that provides most of the mineral dust to the Amazon forest.



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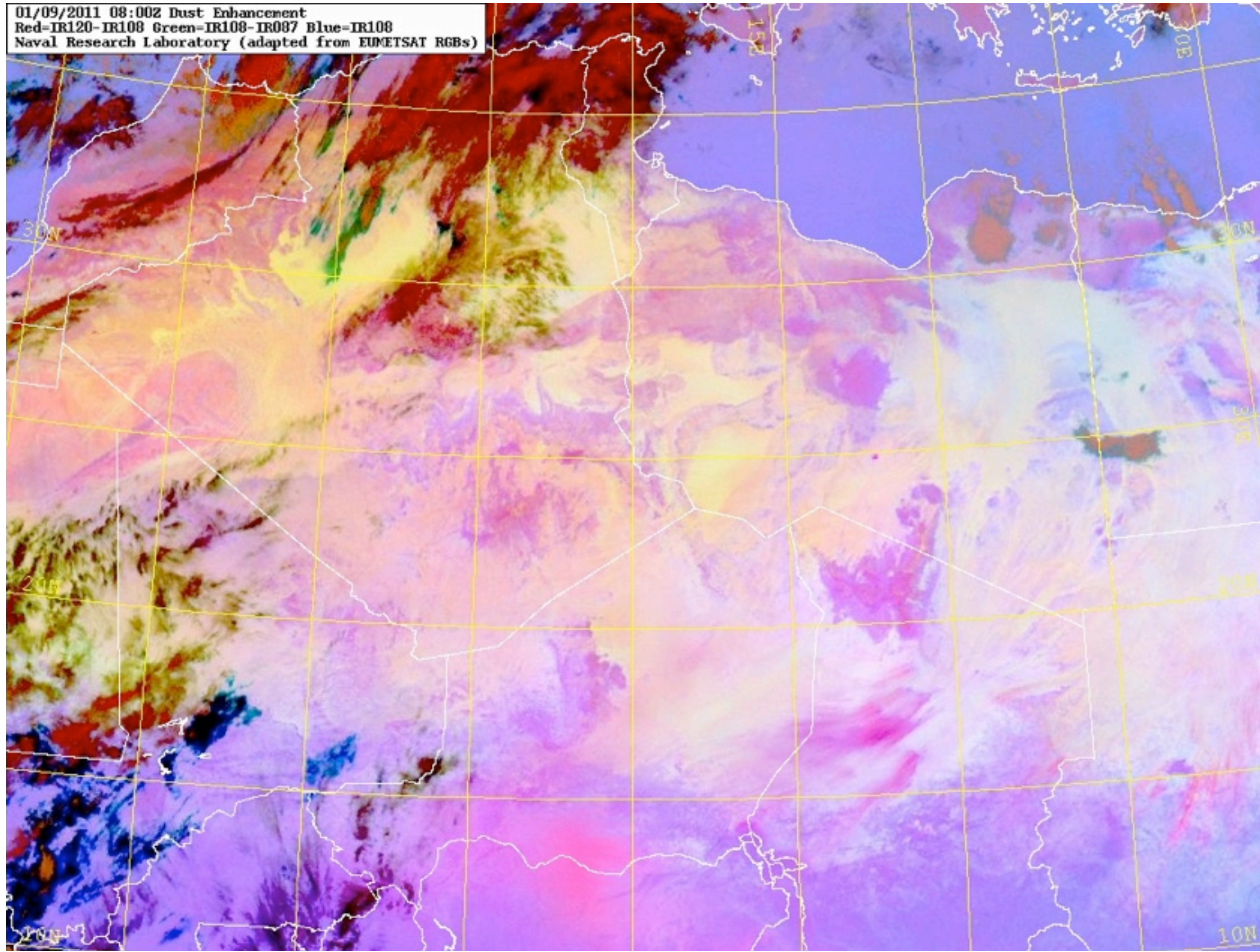
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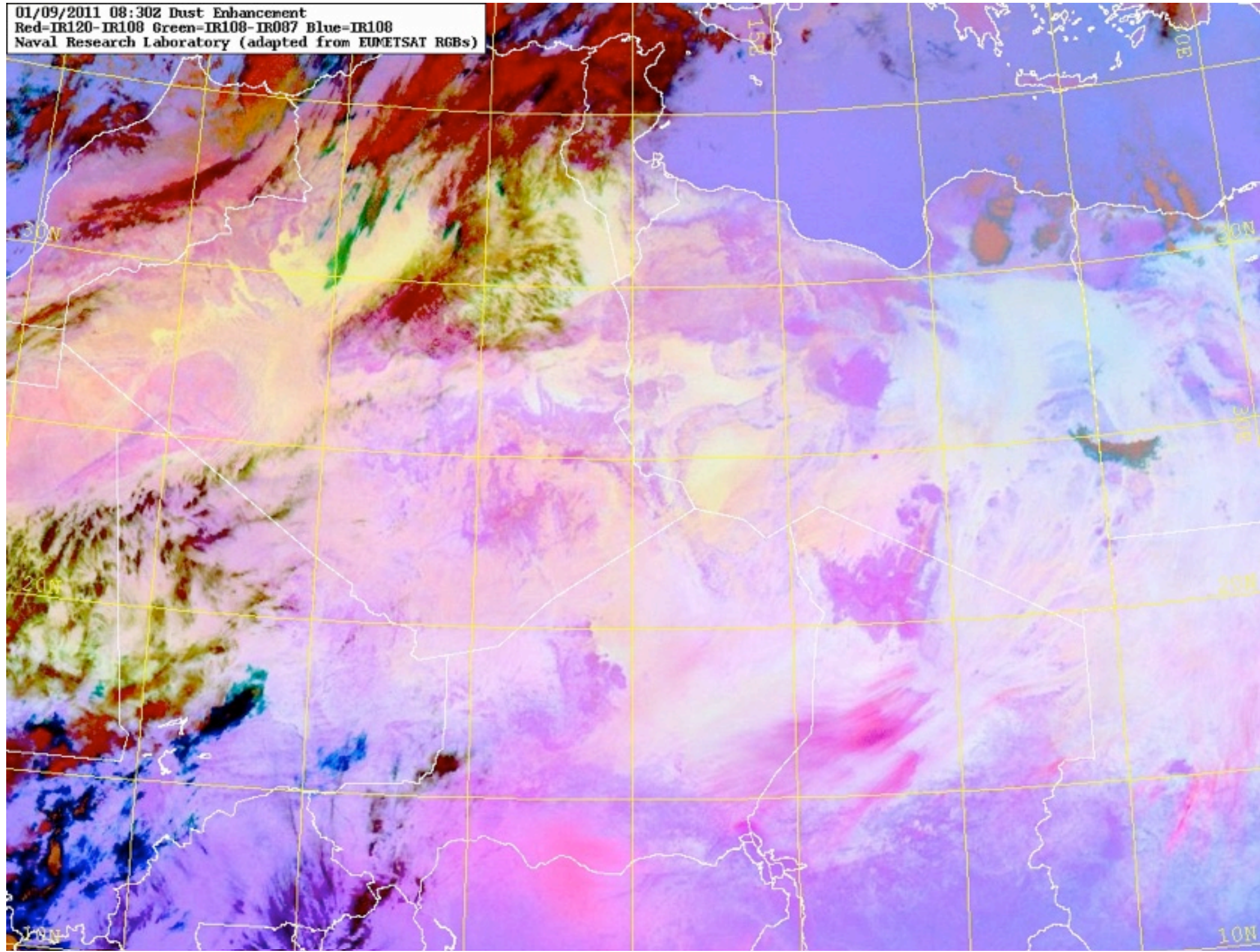
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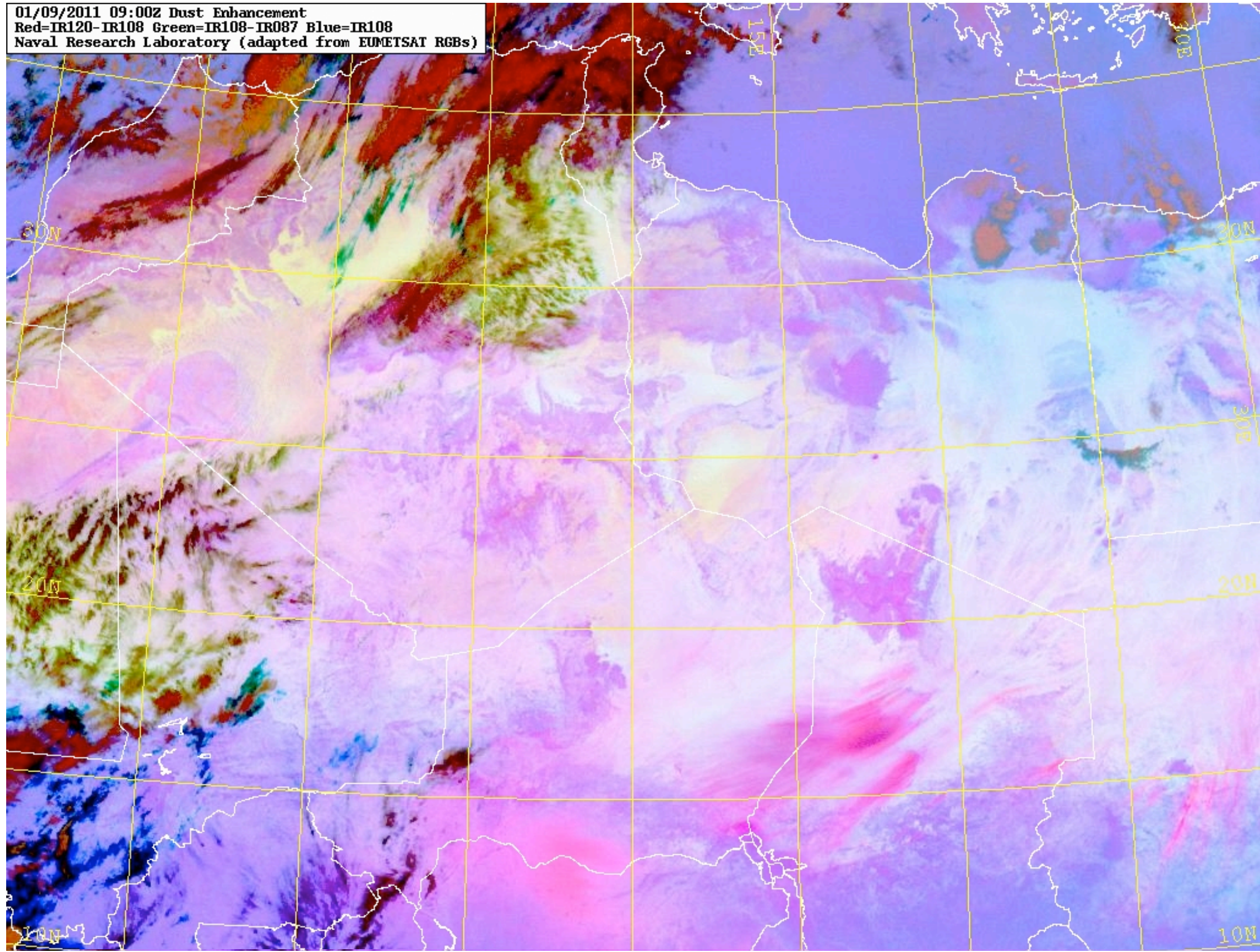
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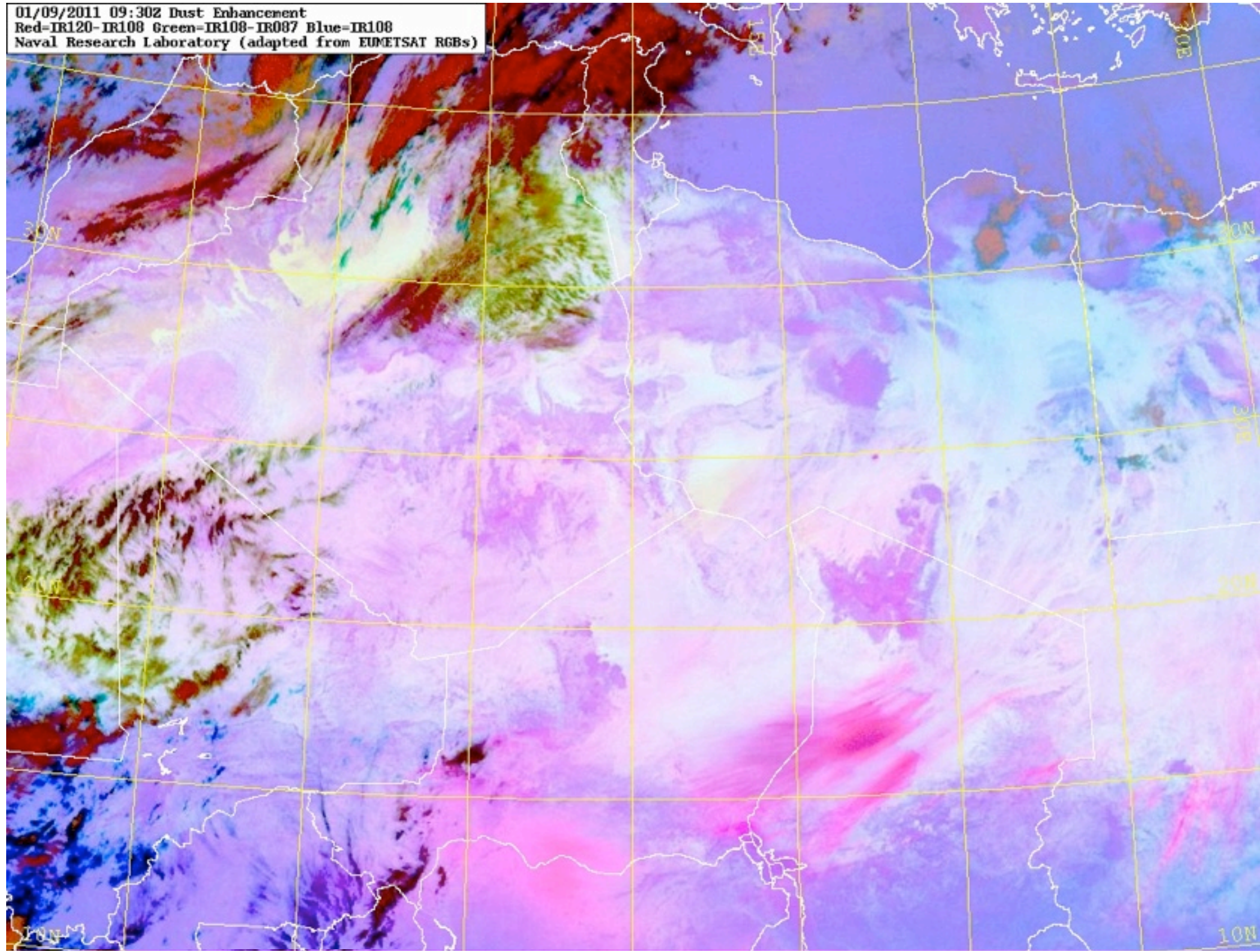
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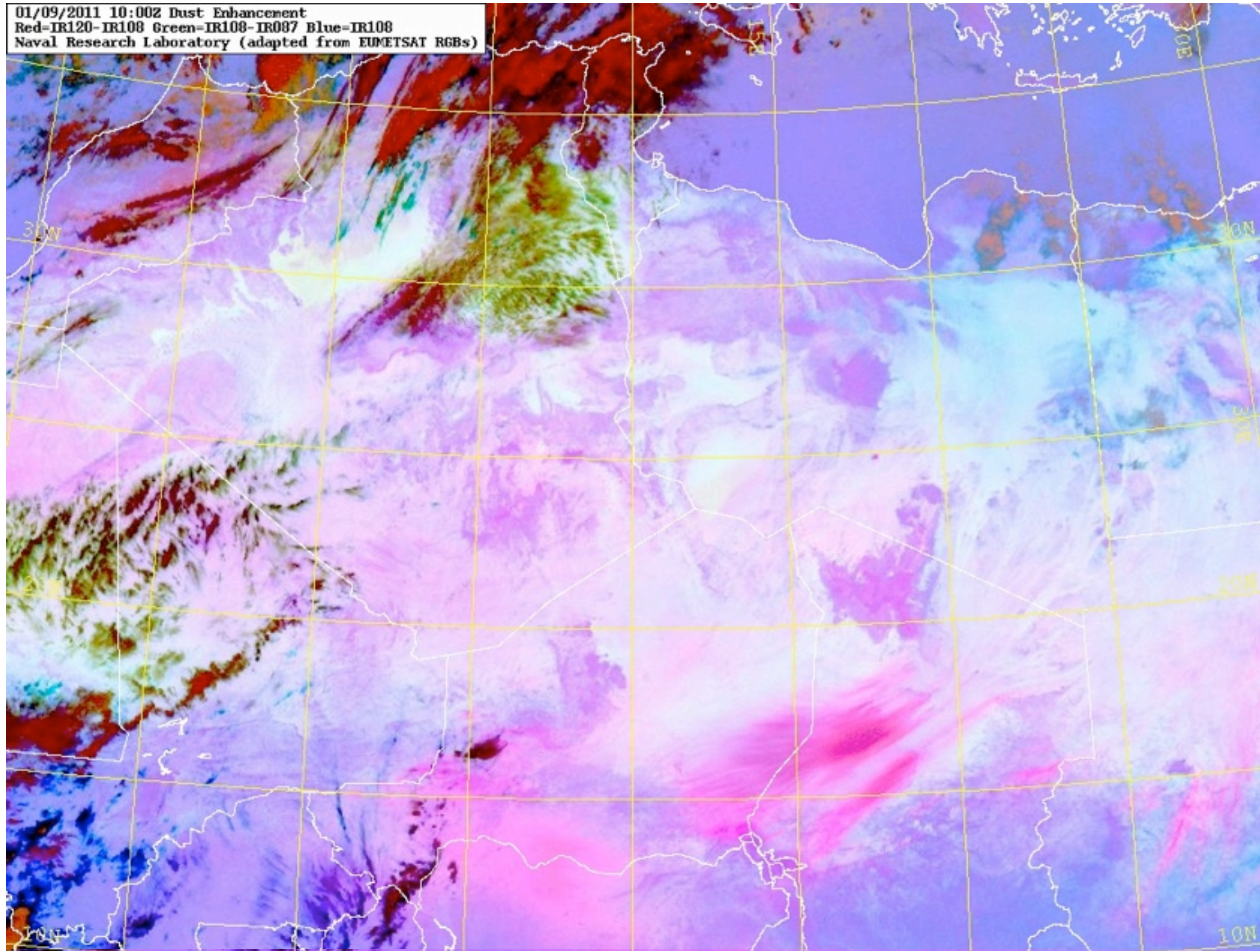
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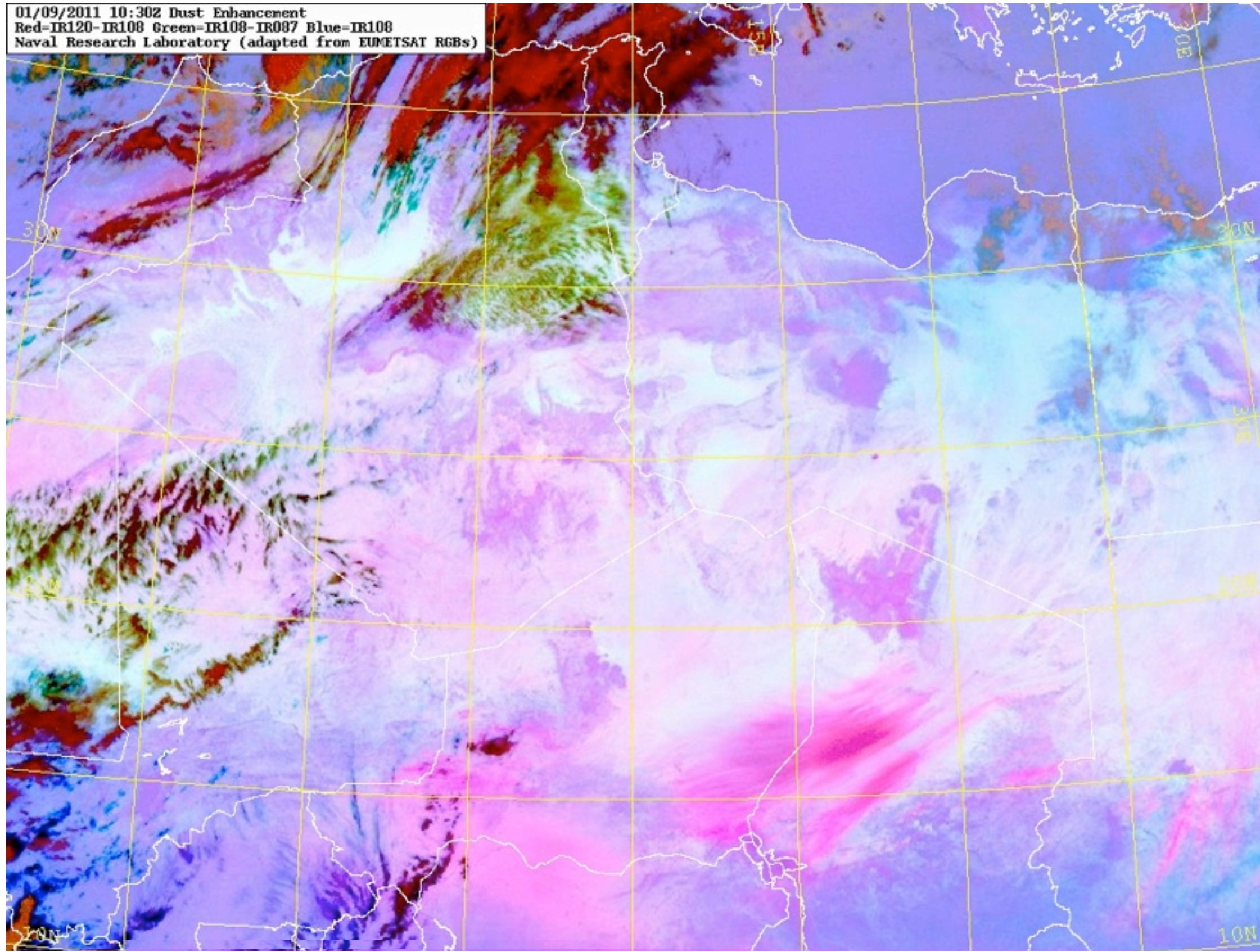
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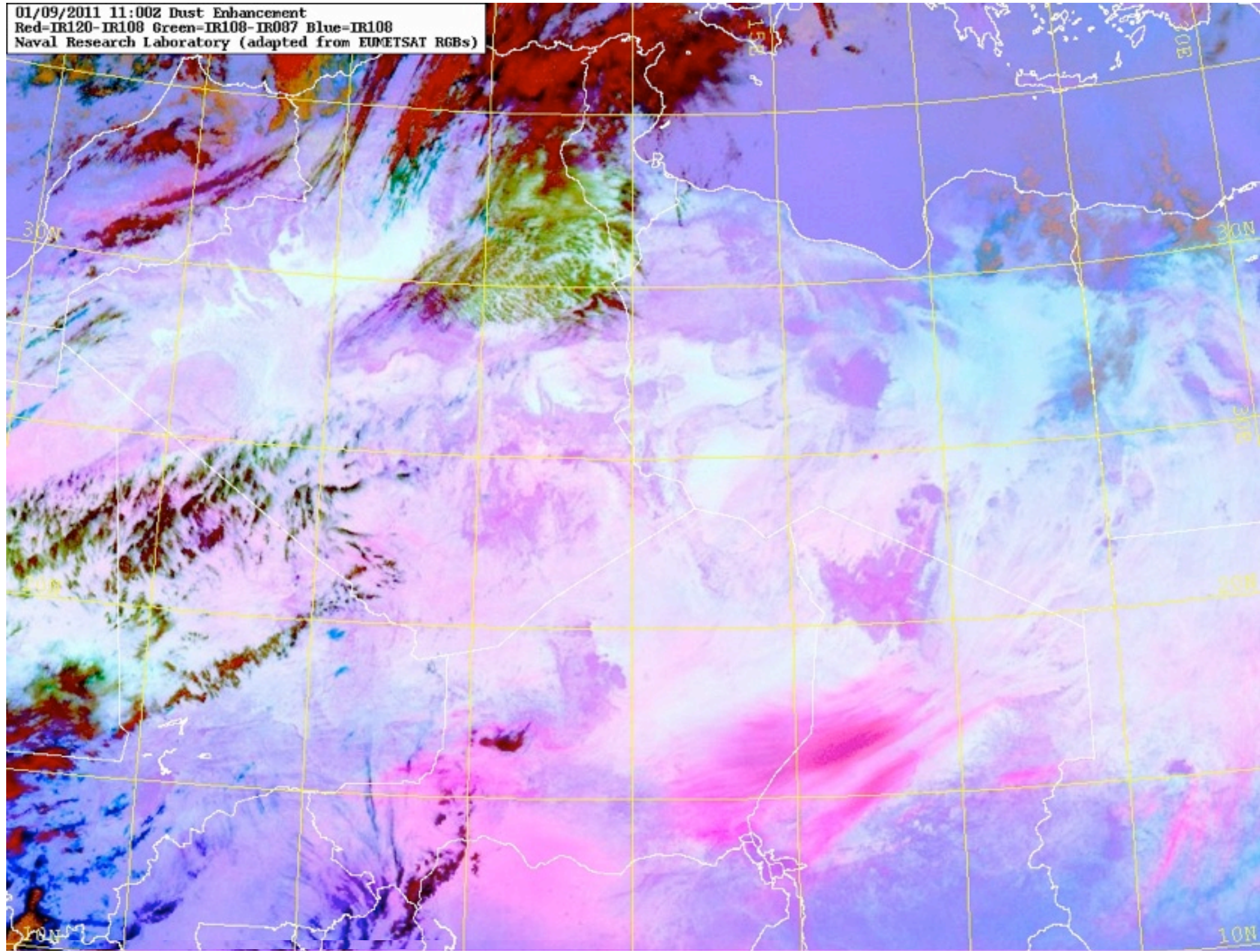
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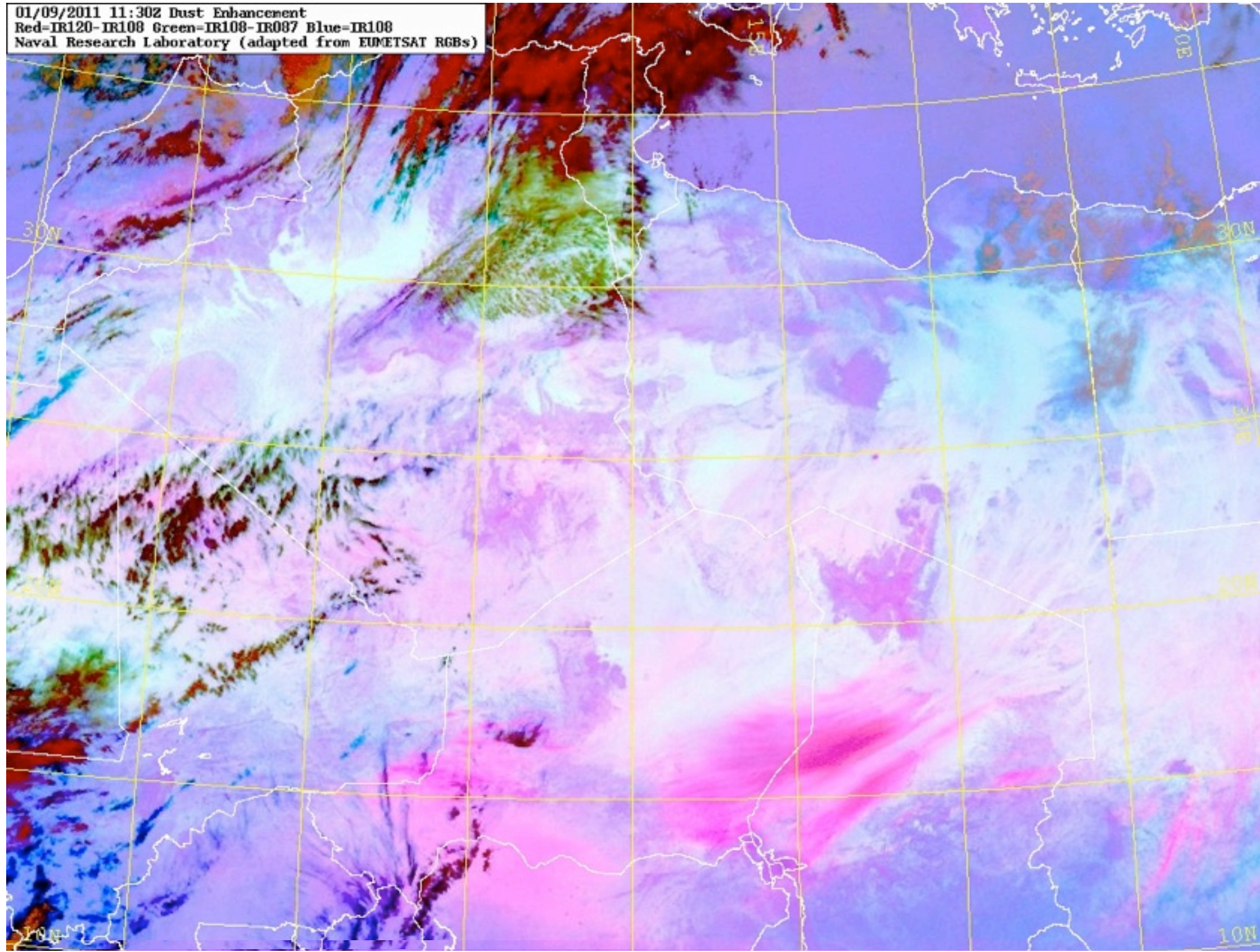
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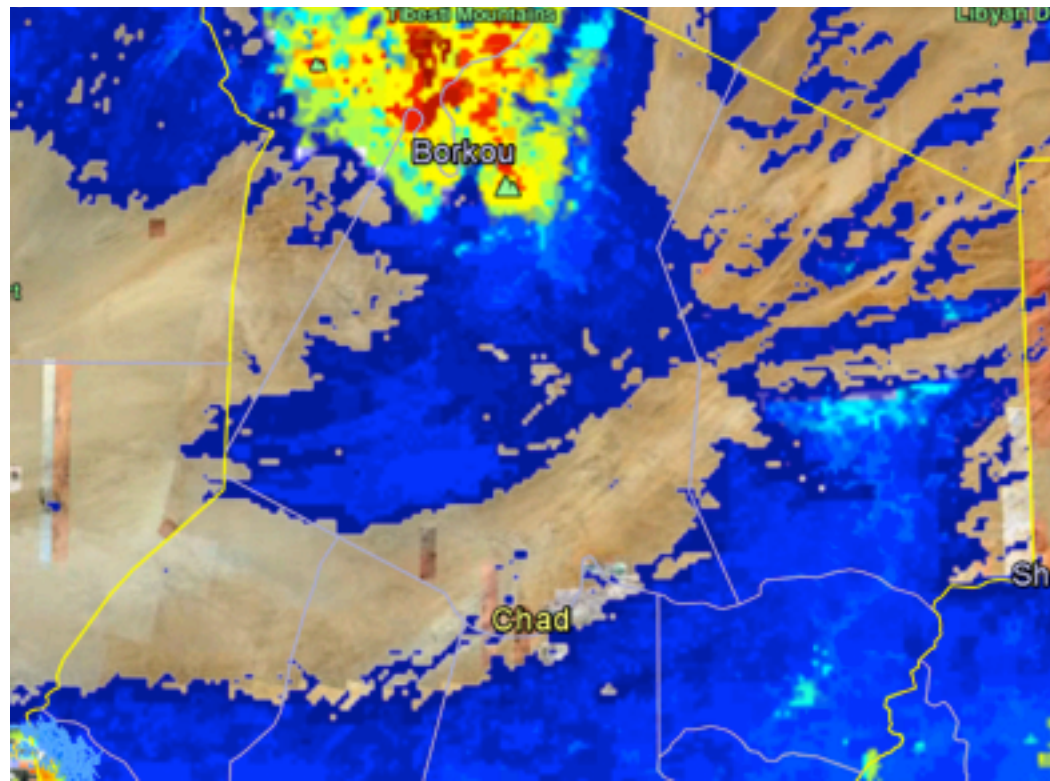
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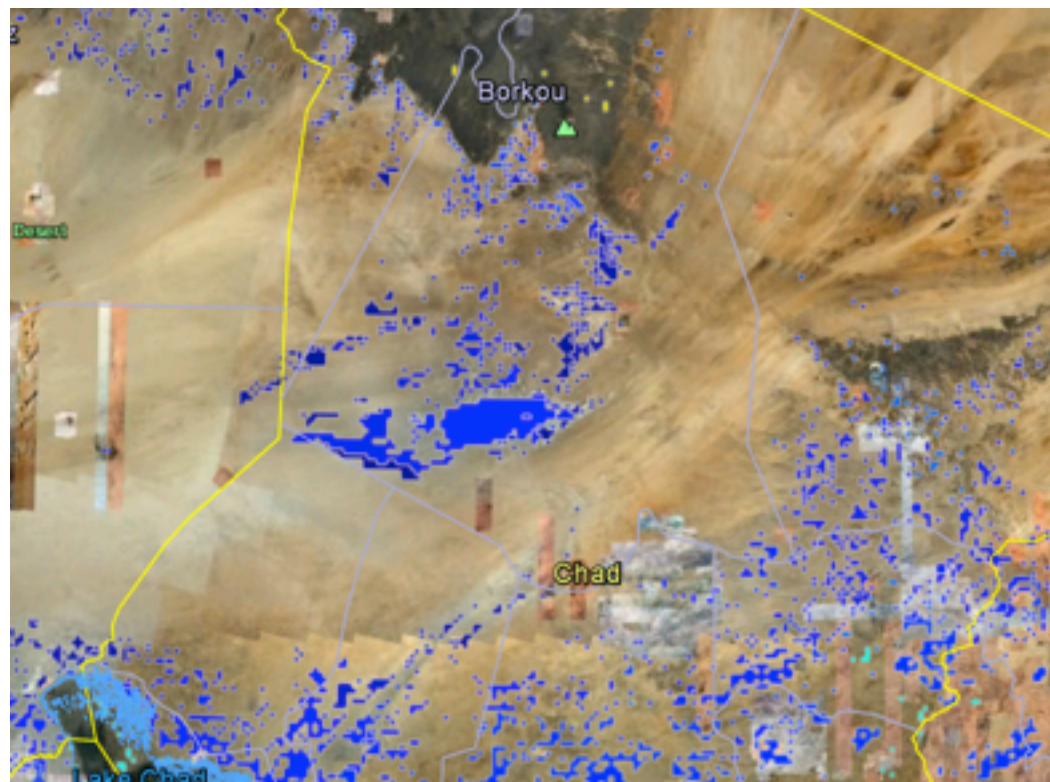


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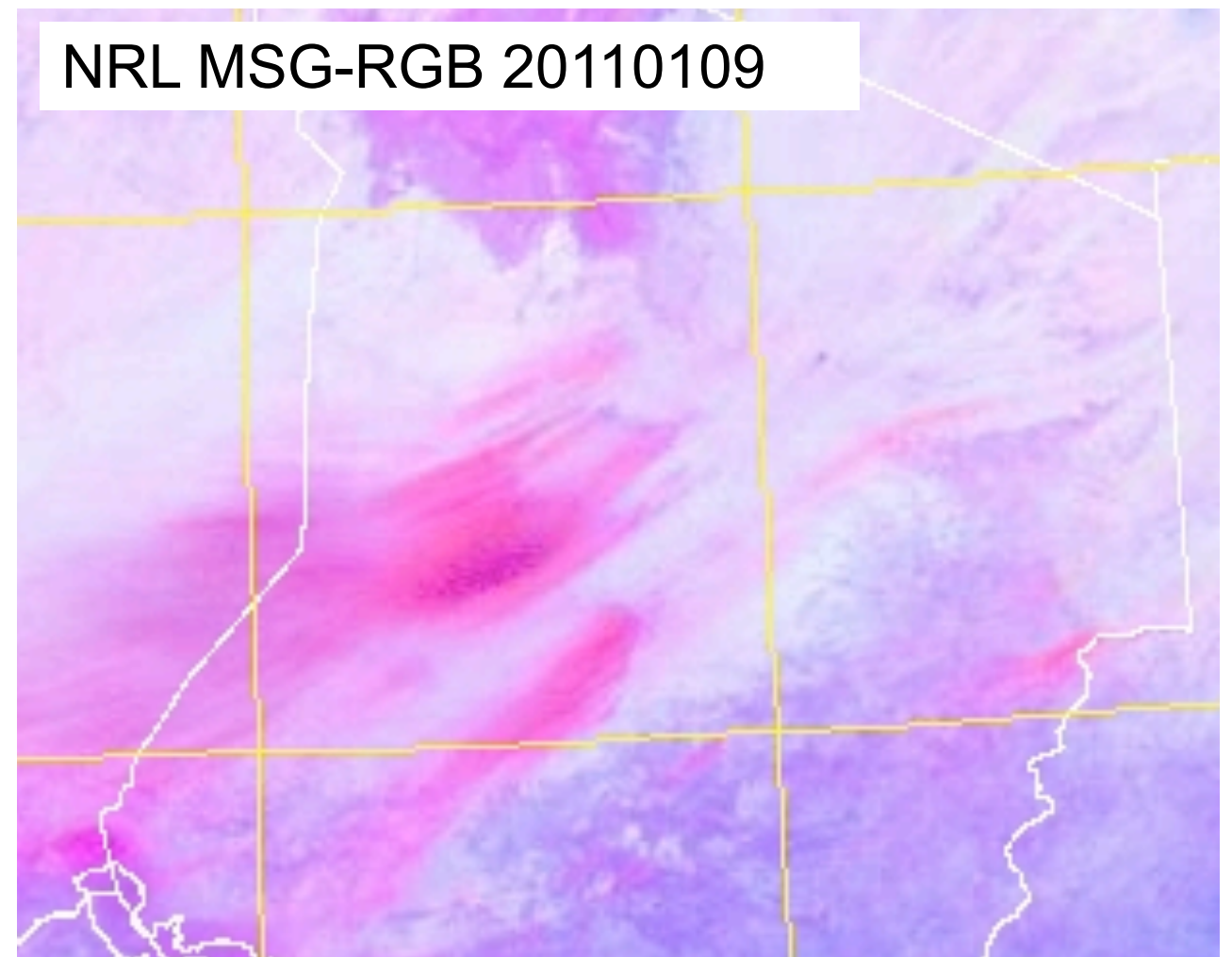


1000 SOM Classes

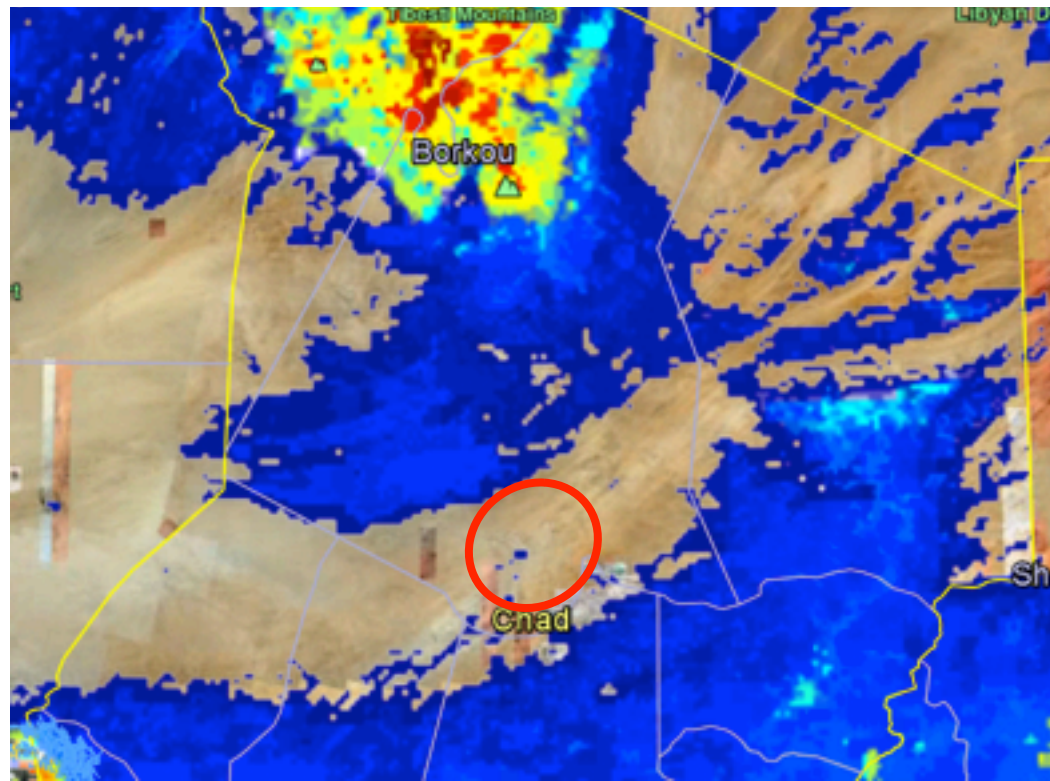
Source area is not designated in first pass of MODIS reflectance and land surface classification.



Selected SOM Classes

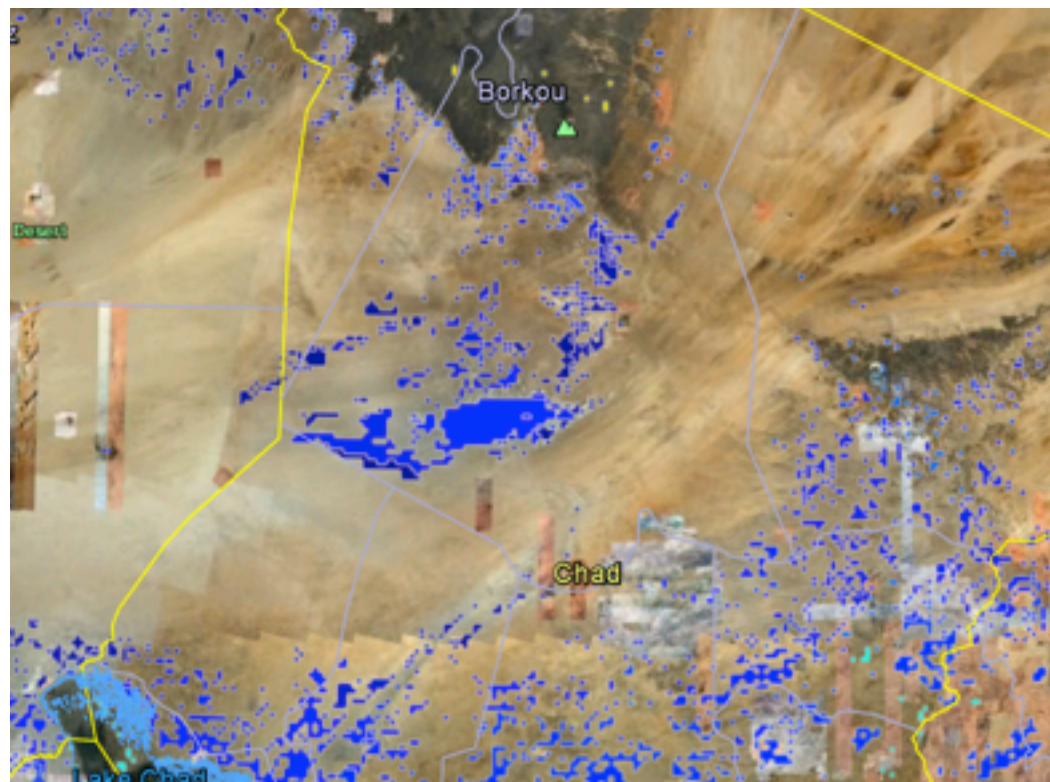


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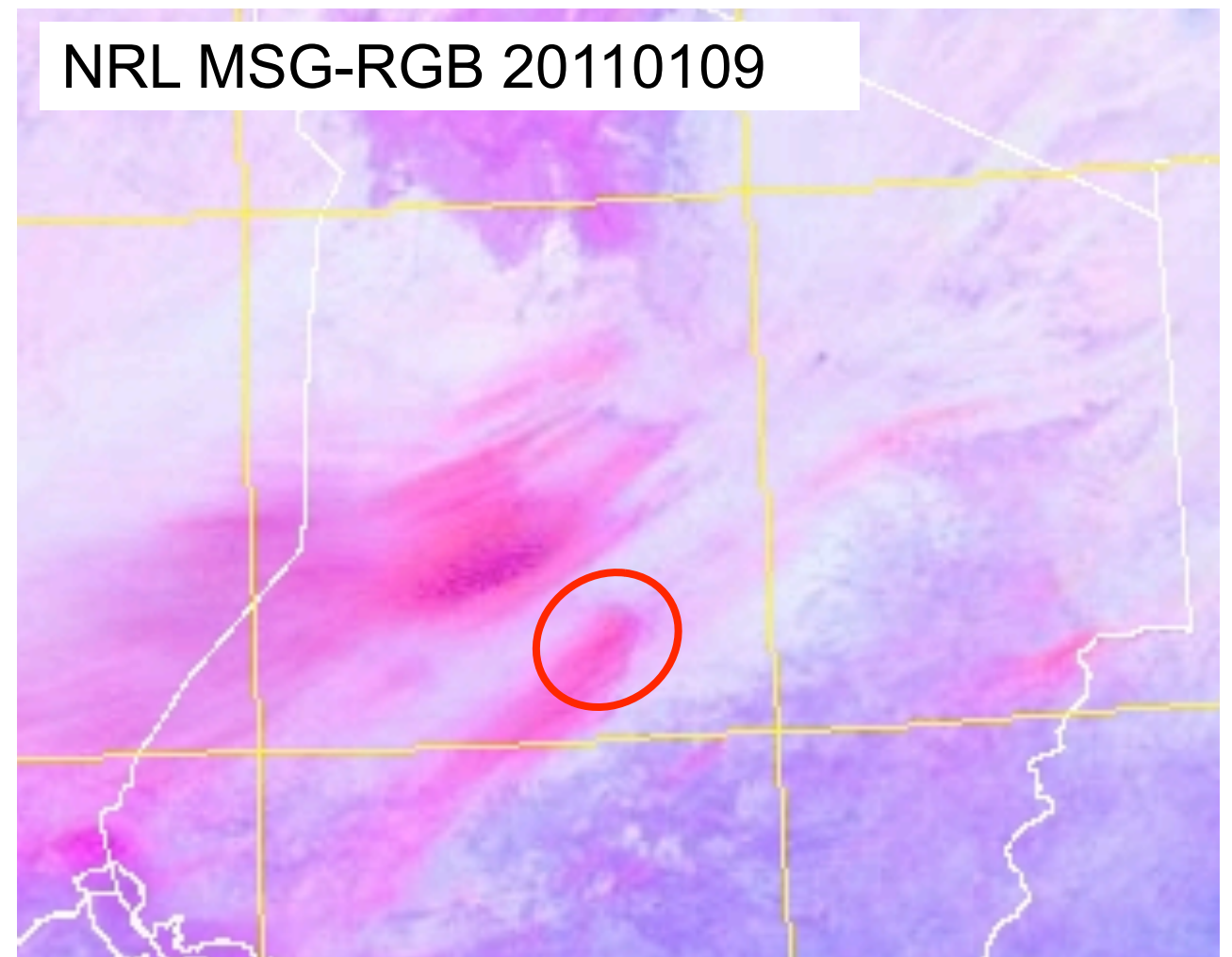


1000 SOM Classes

Source area is not designated in first pass of MODIS reflectance and land surface classification.

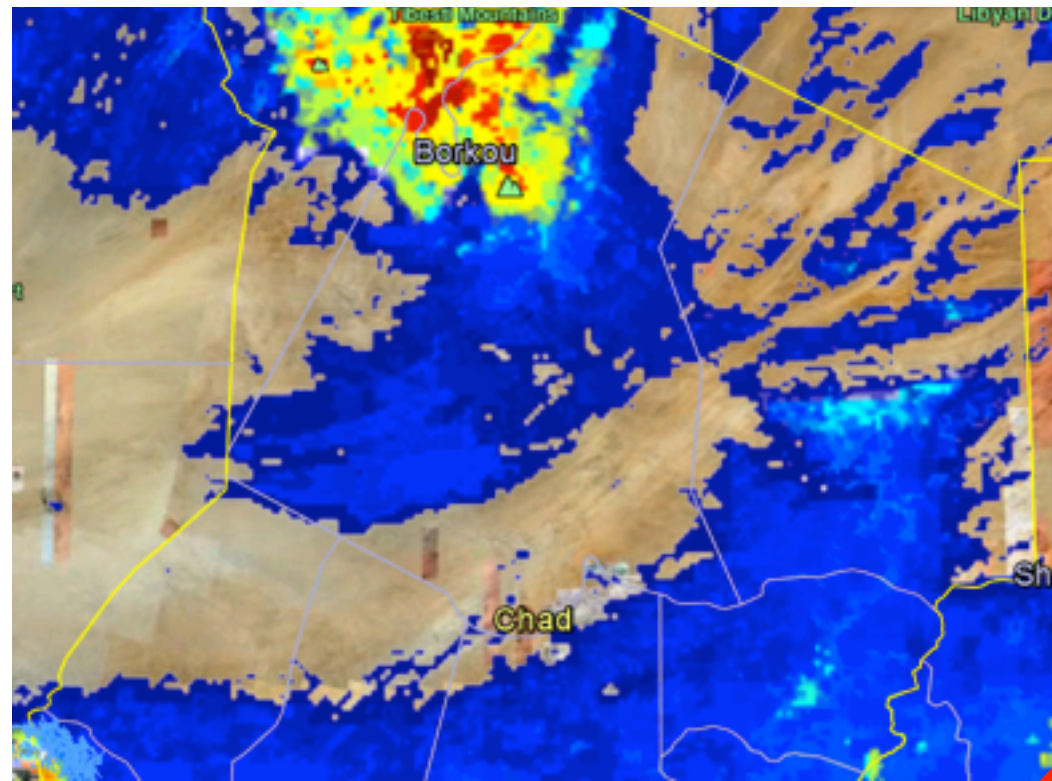


Selected SOM Classes



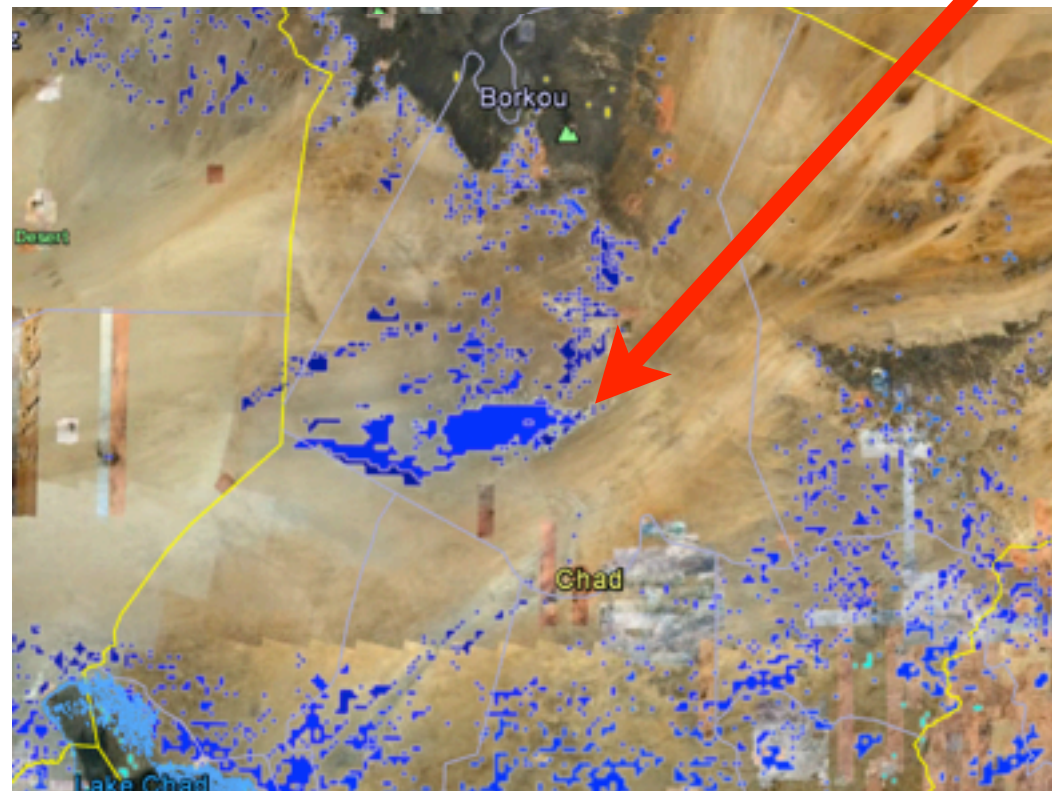
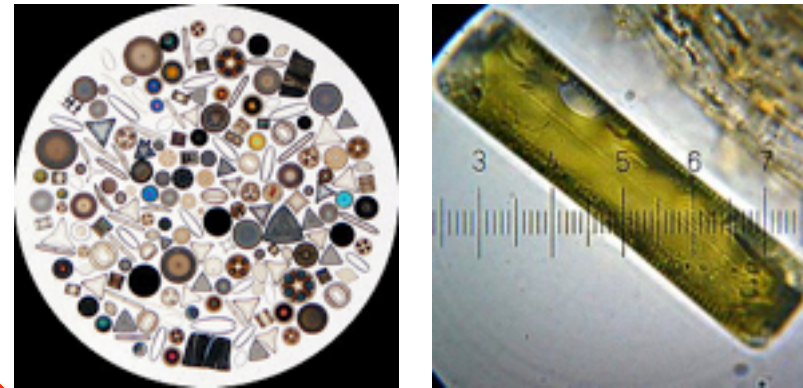
NRL MSG-RGB 20110109

Chad: Bodélé Depression

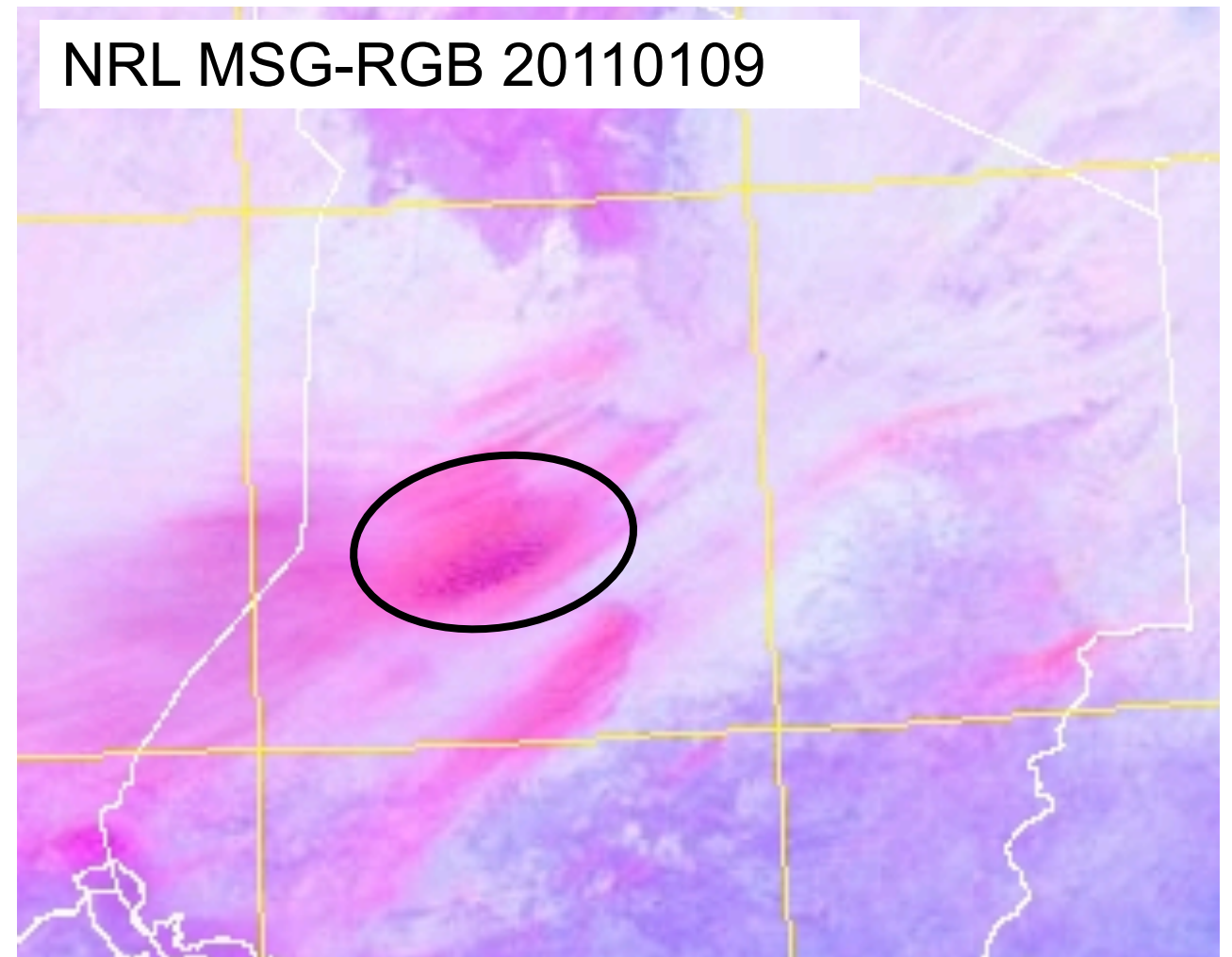


1000 SOM Classes

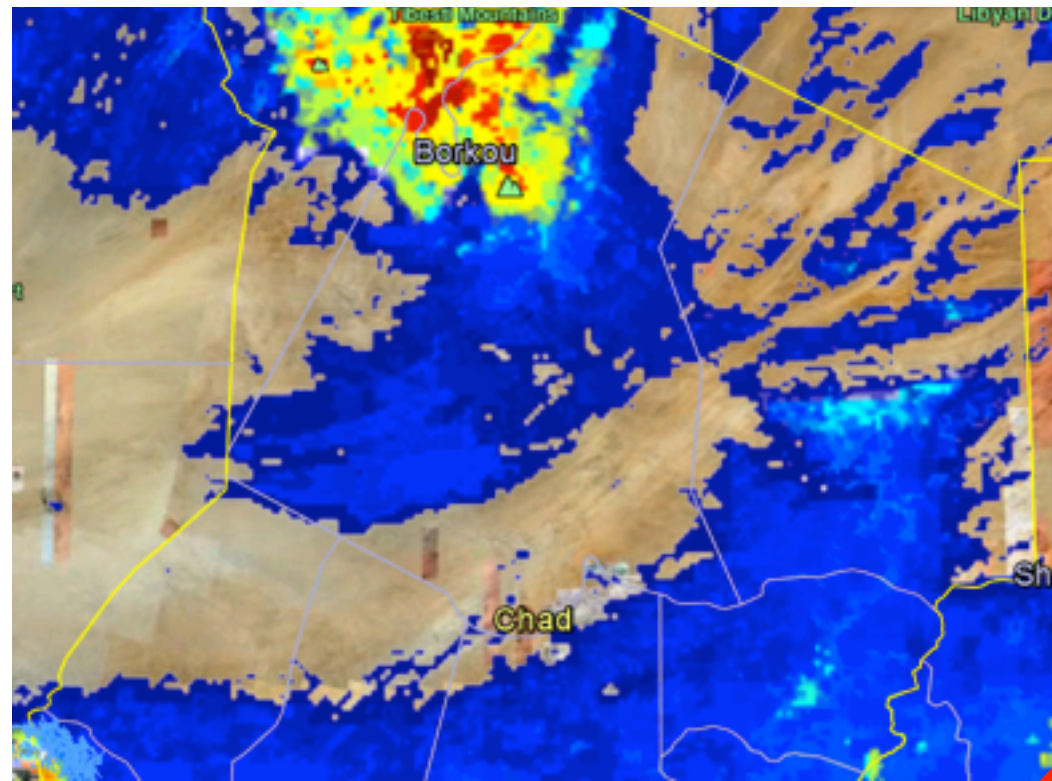
Class 137 maps diatom sediment in depression.



Selected Classes with Class 137

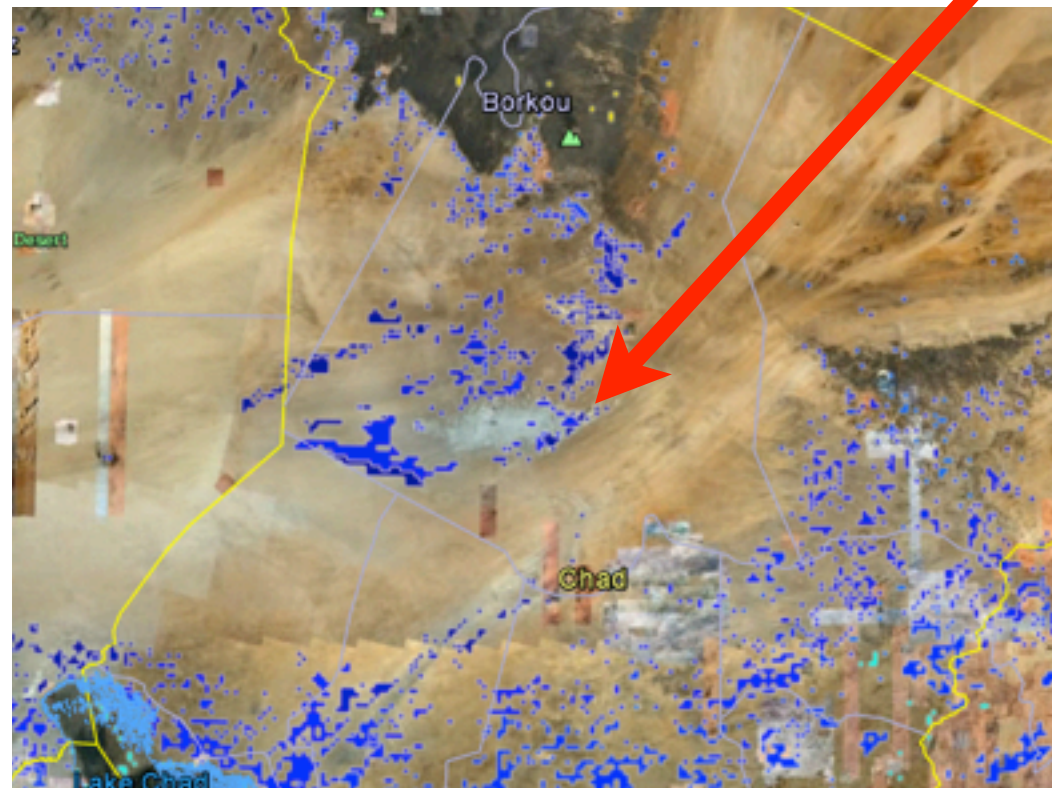
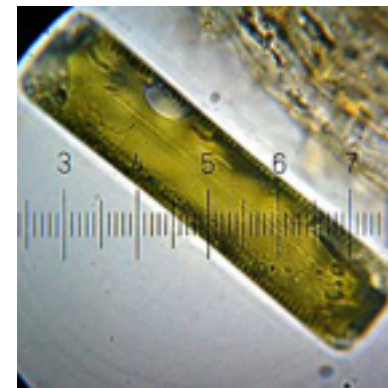
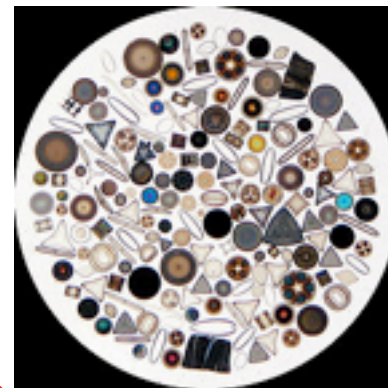


Chad: Bodélé Depression

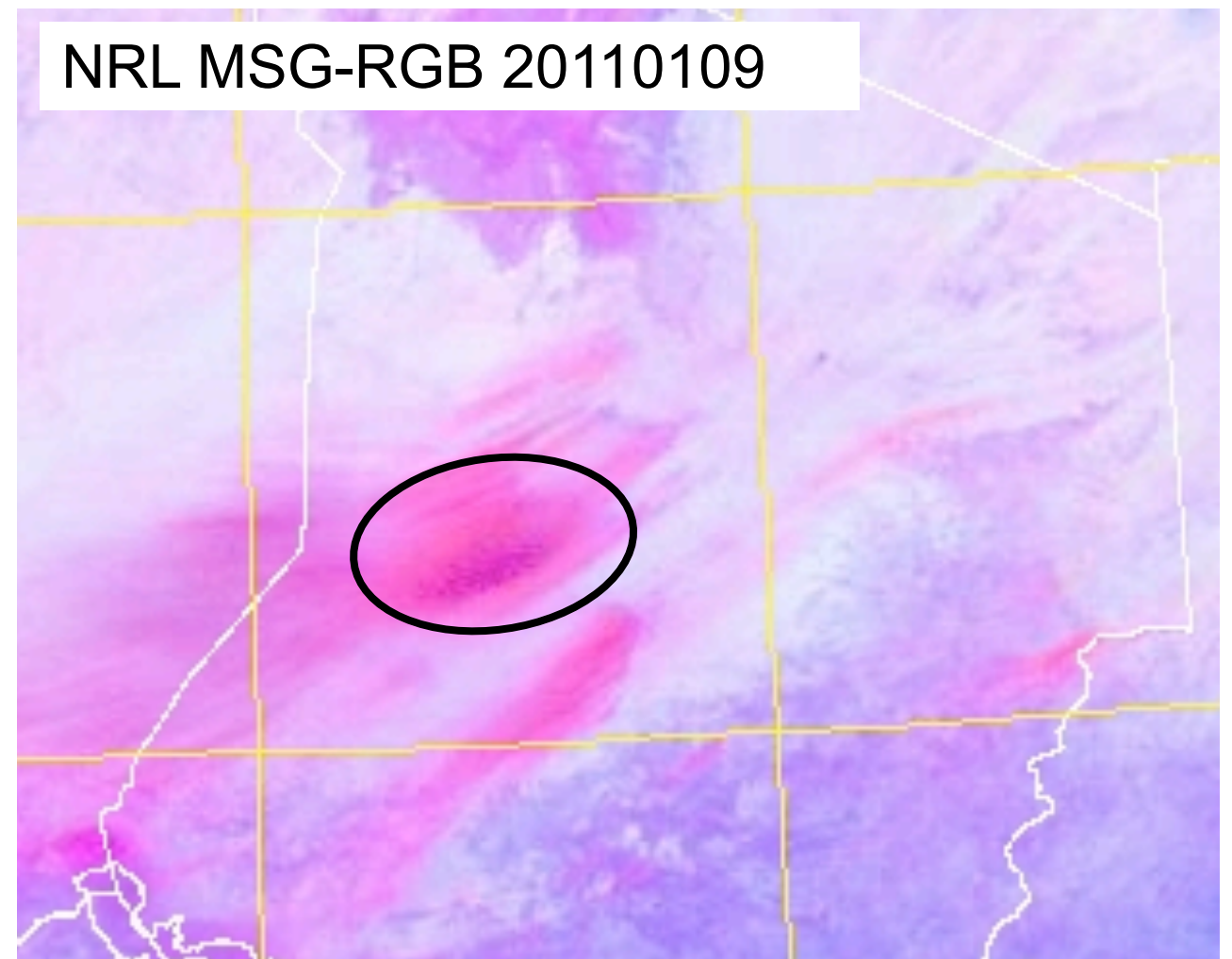


1000 SOM Classes

Class 137 maps diatom sediment in depression.

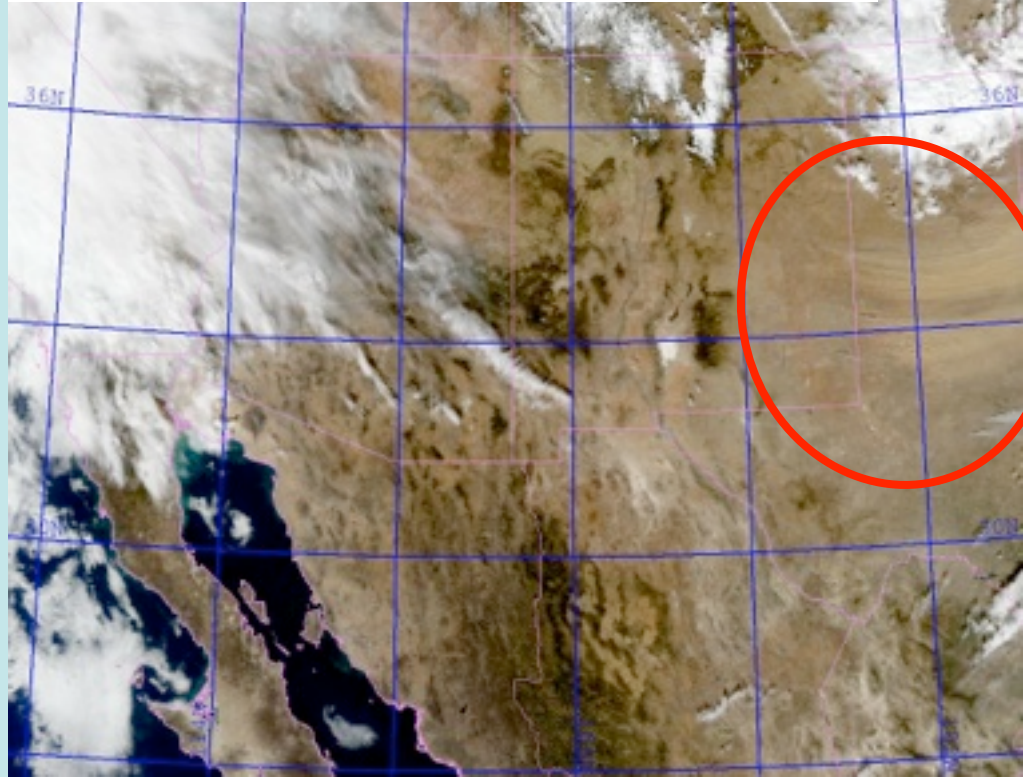


Selected Classes **Without Class 137**

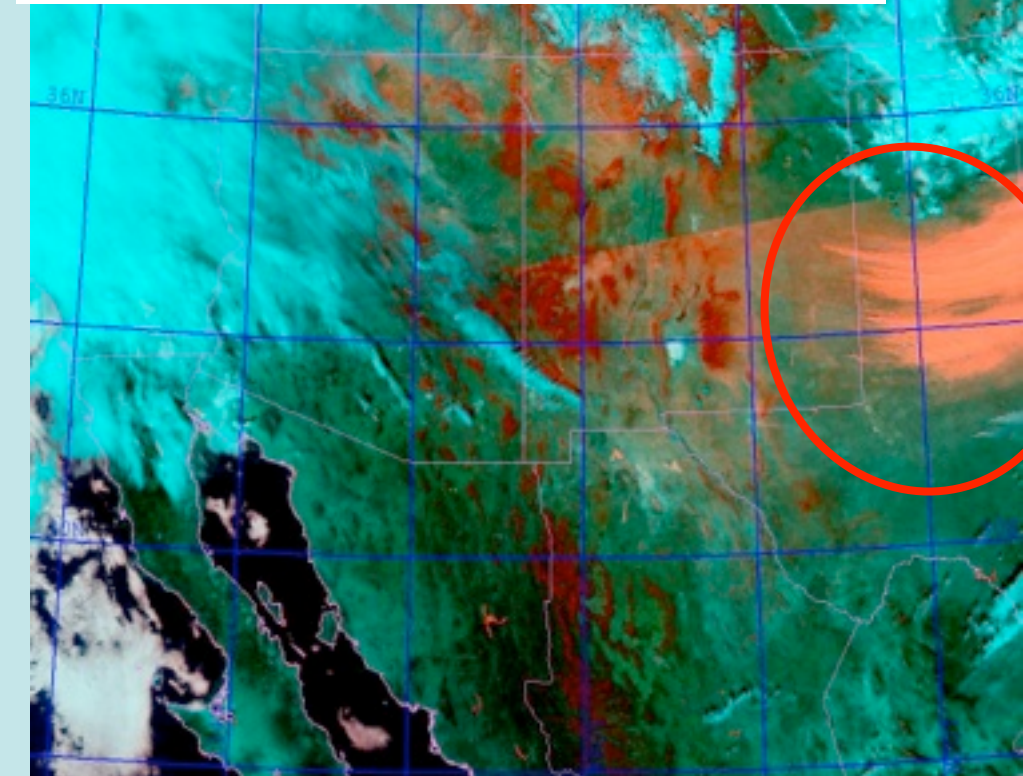


Sources along New Mexico/Texas border

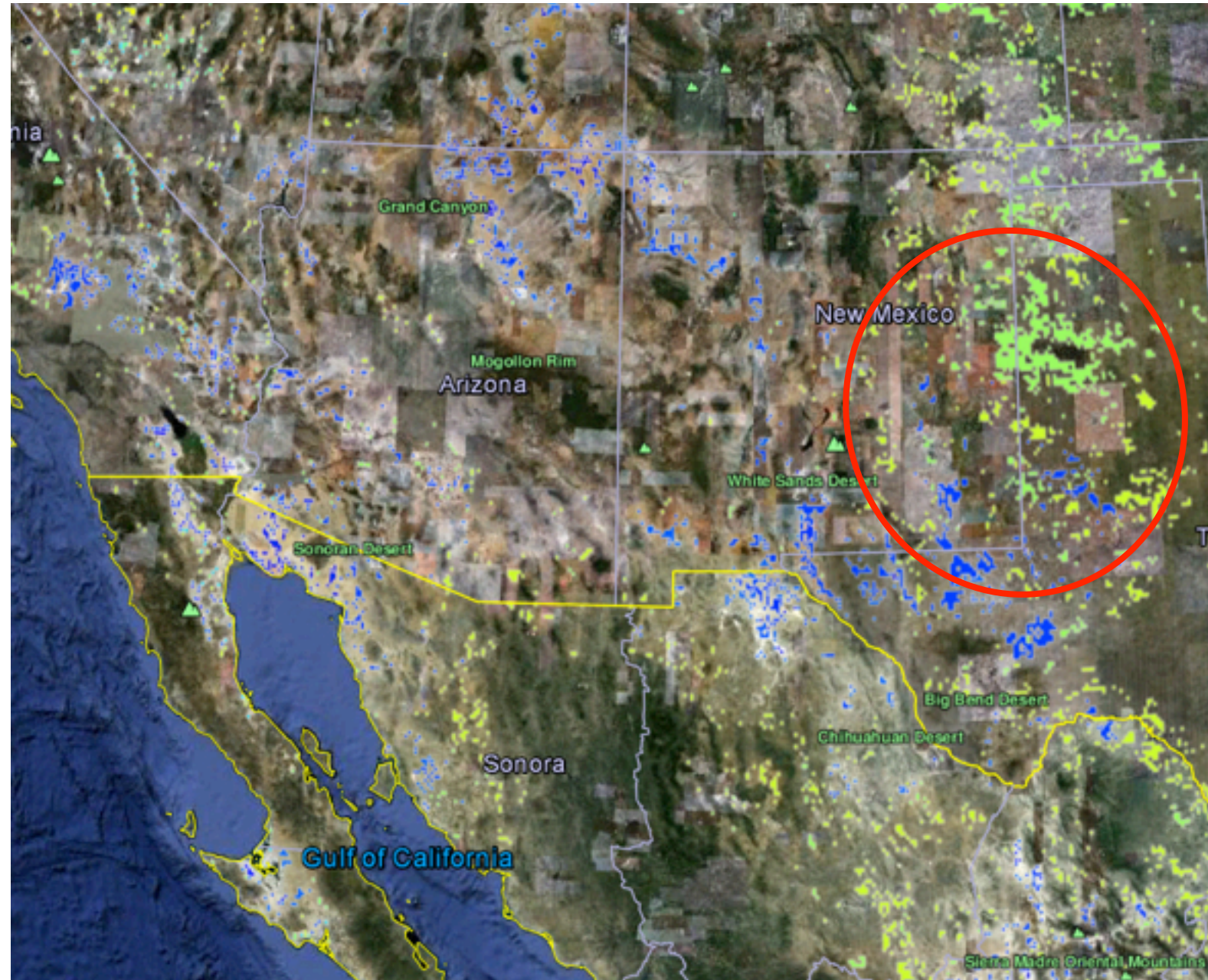
Jan 1, 2006 True Color



Jan 1, 2006 NRL DEP

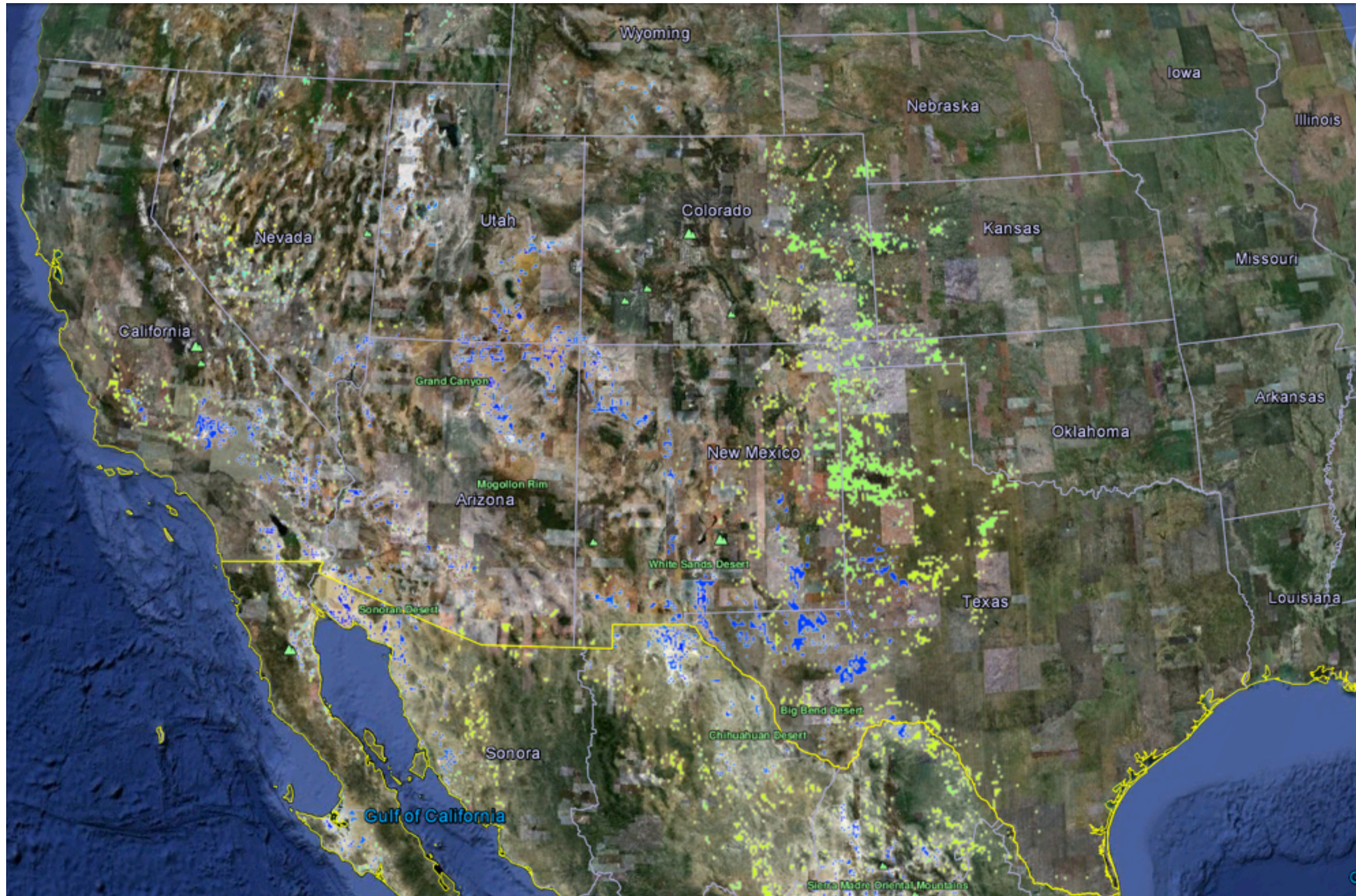


Agricultural on high planes
Blue desert areas

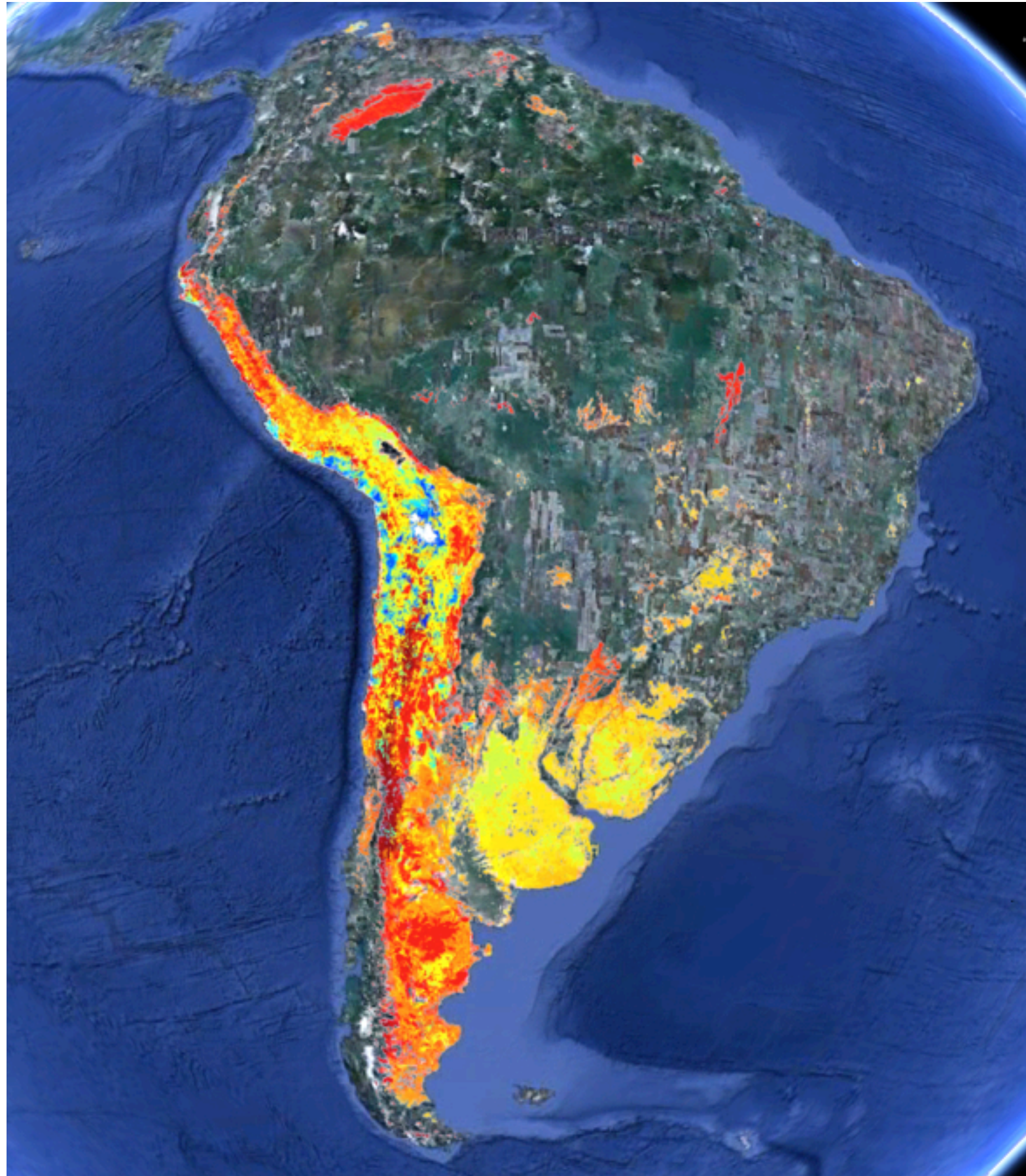


The North American sources have a different spectral signature than those we saw in SW Asia

Selected Classes for North America (n=64)



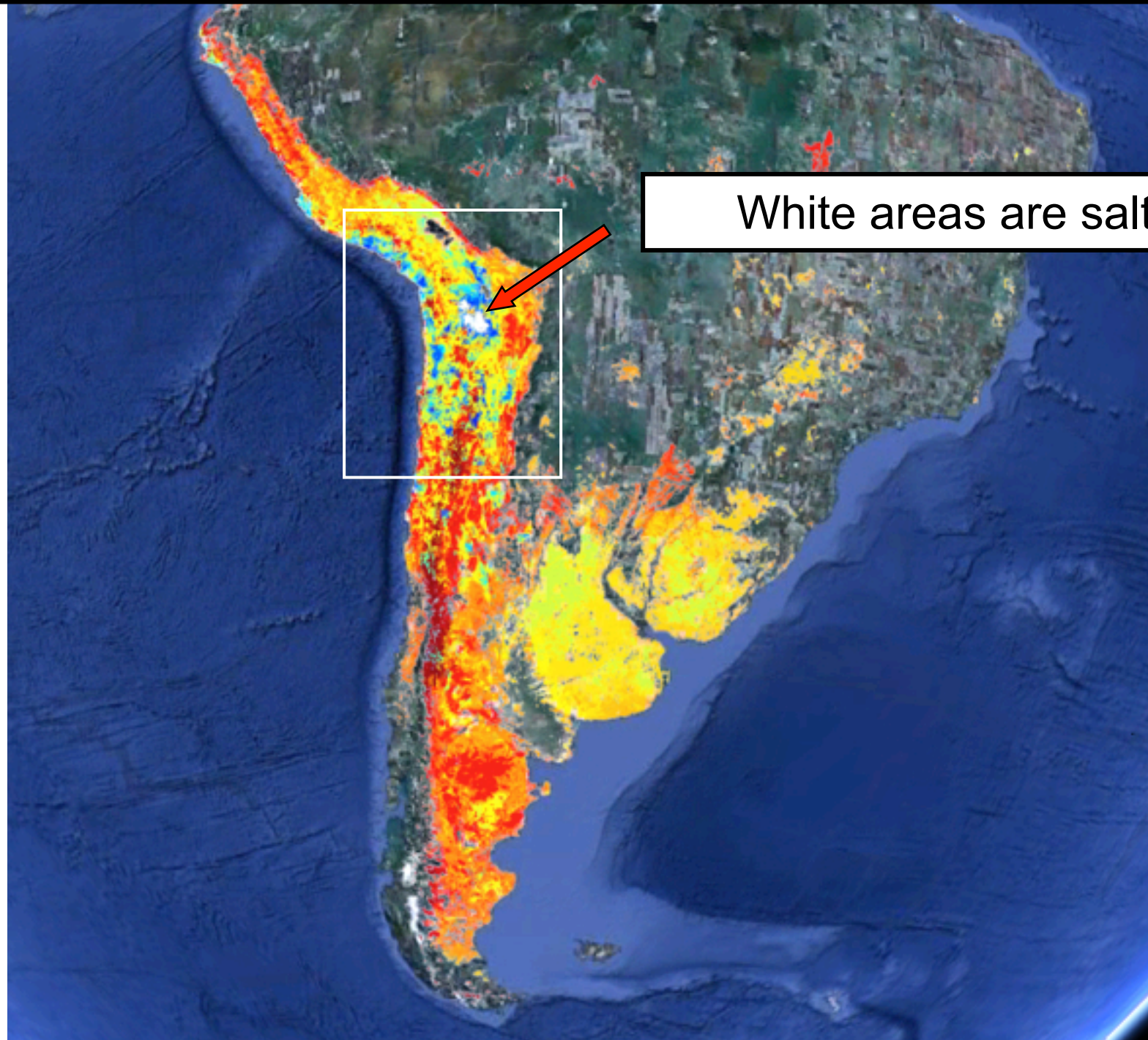
All 1000-Classes mapped for South America



All 1000-Classes mapped for South America



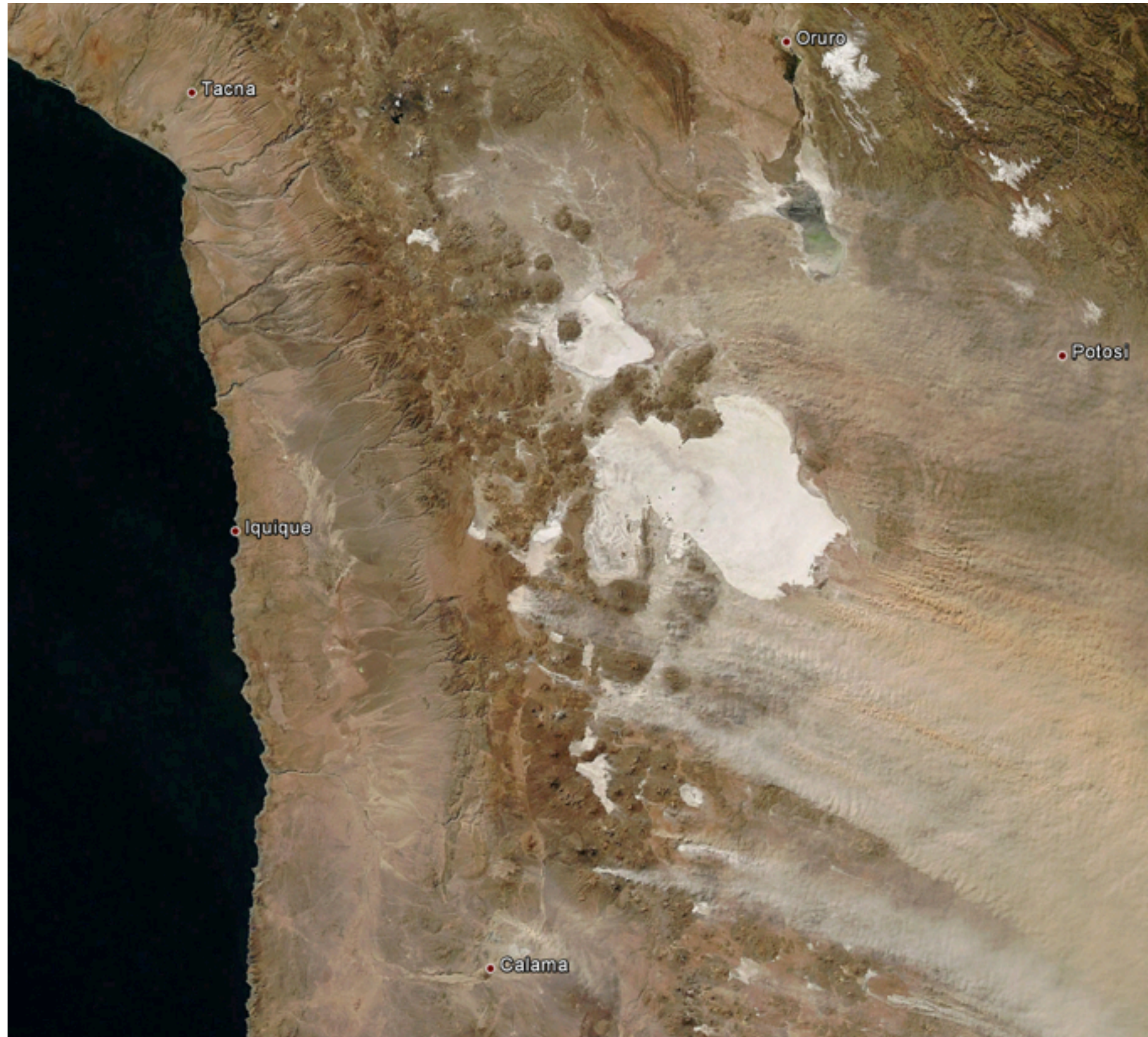
Blue colored SOM-Classes are concentrated in Atacama and Salar de Uyuni deserts



White areas are salt flats

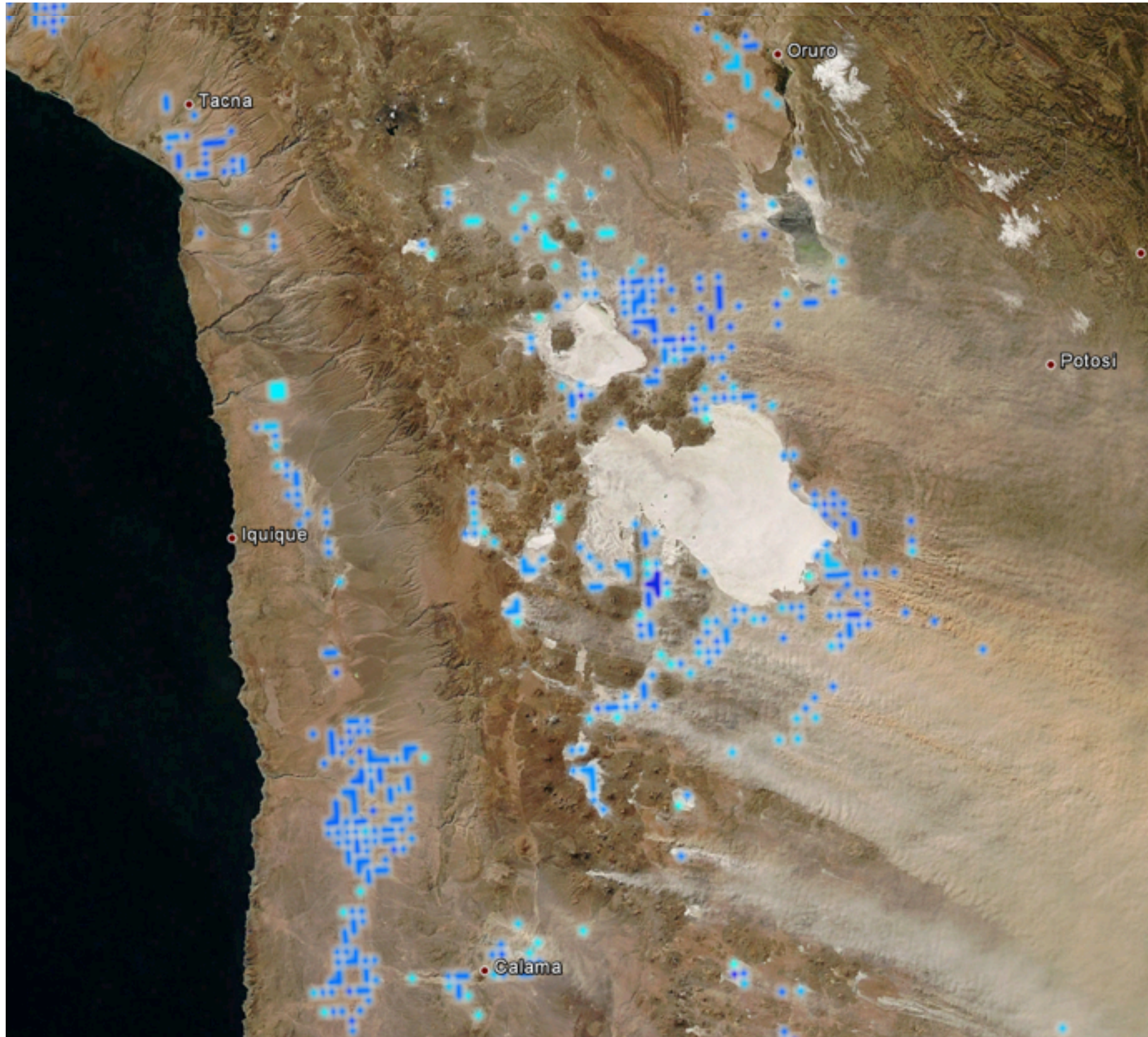
South America: Bolivia and Chile

July 18, 2010 MODIS Terra True Color



South America: Bolivia and Chile

Selected SOM-Classes in 200s, 300s, and 400s



An Objectively Optimized Earth Observing System

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2. The decision support criteria
3. The policy decisions

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The purpose of this project has been to develop a software infrastructure to optimally direct observations that allows us to **automatically focus on the key issues**:

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The project was inspired by two ancient sayings:

1. “Wisdom is profitable to direct!”
This inspired the automation of observation direction
2. “The knowledge of ignorance is the beginning of knowledge”
This inspired using quantitative measures of uncertainty (ignorance) to select our targets.

What issues can we address with this system?

- With flexible pointing instruments:
 - What is the optimum real time pointing?
- With flexible mode instruments:
 - What is the optimum real time use of zoom in mode?
- When should balloons be launched?
- What are the optimum trajectories for UAVs and aircraft?

Autonomous Observing System

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- Put simply:
 - we use quantitative measures of **uncertainty** to determine our future **observations** and their **location**,

Autonomous Observing System

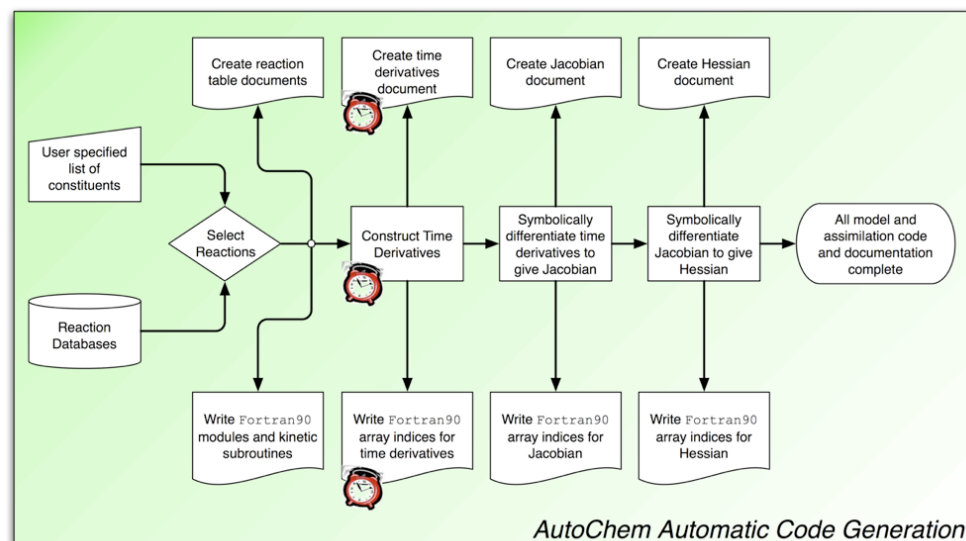
- Put simply:
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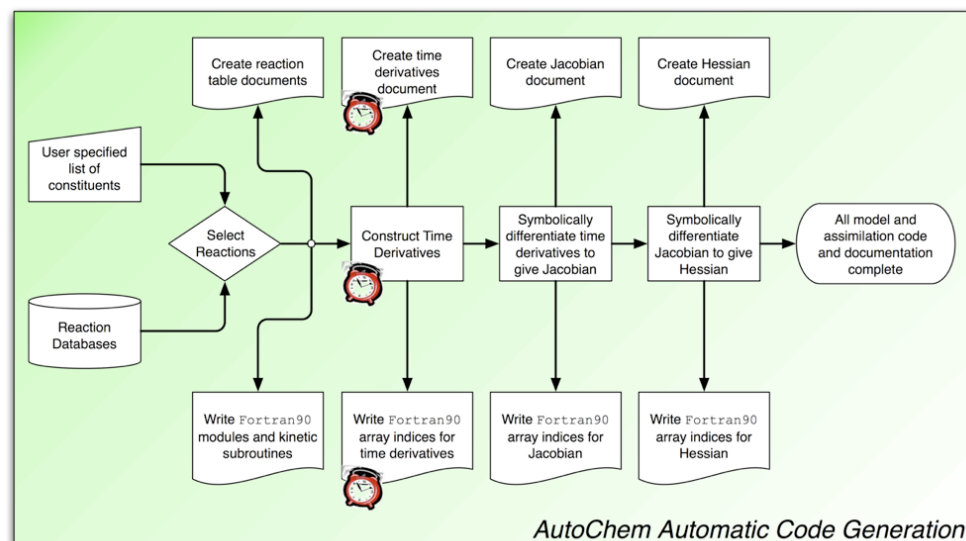
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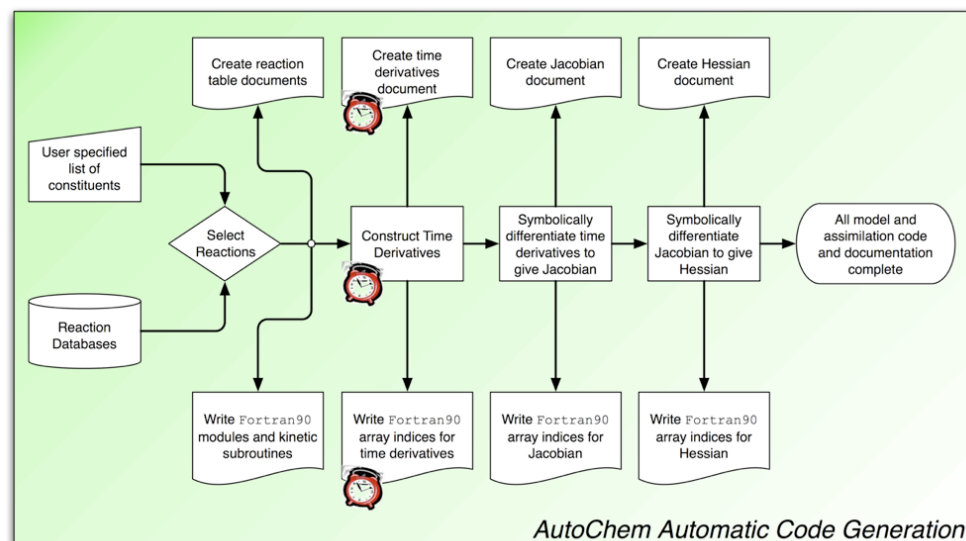
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- What we do not know is quantified by the **state vector uncertainty** supplied by the assimilation system.
- How important it is to make the observations is quantified by **information content** also supplied by the assimilation system.
- The **geographic extent** of the uncertainty maxima is one metric that can be used to determine whether zoom in or survey mode is required.



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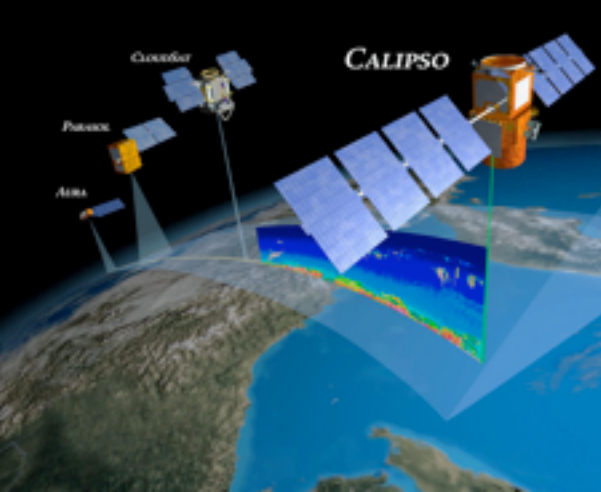
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 - Data Assimilation is a mathematical/statistical approach where we **combine multiple sources of information** on the system we are studying to provide our **best estimate of the state of that system** (the state vector) together with an associated **uncertainty** (the state vector uncertainty).
 - Each source of information is weighted by **how much we trust it**, quantified by its uncertainty.
 - The sources of information we use here are:
 1. Observations
 2. Theory (encapsulated in a theoretical deterministic model).

Autonomous Observing Systems

Autonomous Observing Systems

- The requirements will be varied depending on the application.
- The observing system will contain many components, orbital and suborbital.





How do we achieve this?



How do we achieve this?

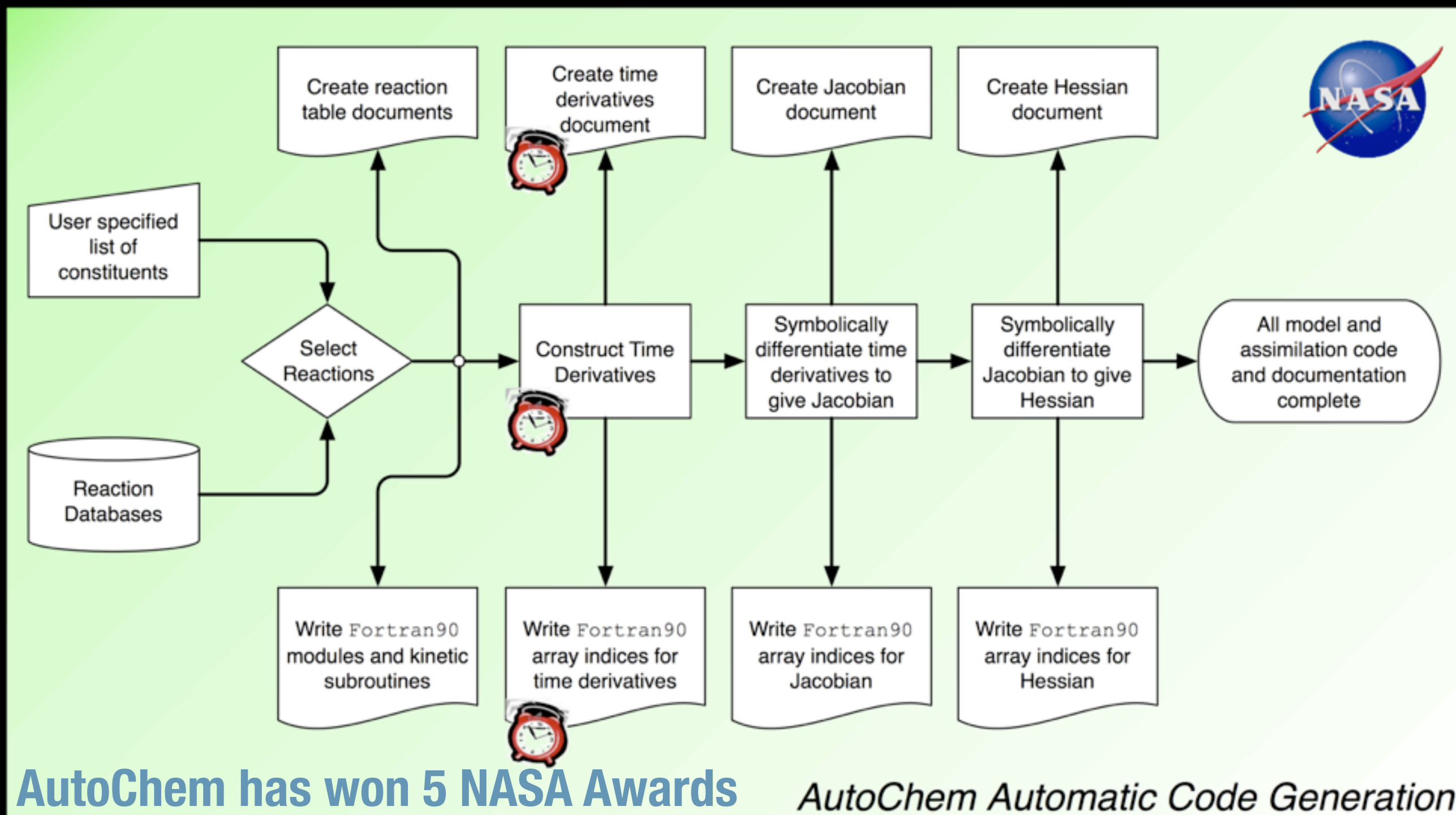
The knowledge of ignorance is
the beginning of knowledge

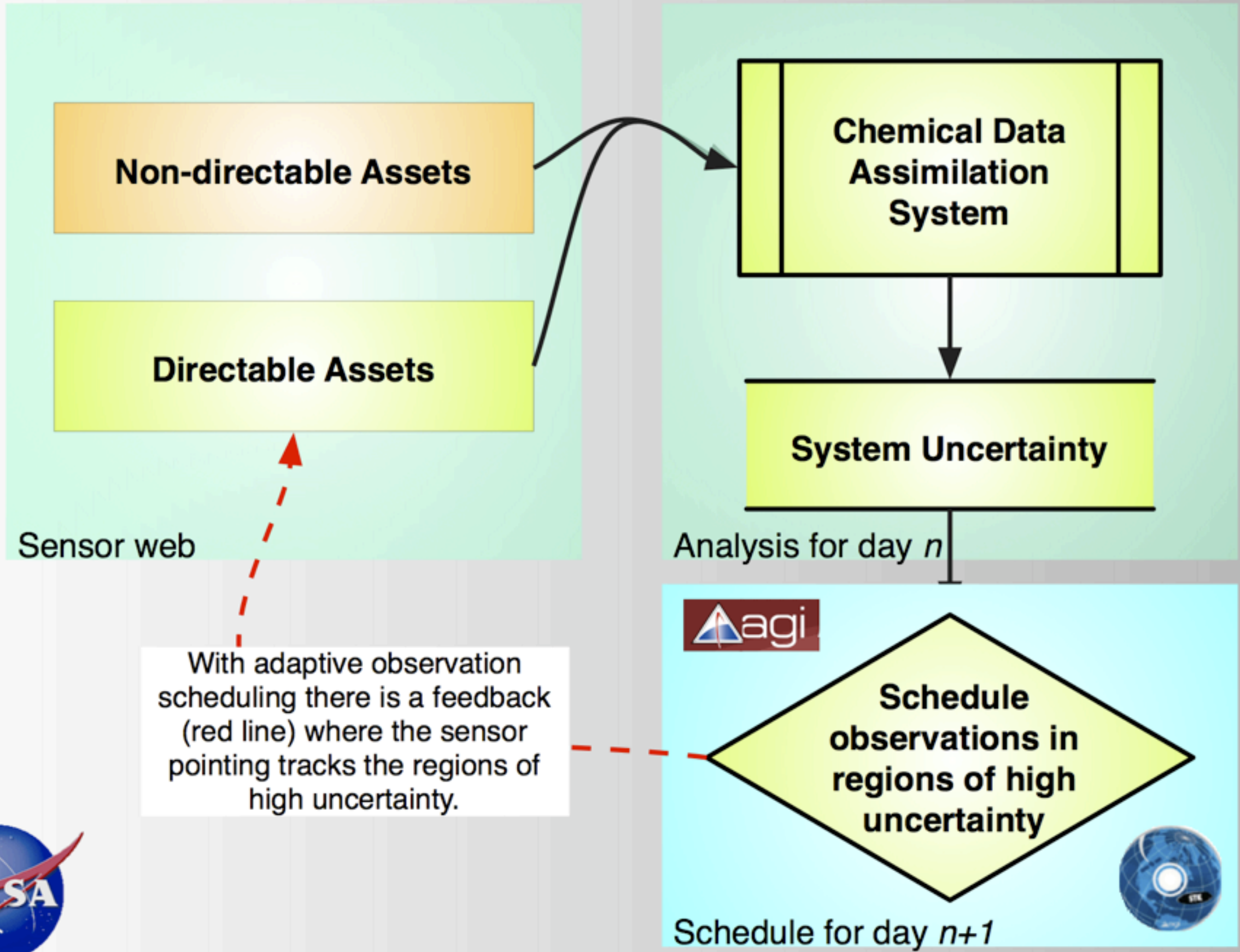
Ancient Greek Saying

Automatic Code Generator for Chemical Kinetics



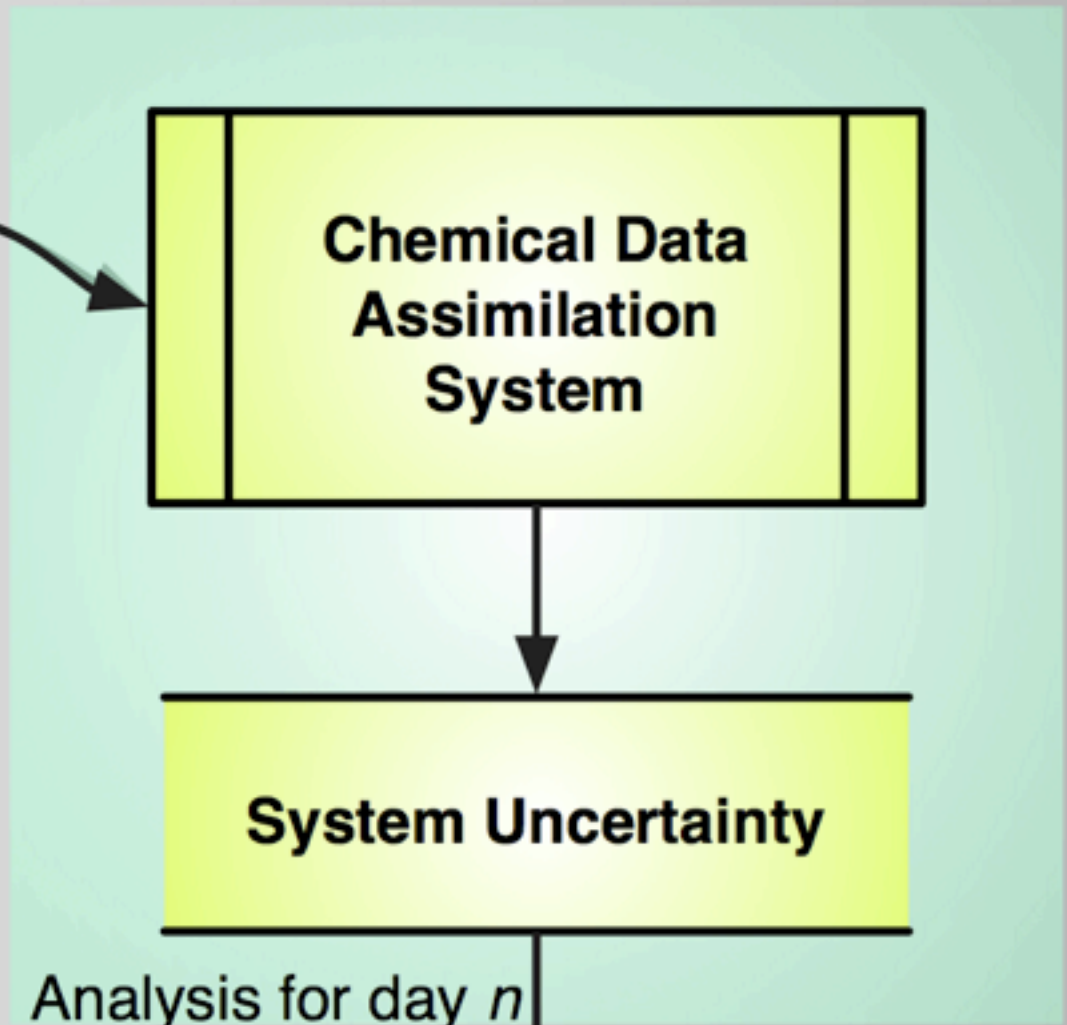
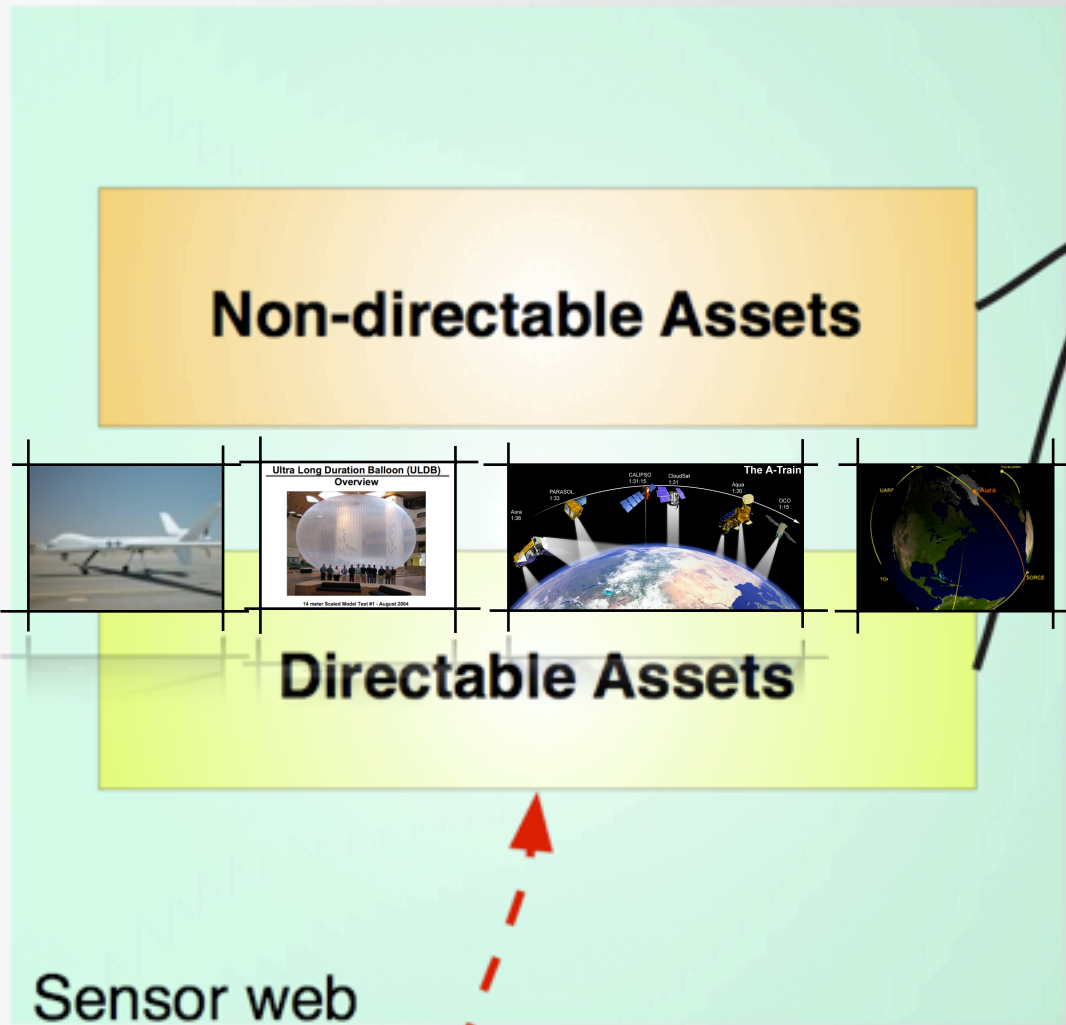
Automatic Code Generator for Chemical Kinetics



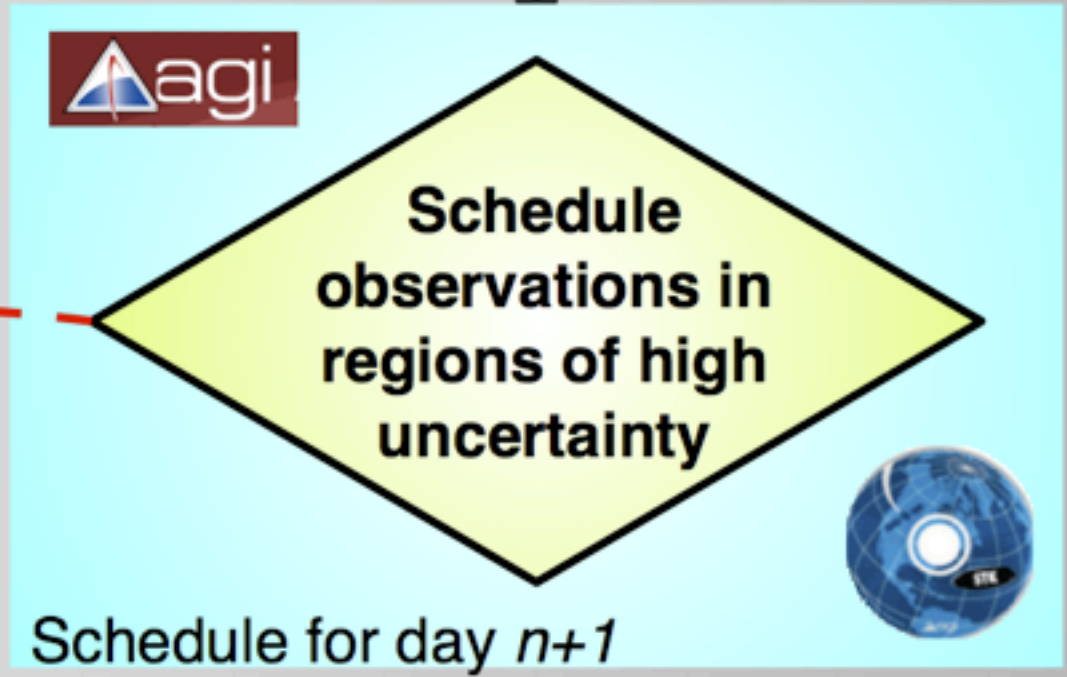


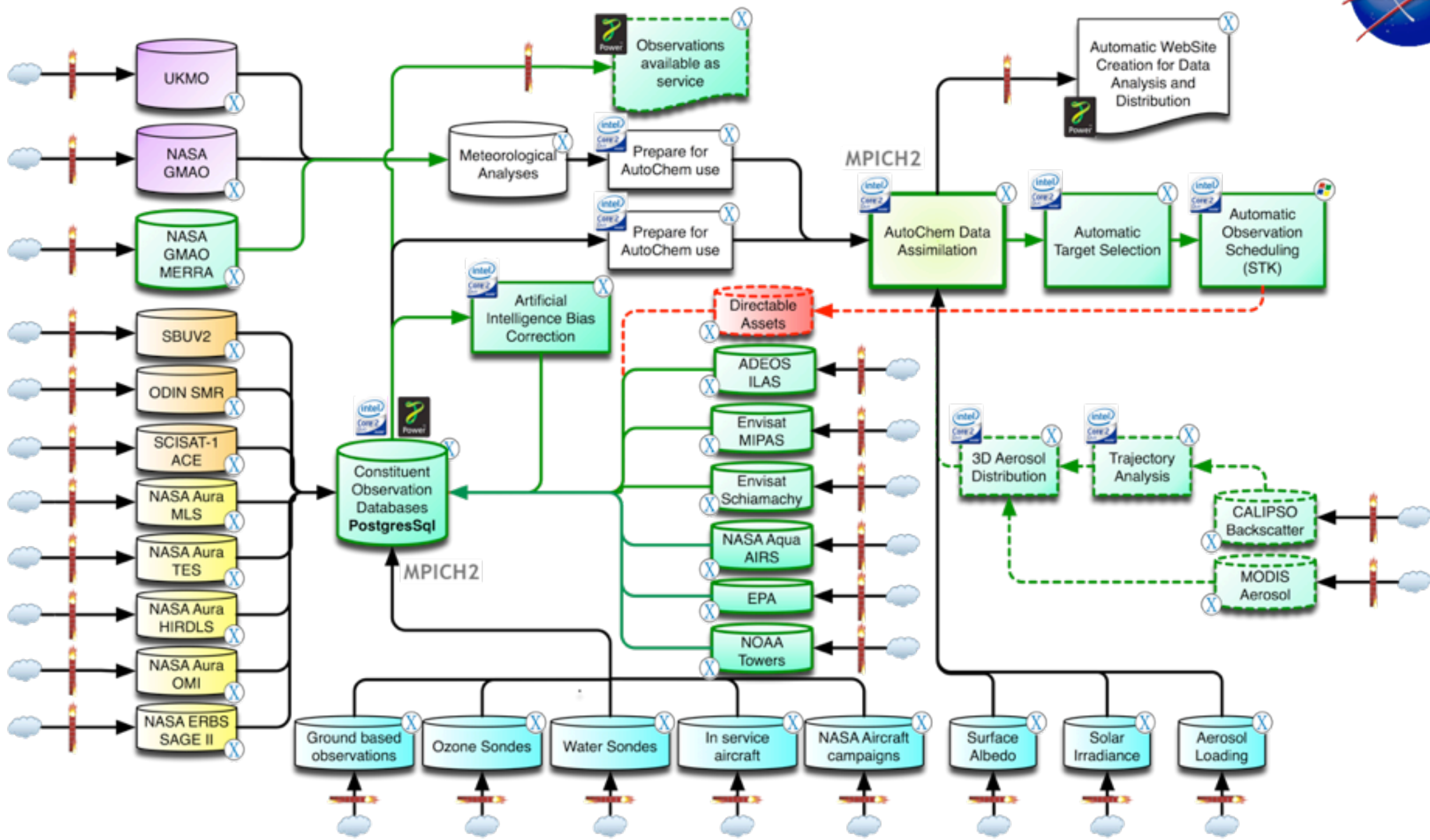
With adaptive observation scheduling there is a feedback (red line) where the sensor pointing tracks the regions of high uncertainty.





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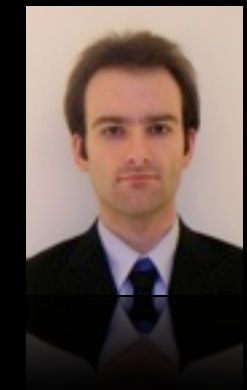
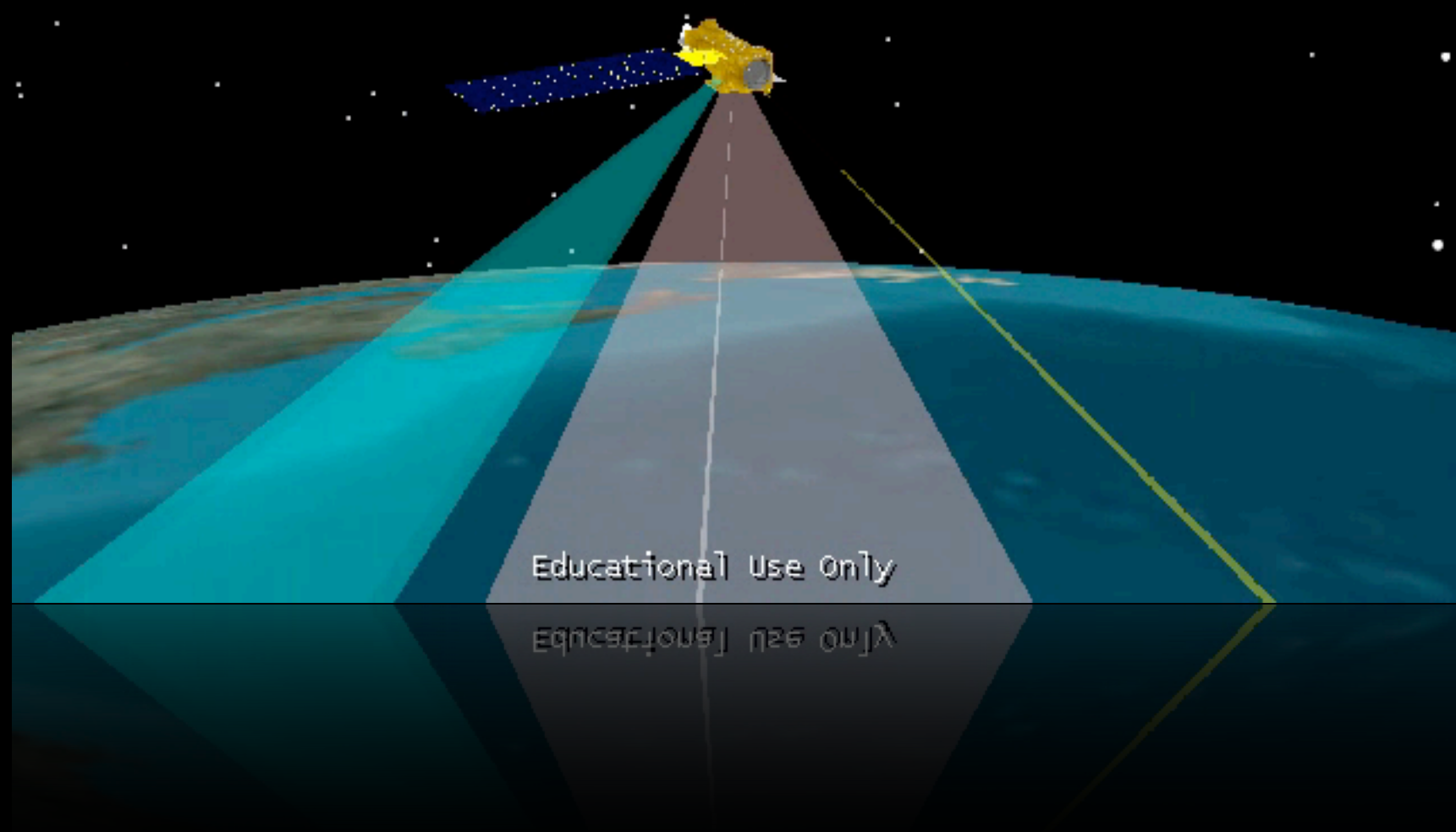


The lines represent data flow. Green lines represent new or recently updated elements. Dashed lines represent elements in preparation. Portions yet to be completed are in red. The cloud symbol ☁ represents that the data comes from an external data repository. The wall with a flame 🔥 represents the firewall. The operating system used for a given element is indicated by the operating system logo, (X) for OSX, and (Windows logo) for Windows. The hardware platform is indicated by the processor logo, (PowerPC logo) for PowerPC and (Intel logo) for Intel. The elements that are implemented as parallel components using MPICH2 have the MPICH2 logo.



Sensor Web Simulation in STK

```
AURA Classical Orbit Elements Educational Use Only
Time (UTCG): 1 Feb 2007 17:50:20.000
Semi-major Axis (km): 7082.352943
Eccentricity: 0.001438
Inclination (deg): 98.203
RAAN (deg): 337.559
Arg of Perigee (deg): 101.825
True Anomaly (deg): 288.301
Mean Anomaly (deg): 288.458
```





Final000DS - STK 8 - 3D Graphics 1 - Earth

File Edit View Insert Tools Satellite Window Feedback Help

16 Feb 2009 00:00:00.000

Object Browser

- Final000DS
 - CH4_1_10-4687
 - CH4_2_10-4687
 - CH4_3_10-4687
 - CH4_4_10-4687
 - CH4_5_10-4687
 - CH4_6_10-4687
 - CH4_7_10-4687
 - CH4_8_10-4687
 - CH4_9_10-4687
 - AURA
 - TES
 - ENVISAT
 - SCIMACHY

3D Graphics 1 - Earth

Evaluation Copy

Earth Inertial Axes

16 Feb 2009 00:00:00.000 Time Step: 180.00 sec

2D Graphics 1 - Earth

CH4_9_10-4687

AURA

agis

AURA - Earth 16 Feb 2009 00:00:00.000 Time Step: 180.00 sec

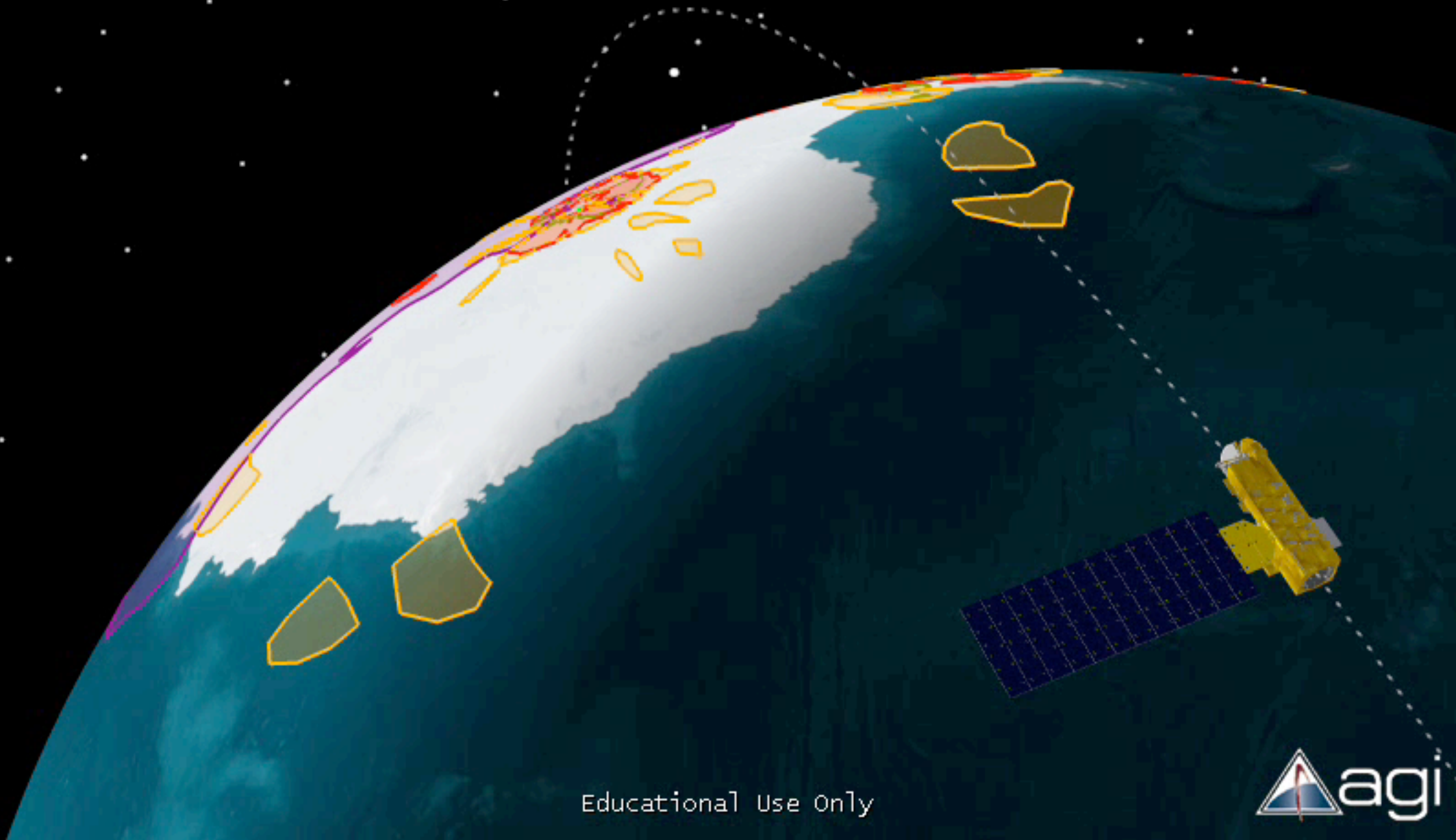
start Final000DS - STK 8 - ... STK Scheduler - [Sch... 6:21 PM

To return to your computer, press Control-Alt-Delete

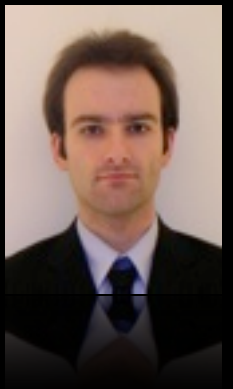
Final000DS - STK 8 - ... STK Scheduler - [Sch... 6:21 PM

AURA - Earth 16 Feb 2009 00:00:00.000 Time Step: 180.00 sec

Educational Use Only



Educational Use Only



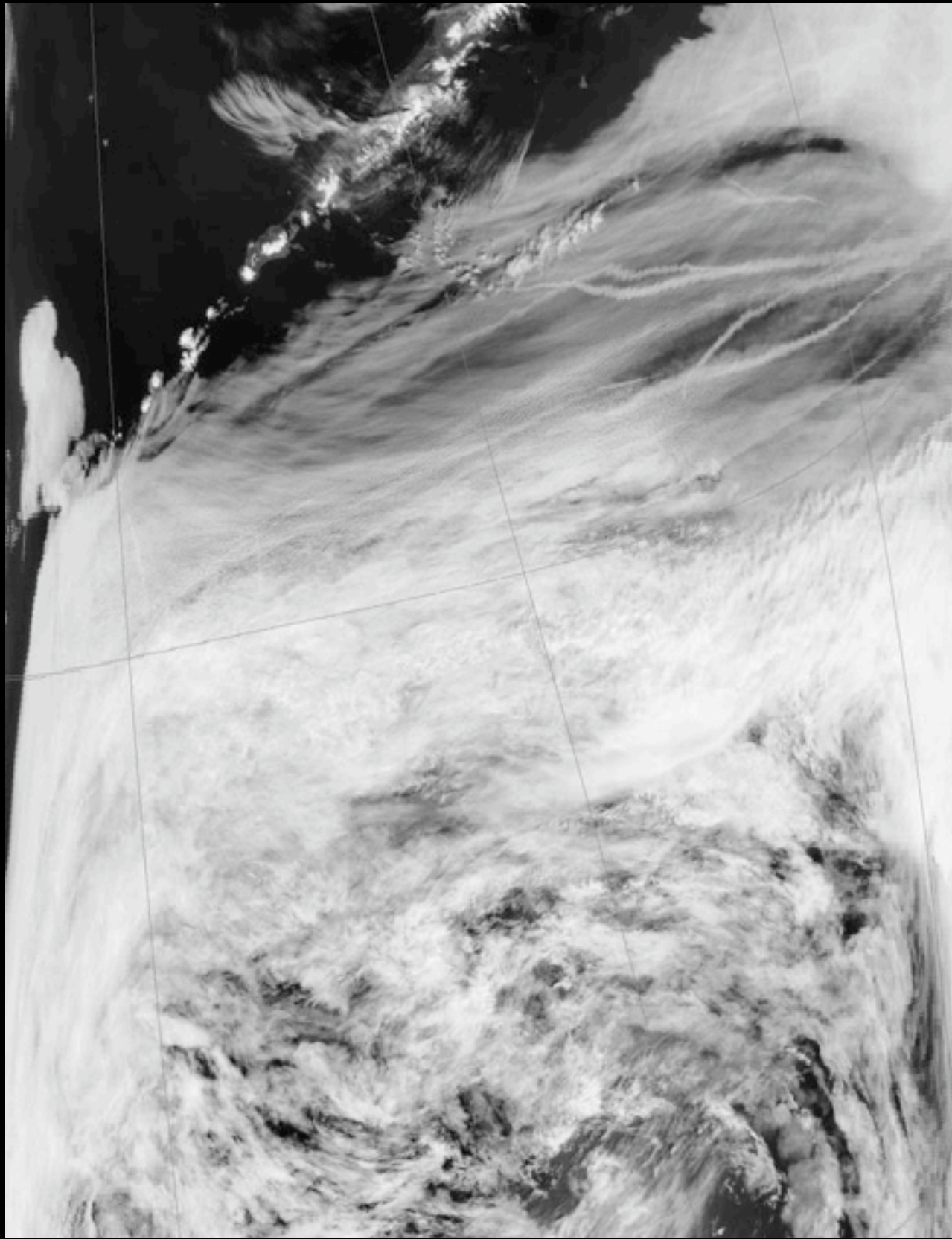
Educational Use Only



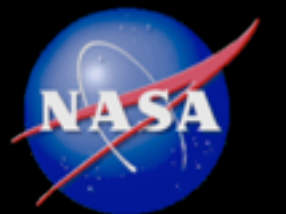
Autonomy

- Autonomous sensor web control is a challenging task. So we have used a modular and distributed approach.
- The autonomy selection criteria are likely to be different depending on the application, hence the advantage of modularity. For example:
 - For validation campaigns we may want to use regions of highest “certainty” as targets. For regular operation we may want to use regions of lowest “certainty” as targets.
 - We may want to use feature recognition in other applications.

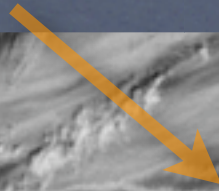




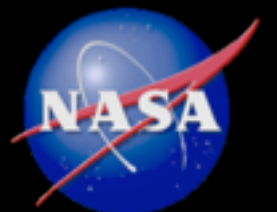
Feature recognition



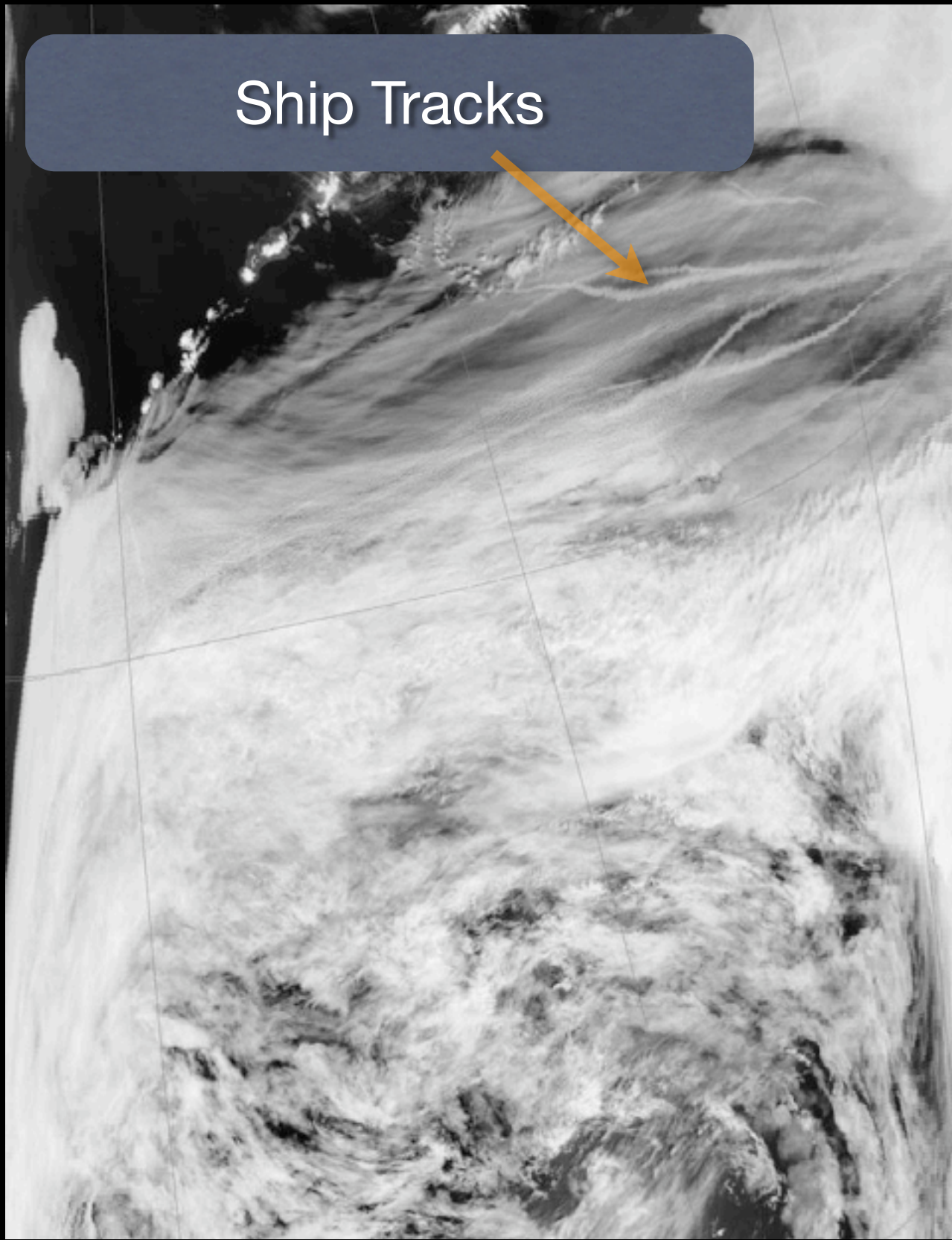
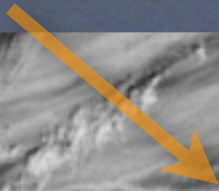
Ship Tracks



Feature recognition

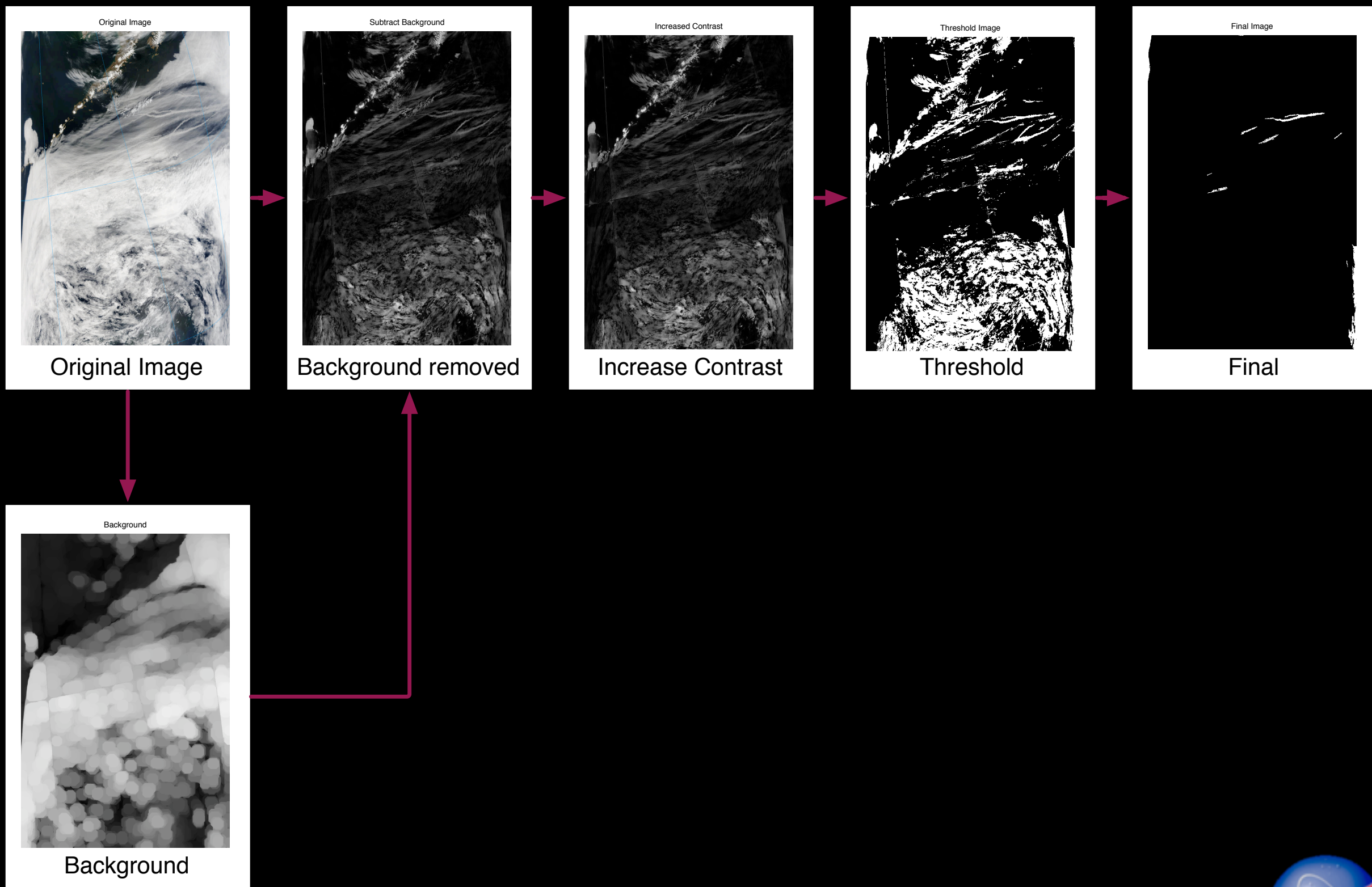


Ship Tracks



Feature recognition





Objectively Optimized Mission Planning



Science Goals

Quantitative
Optimization

Engineering
Requirements

A Web 2.0 design application can run on each of these workstations. It both explicitly facilitates communication between the discipline engineers and enables objective quantitative optimization of the mission design.

Large Trade Space

Driven by Science Objectives

- Possible Optimization for:
 - Science goals
 - Cost
 - Mass
 - Power
 - Coverage (polar?)
 - Detector Life
 - Retrieval Error
 - OSSE scores
- Trade variables:
 - Resolution (spatial, spectral)
 - Orbit (type, altitude, inclination)
 - Swath width
 - Repeat times
 - View
 - Spectral regions
- Each requirement is quantified with a cost function.
- **Multi-objective optimization.**

Team Building

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Team Building

Ideas!

- Augment human experience with objectively optimized design
- Build on the experience we have had with:
 - Objective design of neural networks using genetic algorithms
 - Software Infrastructure for Autonomous observing systems
- Incorporate artificial intelligence and a modeling/assimilation system

Why?

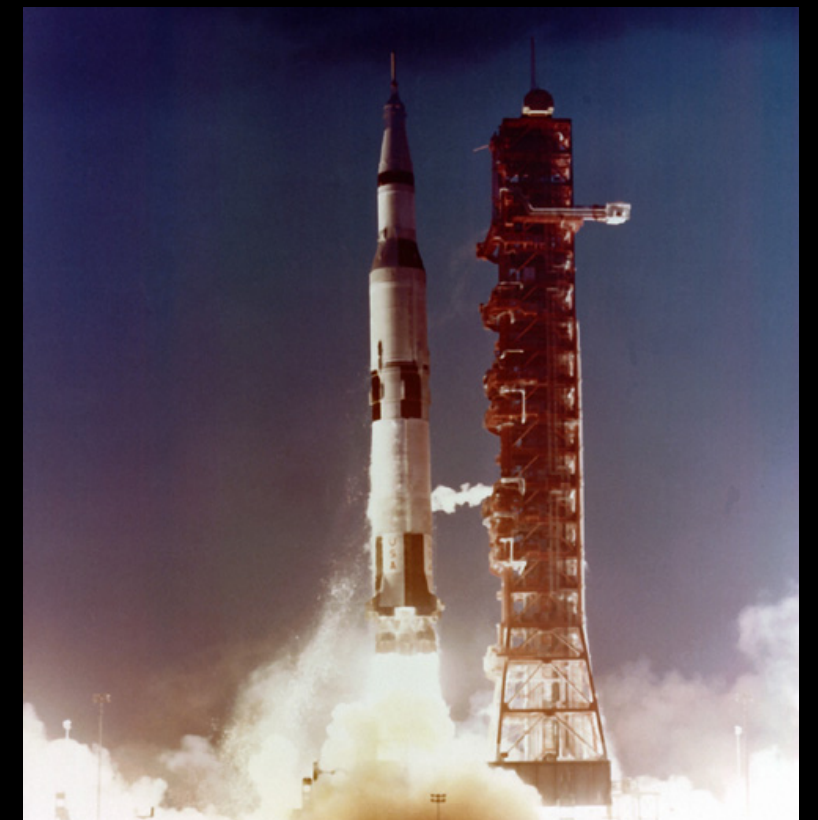
- Constrained budget
- Better meet requirements
- Possible route to out of the box solutions
 - Antenna example
- Make greater use of resources
- Make decisions less political

.... go one step further
and have an observing
system architect

Potential Payoff: This structured, analytical approach just might take us to a different region or point in the tradespace, with more science per dollar and lower cost missions

Motivation for a Great Architecture

- Architecture is design at the system level
- We have before us the design of an *unprecedented* system to observe the earth and monitor climate, fundamental to the future of humanity
- The system will have many stakeholders with differing and **changing** needs
- We must design and execute system **responsive** to these needs; that is flexible, and returns maximum benefit for the investment
- This is what well architected systems do!



Courtesy of Ed Crowley, MIT

Elements of an Architecture

An architecture is a description of the entities of a system and the relationship between those entities (Crowley et al.)

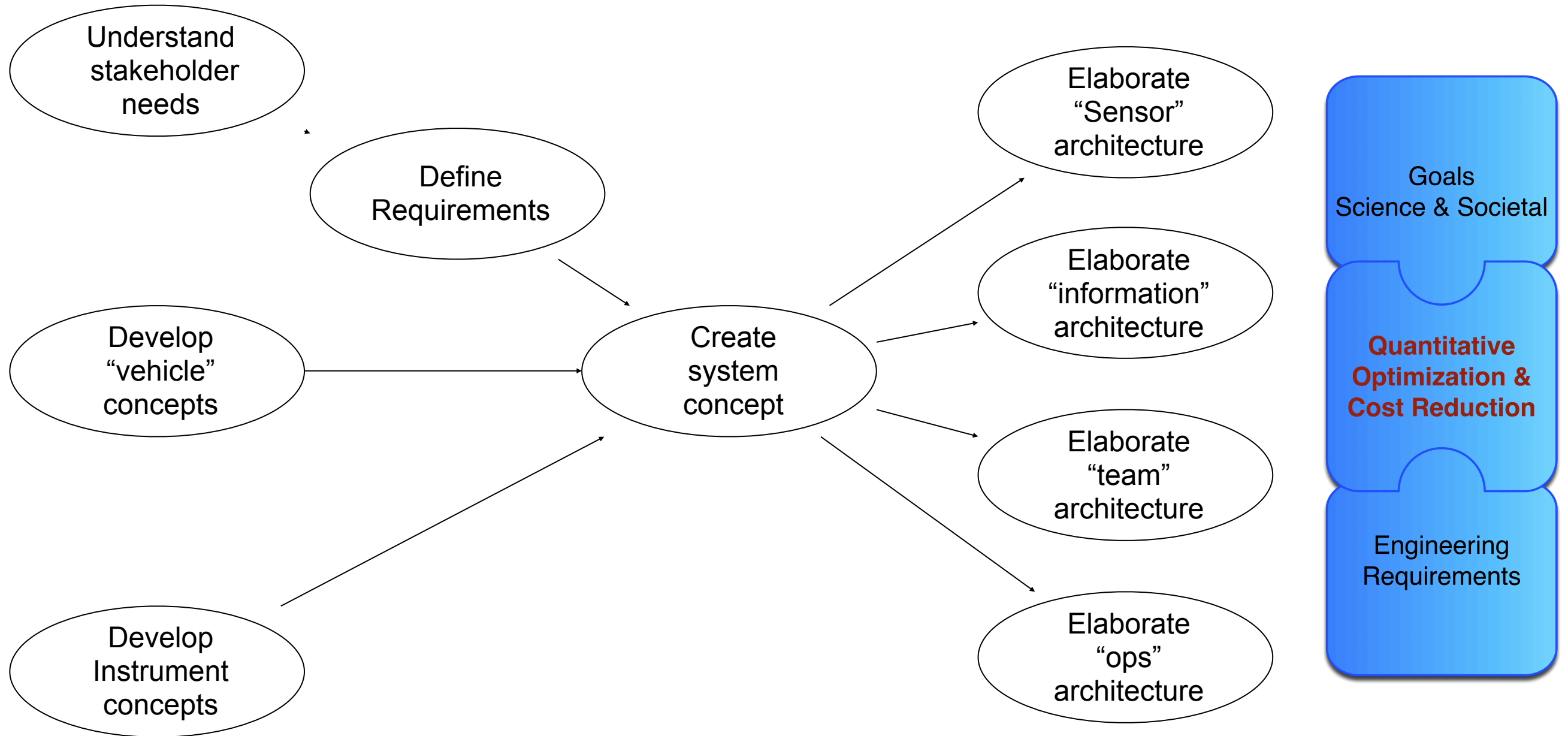
An architecture must be responsive to the needs of all stakeholders, as reflected in the system requirements

Partitions the system into elements, that can be built by individual projects, but which will integrate into a agency/ national/ international system (of systems) that will best inform us of the changing planet.

Describes the function of the system (that delivers benefit), the form of the system (what is built), and the operations of the system

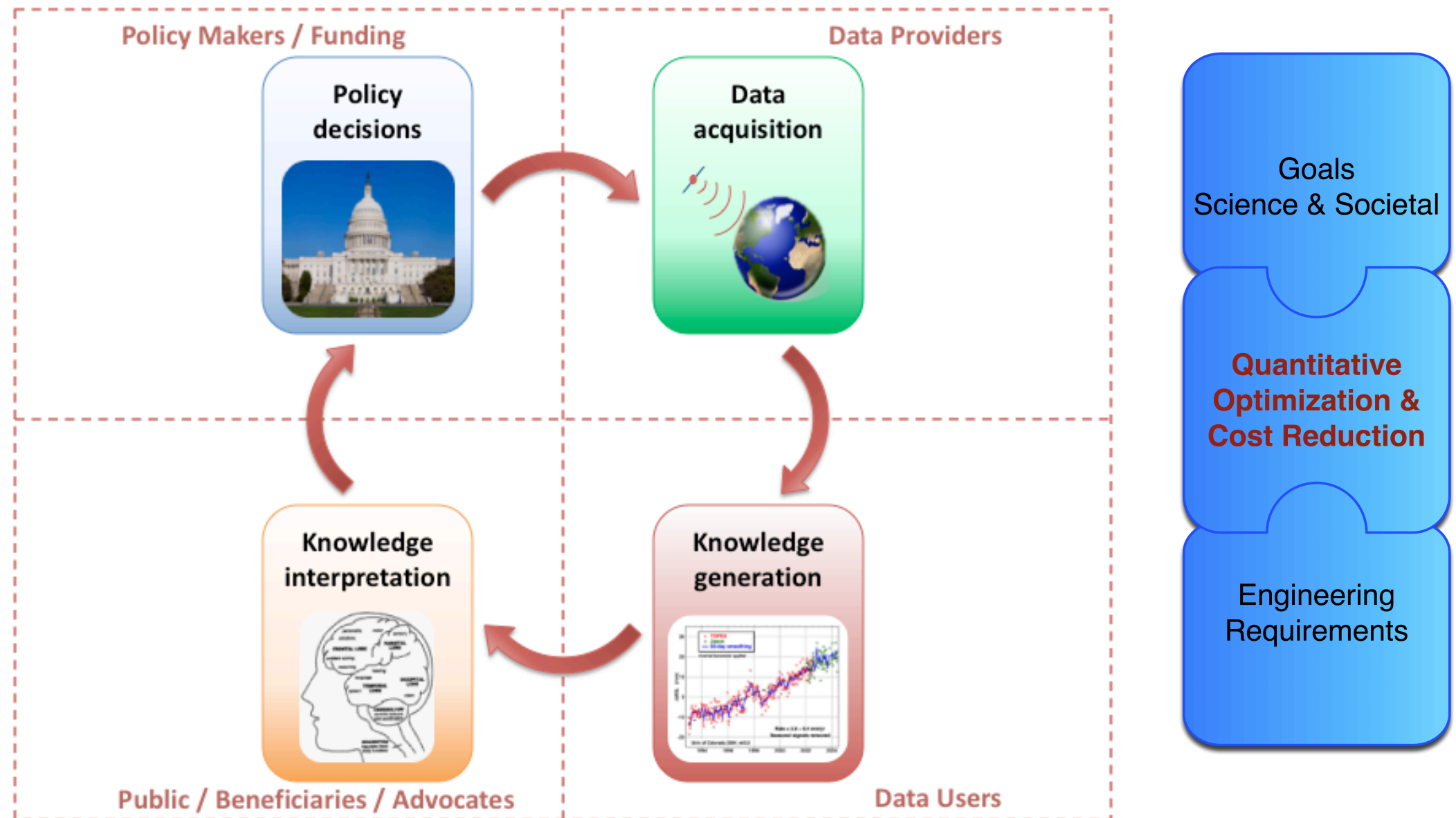
Courtesy of Ed Crowley, MIT

Workflow to Architecture



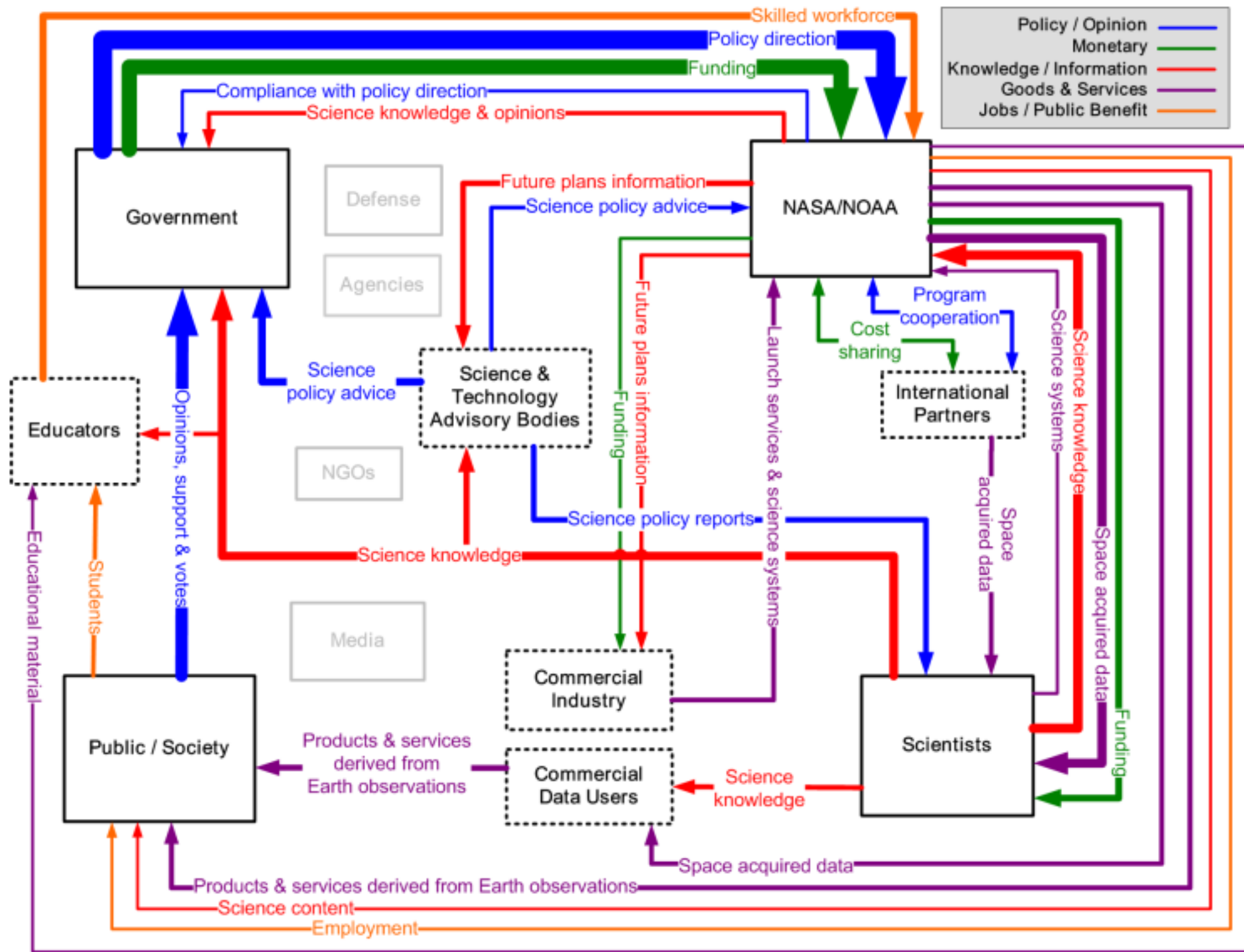
Courtesy of Ed Crowley, MIT

Tracing Stakeholder Value



How do we build a system that produces the greatest value not only to the climate scientists, but to all of the stakeholders, including commercial, other agencies, and the public?

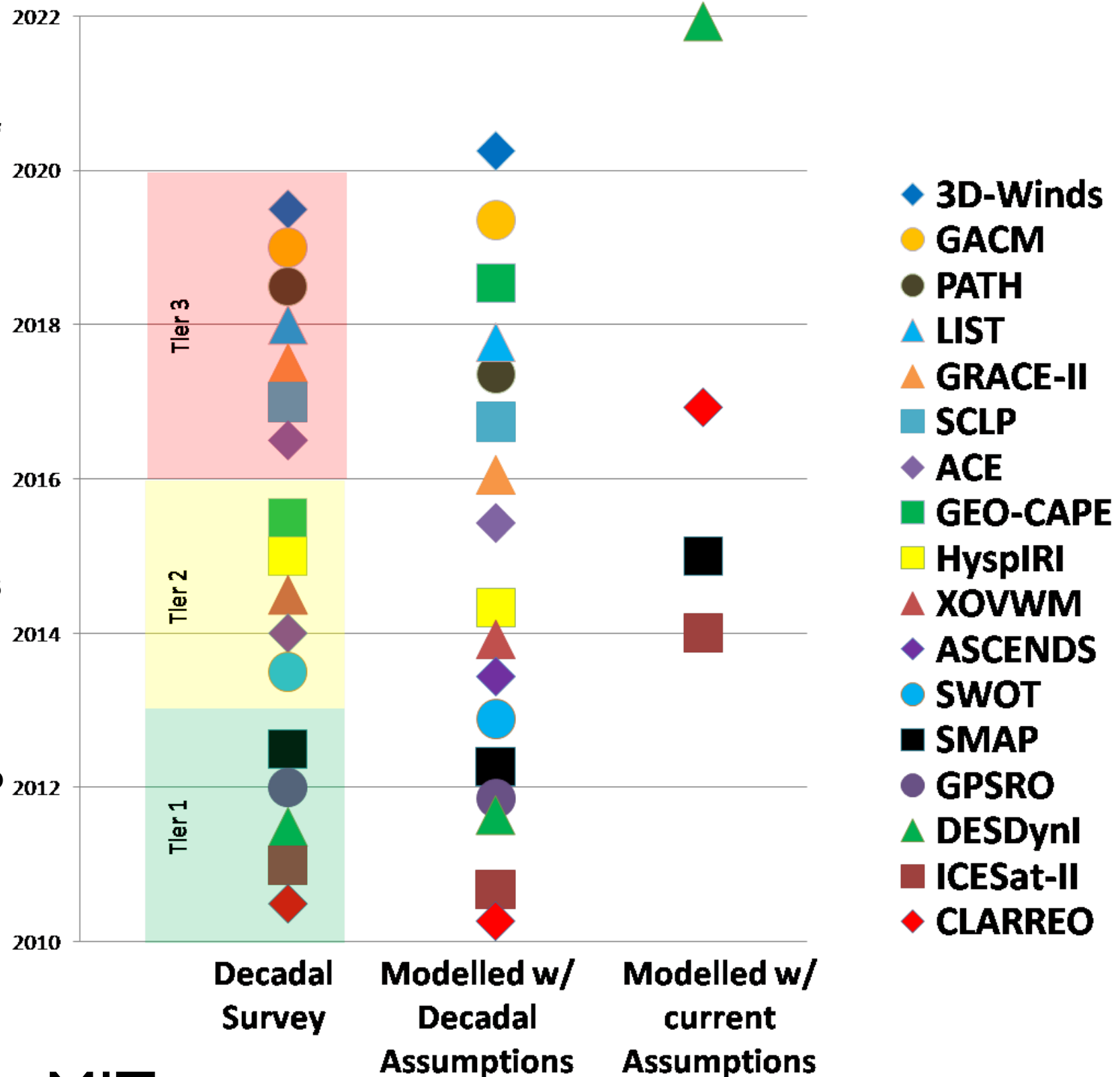
Courtesy of Ed Crowley, MIT



Courtesy of Ed Crowley, MIT

CAMPAIGN DESIGN

- Enumerate and evaluate all feasible architectures
 - Systems architecture principles applied to the scheduling and implementation of large, complex space satellite systems
 - Used “OPN” to enumerate constrained space
 - Utilized value functions and decision metrics to evaluate and rank set of feasible architectures
 - Down-select to a handful of favorable concepts to be carried forward for more detailed study and development
- Calibrated to Decadal Survey
 - Extensive interviewing process captured tacit decision rules used by DS panel members to arrive at recommended architecture
 - Reproduced recommended campaign order of 17 DS missions
- Used to explore reordering optimized to more realistic budget and costs
 - Implement new measurement objectives, and study affects on campaign architecture
 - Adapt campaign to various budget constraints



Courtesy of Ed Crowley, MIT